

Collective Reinforcement Learning Dynamics for Sustainability Economics

Workshop on Modern Applications of Control Theory and Reinforcement Learning | May 21, 2025

Wolfram Barfuss

Argelander Professor of Integrated Systems Modeling for Sustainability Transitions



Plot

CSS+MARL  SusEcon

Are we smart enough
for the good life?

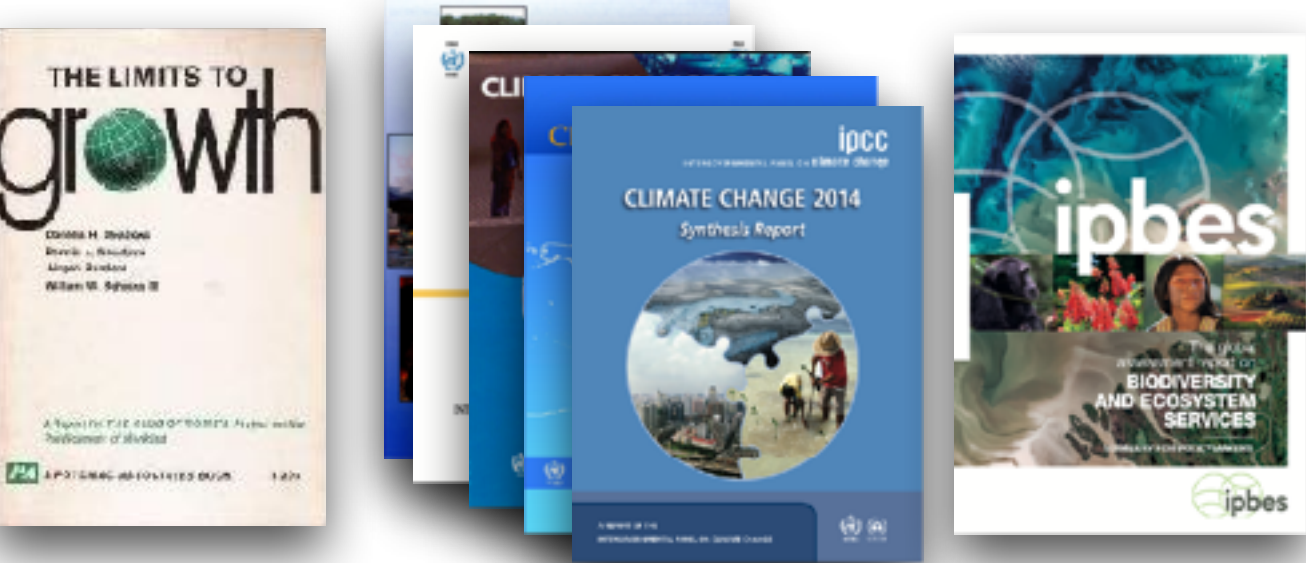
The good life for all within a healthy planet is the challenge of the 21st century



Urgent & large-scale collective action

How to enter a safe and just space?

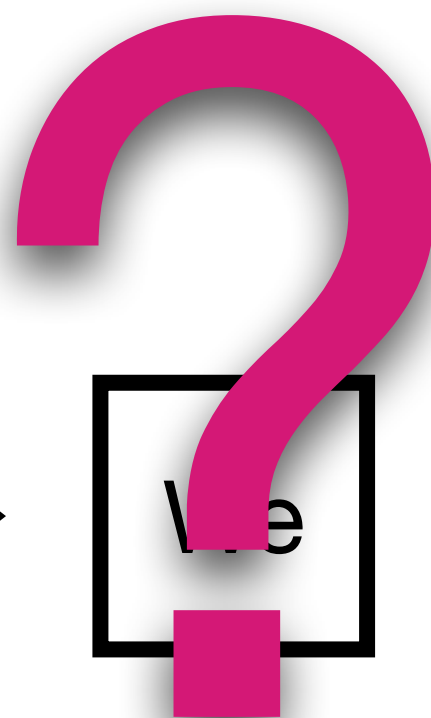
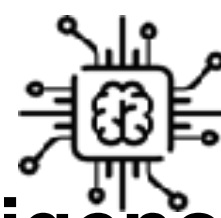
from 1970s onward



Report danger
(with more certainty)

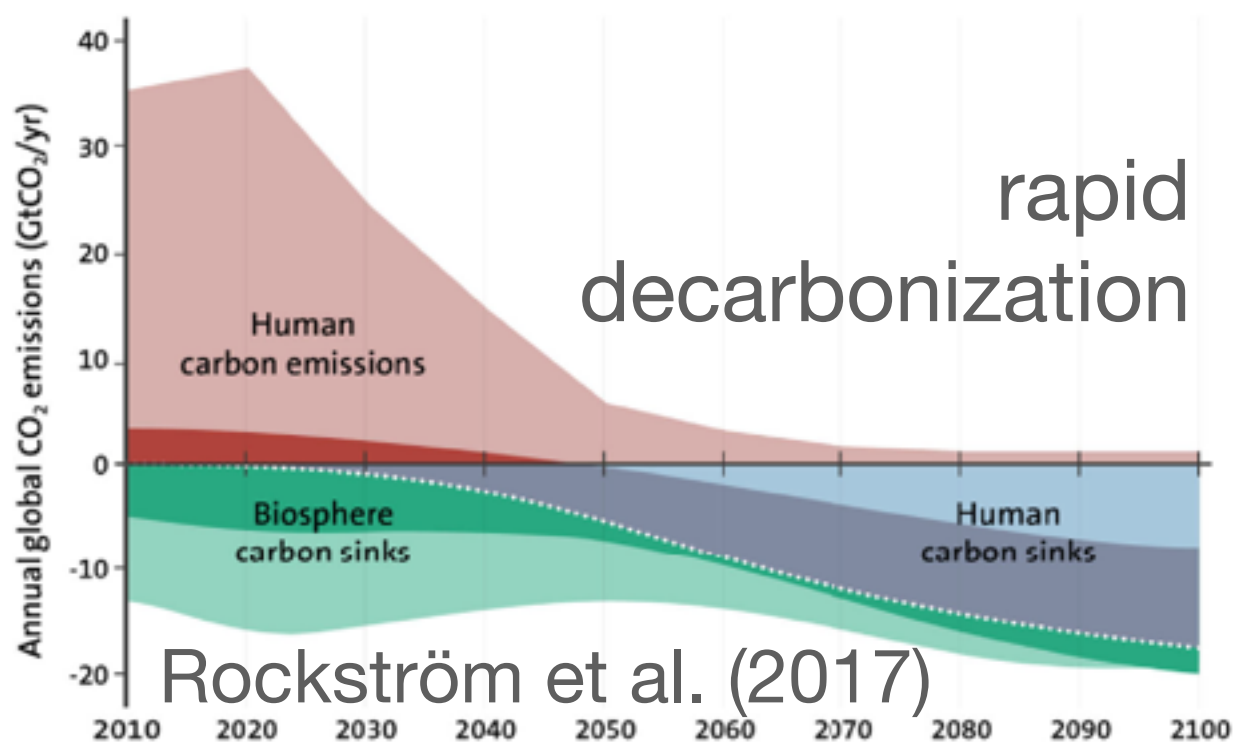
We *know*
there is a problem

Technology
Social Media
Artificial Intelligence



Info

Act



Propose
solutions

Technological
Institutional

We *know*
what to do

Outline

Why | Collective action challenges in human-machine ecologies

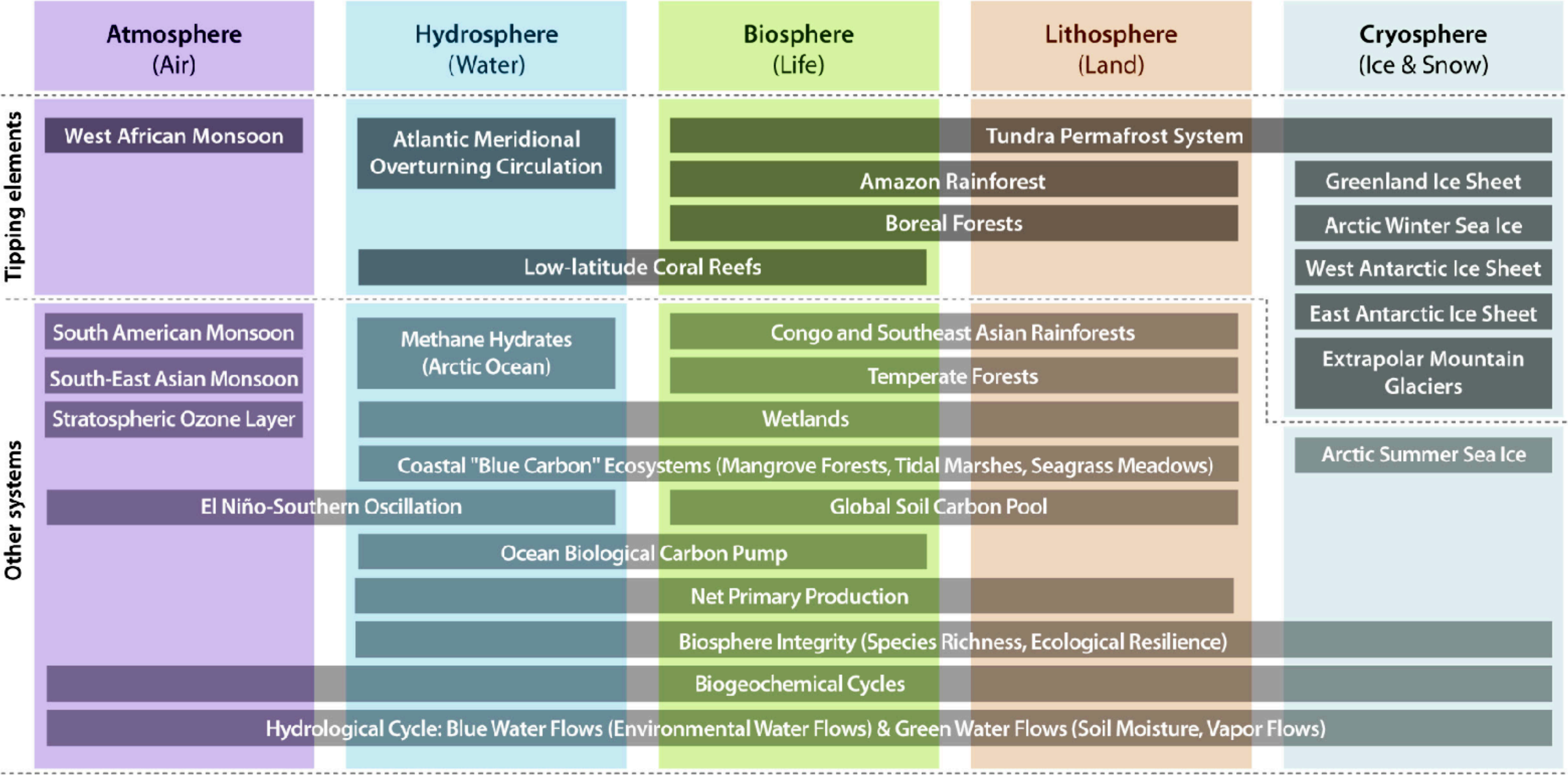
How | Building bridges

What | Emergent phenomena from cognition in contexts

WHY | Collective action challenges in human-machine ecologies

Planetary commons

Nature’s regulating and maintenance services requiring cooperation



The challenge of collective action | **Cooperation**

Individual
pays a cost c



Collective
All receive benefit b
with $b < c < Nb$

The tragedy of the commons Hardin (1968)

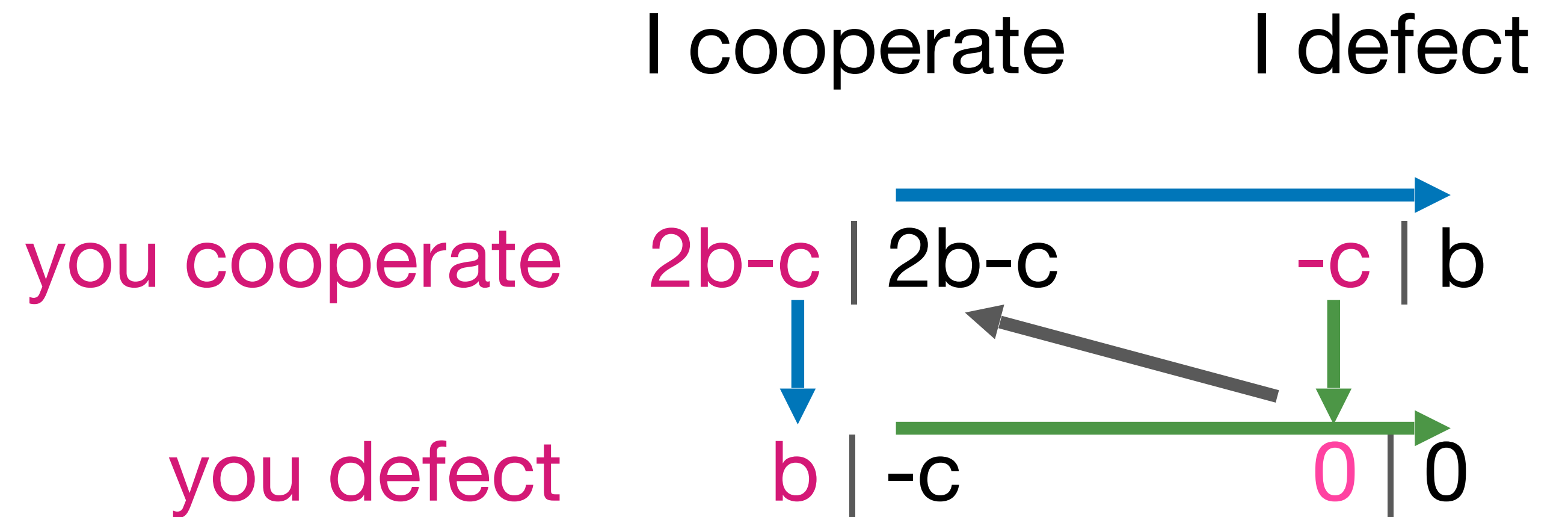
A conflict of interest between individual and collective

Greed to exploit others and
fear of being exploited by others

Individual interest → defection

Everyone is better off cooperating

Collective interest → cooperation



Solution | Outside central authorities or privatization

Problem | Not possible for planetary commons

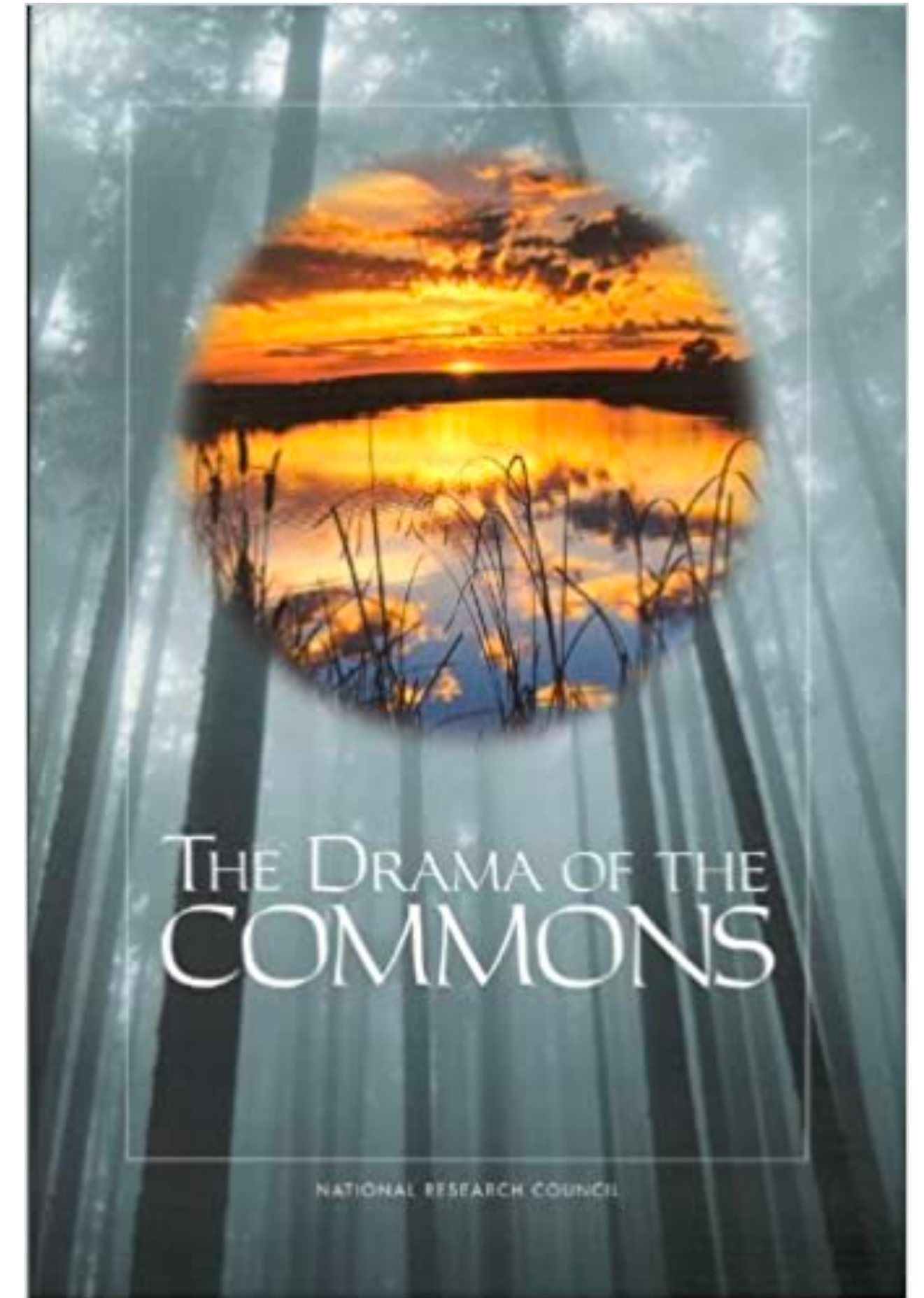
Governance of local commons

Tragedy is not inevitable - Things are **not as simple** as they seem in the prototypical model. **Human motivation** is complex [...], and the **resource systems themselves have dynamics** that influence their response to human use.

Centralized authorities tend to overuse the commons as well.

Solution | Bottom-up approaches, decentralized governance, social reciprocity

Problem | Difficult to scale to the global level



Ostrom et al. (2002). The drama of the commons

Intelligent technology should also cooperate

Setting the agenda in research

Comment



A huddle at the 2017 United Nations Climate Change Conference, where attendees cooperated on mutually beneficial joint actions on climate.

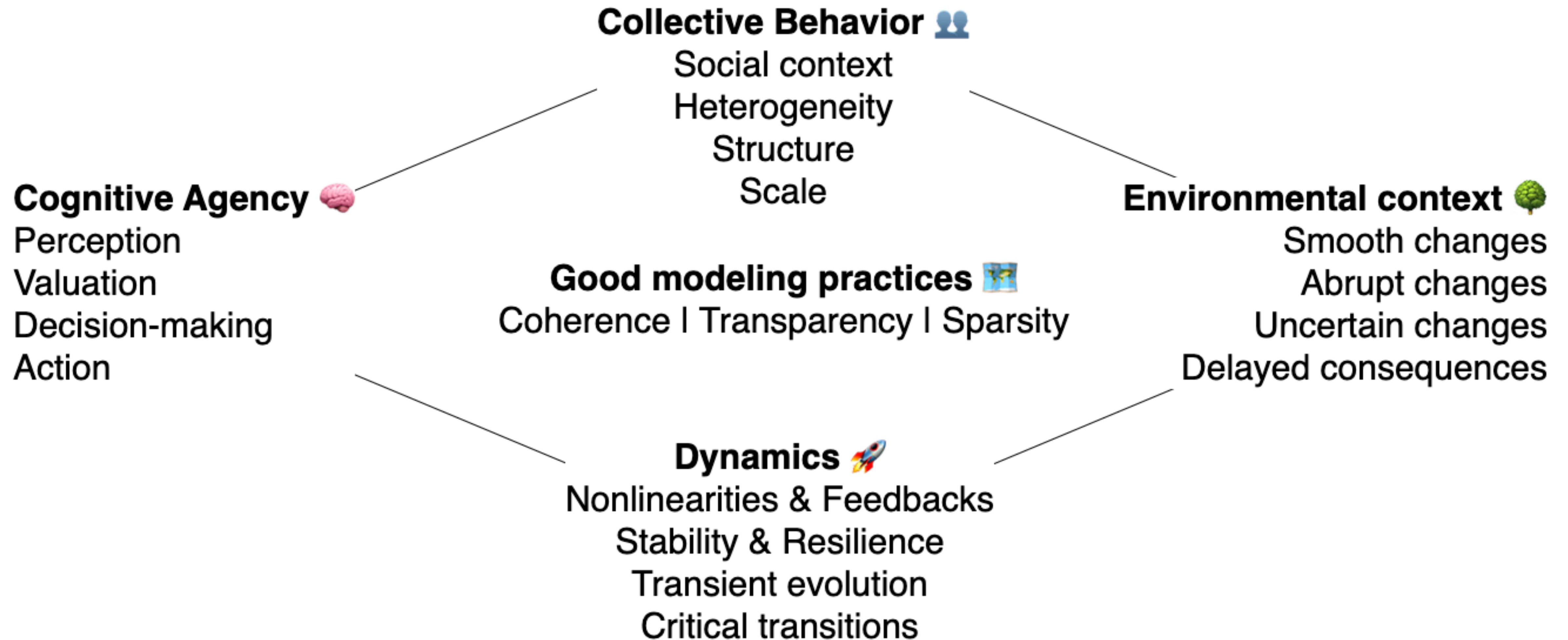
Cooperative AI: machines must learn to find common ground

Allan Dafoe, Yoram Bachrach, Gillian Hadfield, Eric Horvitz, Kate Larson & Thore Graepel

“To help humanity solve **fundamental problems of cooperation**, scientists need to reconceive **artificial intelligence as deeply social**”

Cooperation challenges in human-machine ecologies

Why are we not cooperating more toward a sustainable future for all?



HOW | Building bridges

How to model? | Three types of models

Dynamic-system
models

Transparent
Dynamics

Collective behavior

? **agency** ?

Environmental contexts

Equilibrium-based
models

Transparent

Static

Collective behavior

Hyper-rational agency

Environmental contexts

Model desiderata

Transparent
Dynamics

How to integrate?

Often opaque

Dynamic

Collective behavior

Arbitrary agency

Environmental contexts

Agent-based models

Building bridges between communities

Complex Systems Science

Insightful - produced rich understanding on how cooperation can emerge

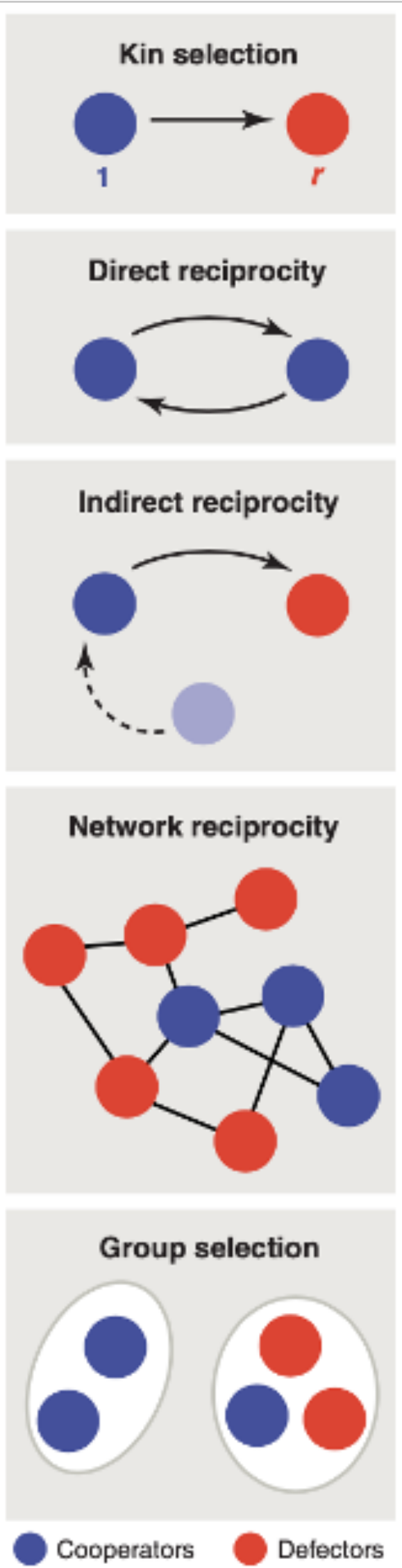
Simplistic - ignoring individual-level complexity and environmental context

Multiagent reinforcement learning

Rich - combining collectives of individually intelligent agents in changing environments

Obscure - highly stochastic, computationally expensive, and challenging to interpret

CSS Example | Five rules for the evolution of cooperation



Cooperation as an emergent phenomenon, given ...

| | | Payoff matrix | | Cooperation is... | | | |
|-----------------------------|----------|---------------------|-----------------|---------------------------------|---------------------------------|----------------------------------|--|
| | | <i>C</i> | <i>D</i> | ESS | RD | AD | |
| Kin selection | <i>C</i> | $(b - c)(1 + r)$ | $br - c$ | $\frac{b}{c} > \frac{1}{r}$ | $\frac{b}{c} > \frac{1}{r}$ | $\frac{b}{c} > \frac{1}{r}$ | <i>r</i> ...genetic relatedness |
| | <i>D</i> | $b - rc$ | 0 | | | | |
| Direct reciprocity | <i>C</i> | $(b - c) / (1 - w)$ | $-c$ | $\frac{b}{c} > \frac{1}{w}$ | $\frac{b}{c} > \frac{2 - w}{w}$ | $\frac{b}{c} > \frac{3 - 2w}{w}$ | <i>w</i> ...probability of next round |
| | <i>D</i> | b | 0 | | | | |
| Indirect reciprocity | <i>C</i> | $b - c$ | $-c(1 - q)$ | $\frac{b}{c} > \frac{1}{q}$ | $\frac{b}{c} > \frac{2 - q}{q}$ | $\frac{b}{c} > \frac{3 - 2q}{q}$ | <i>q</i> ...social acquaintanceship |
| | <i>D</i> | $b(1 - q)$ | 0 | | | | |
| Network reciprocity | <i>C</i> | $b - c$ | $H - c$ | $\frac{b}{c} > k$ | $\frac{b}{c} > k$ | $\frac{b}{c} > k$ | <i>k</i> ...number of neighbors |
| | <i>D</i> | $b - H$ | 0 | | | | |
| Group selection | <i>C</i> | $(b - c)(m + n)$ | $(b - c)m - cn$ | $\frac{b}{c} > 1 + \frac{n}{m}$ | $\frac{b}{c} > 1 + \frac{n}{m}$ | $\frac{b}{c} > 1 + \frac{n}{m}$ | <i>n</i> ...group size <i>m</i> ...number of groups |
| | <i>D</i> | bn | 0 | | | | |

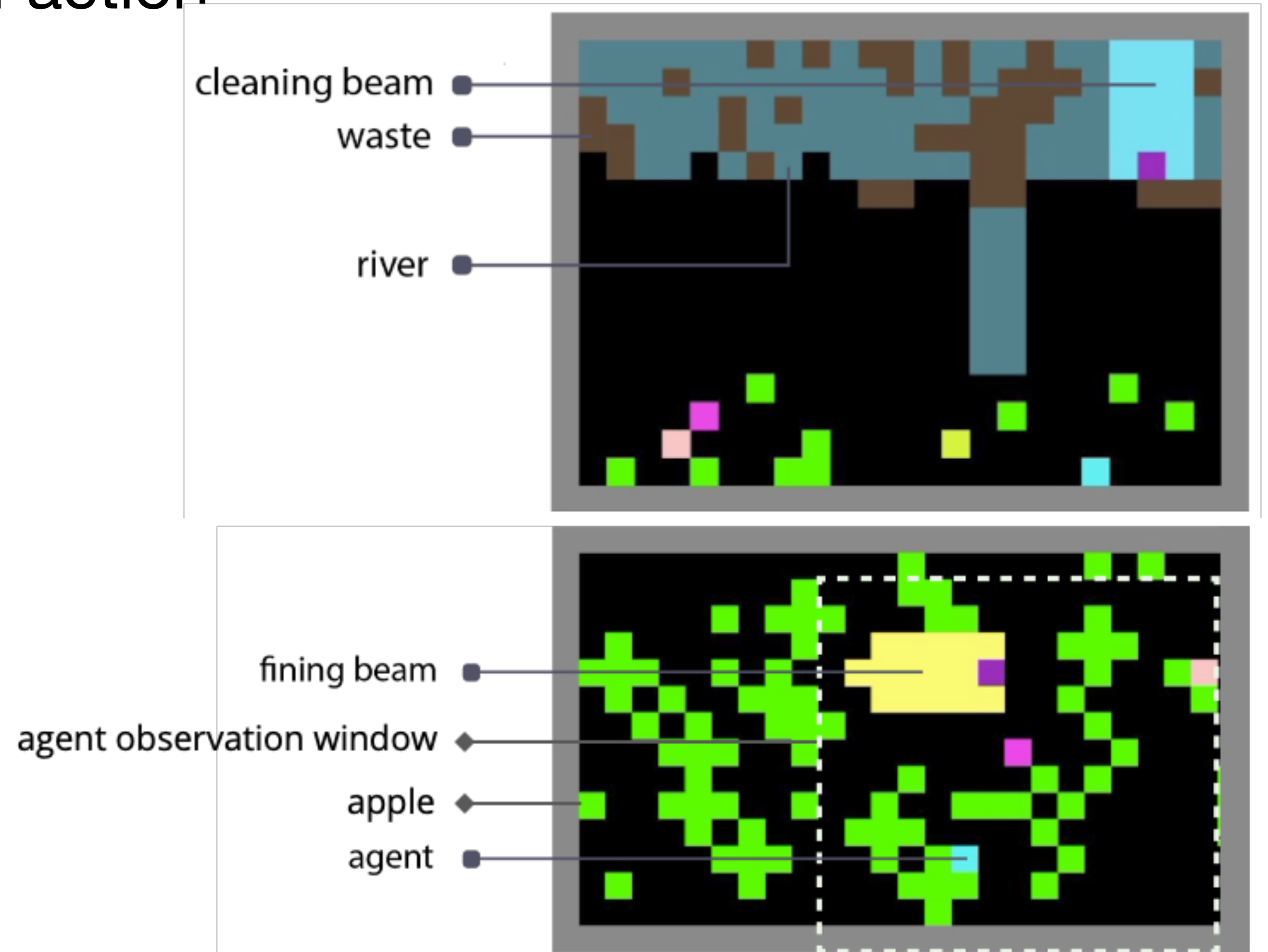
MARL Example | Cooperation in sequential social dilemmas

Cooperation not readily available as a single action
- must be learned as a sequence of action

Solution approaches

- Other-regarding preferences
- Other-influence
- Reputation and norms
- Contracts

Frontiers: LLM-based agents



How to build bridges?

Realize: focus on modeling for understanding - not scaling for engineering

All models are wrong

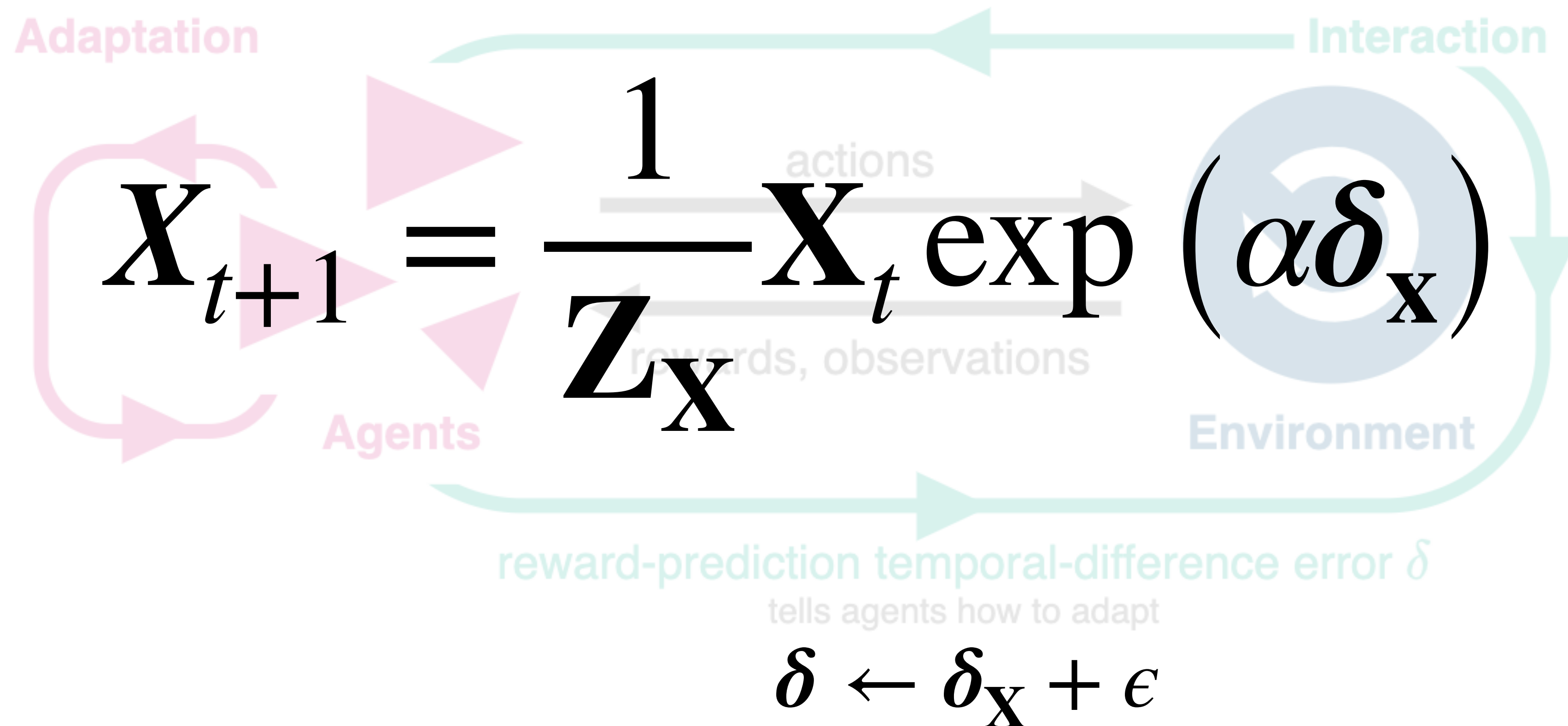
Study low-dimensional environments

Control stochasticity

Collective reinforcement learning dynamics

Treat reinforcement learning as a nonlinear dynamical system

Deterministic approximation from strategy averaging

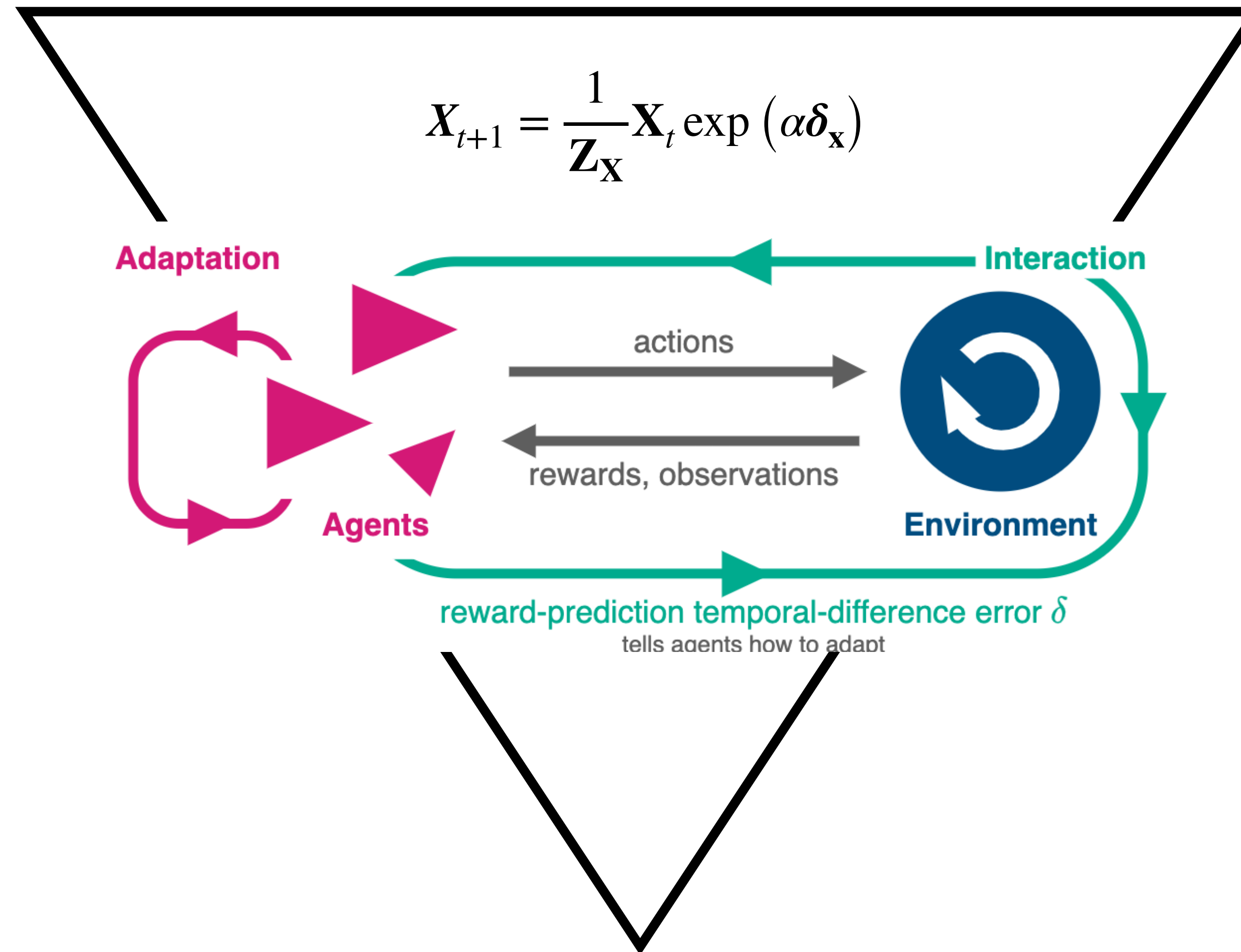


Agents learn how to act as if having a perfect model of the world

Integrating three types of models

Dynamic-system
models

Equilibrium-based
models



Agent-based models

Not a new idea

Building upon an interdisciplinary but scattered foundation

Machine Learning

Control & Engineering

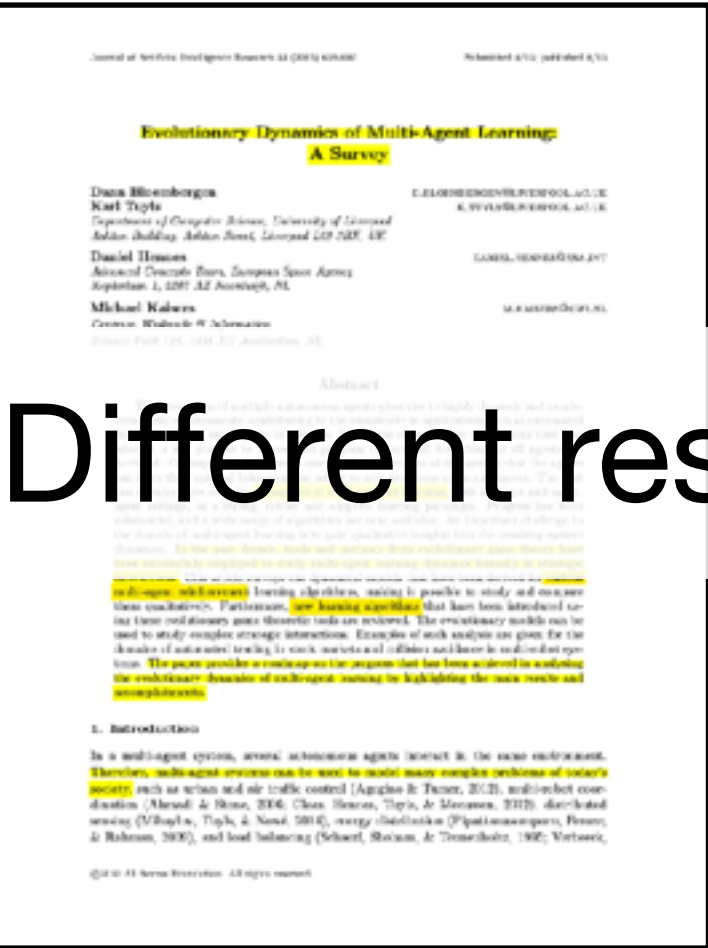
Statistical Mechanics

Economics

Sociology

Mathematical Biology

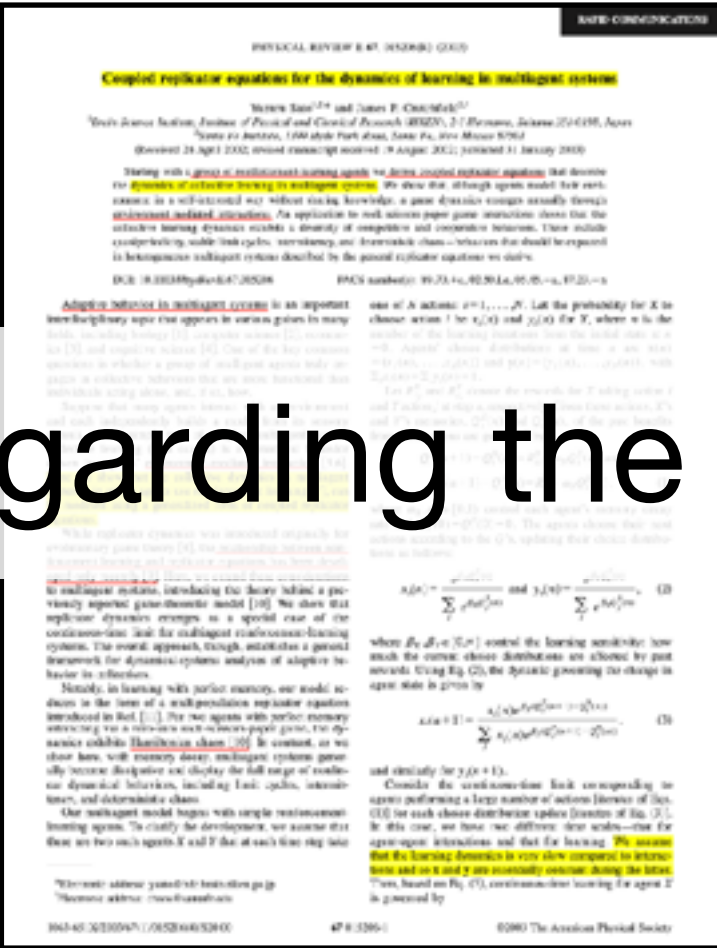
Different research goals regarding the role of equilibria & biological plausibility



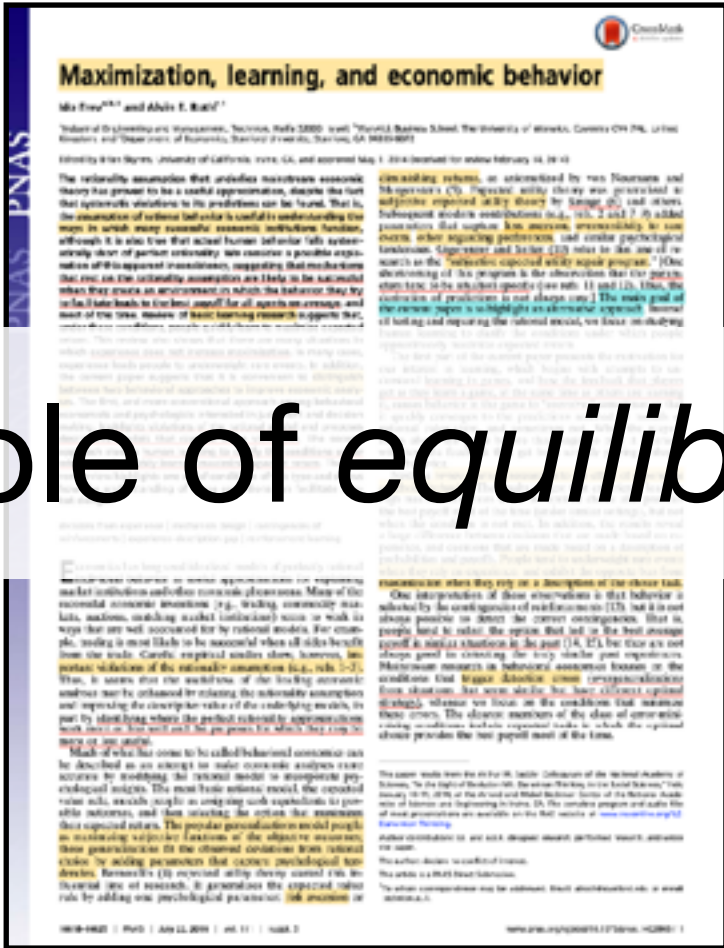
Bloembergen et al. 2015



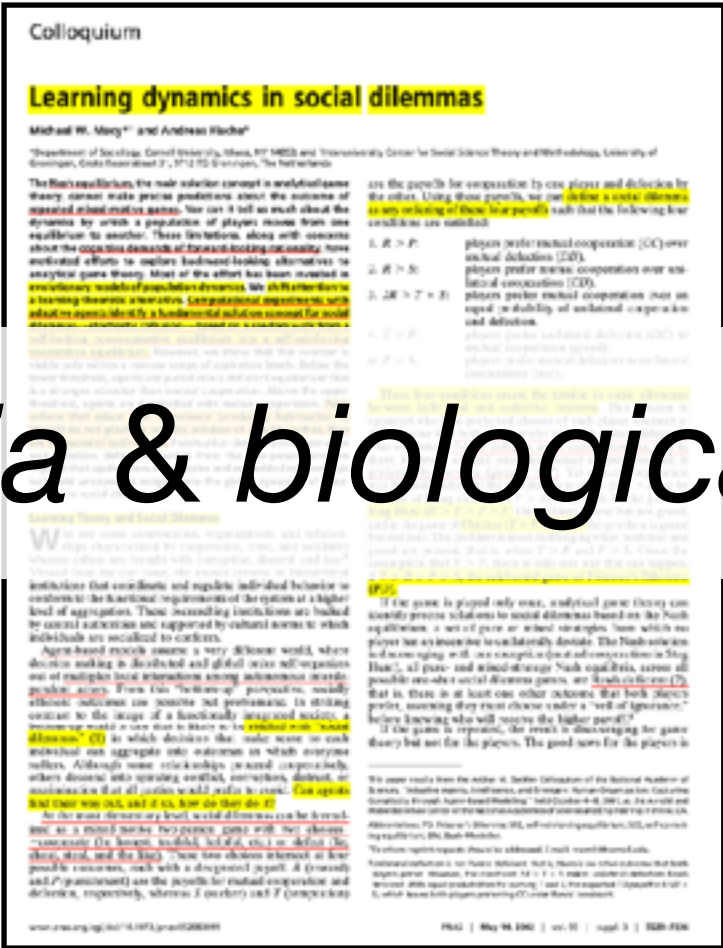
Li et al. 2022



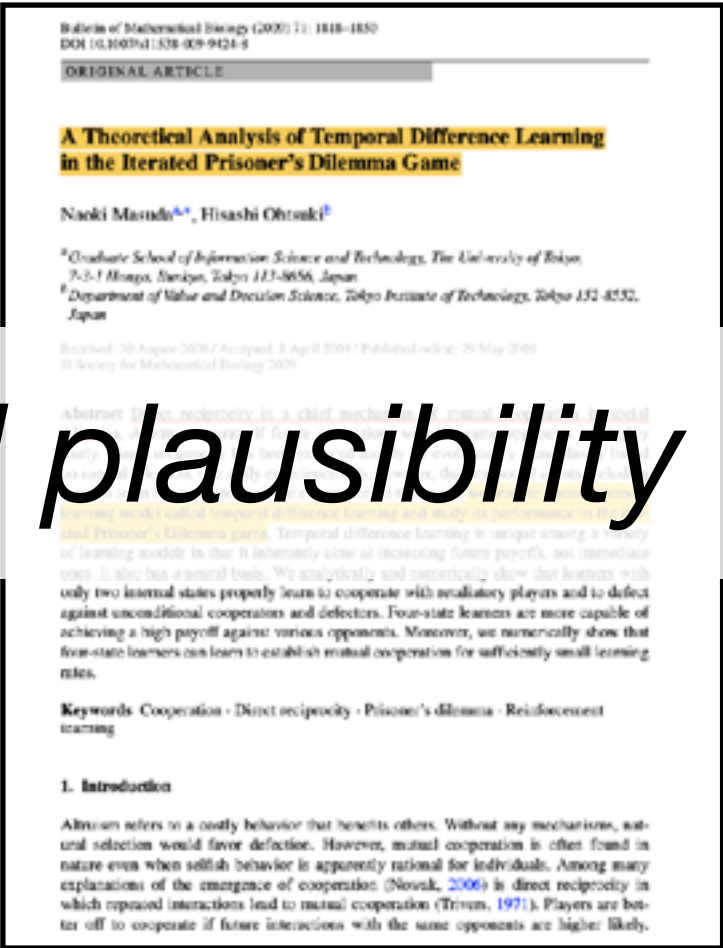
Sato & Crutchfield 2003



Erev & Roth 2014



Macy & Flache 2002



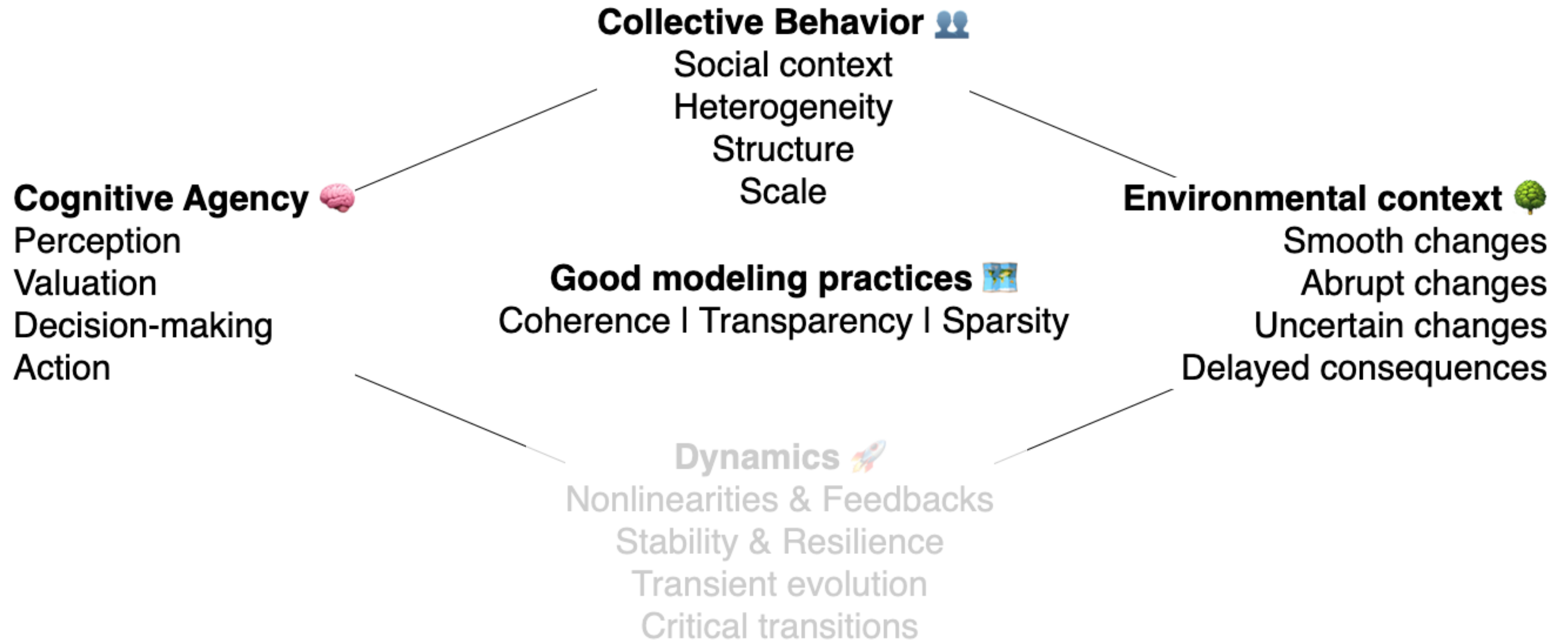
Masuda & Nakamura 2011

Our focus | *non-linear dynamics of biologically-inspired learning of cooperation*

WHAT | MARL → CSS
Cognition in contexts

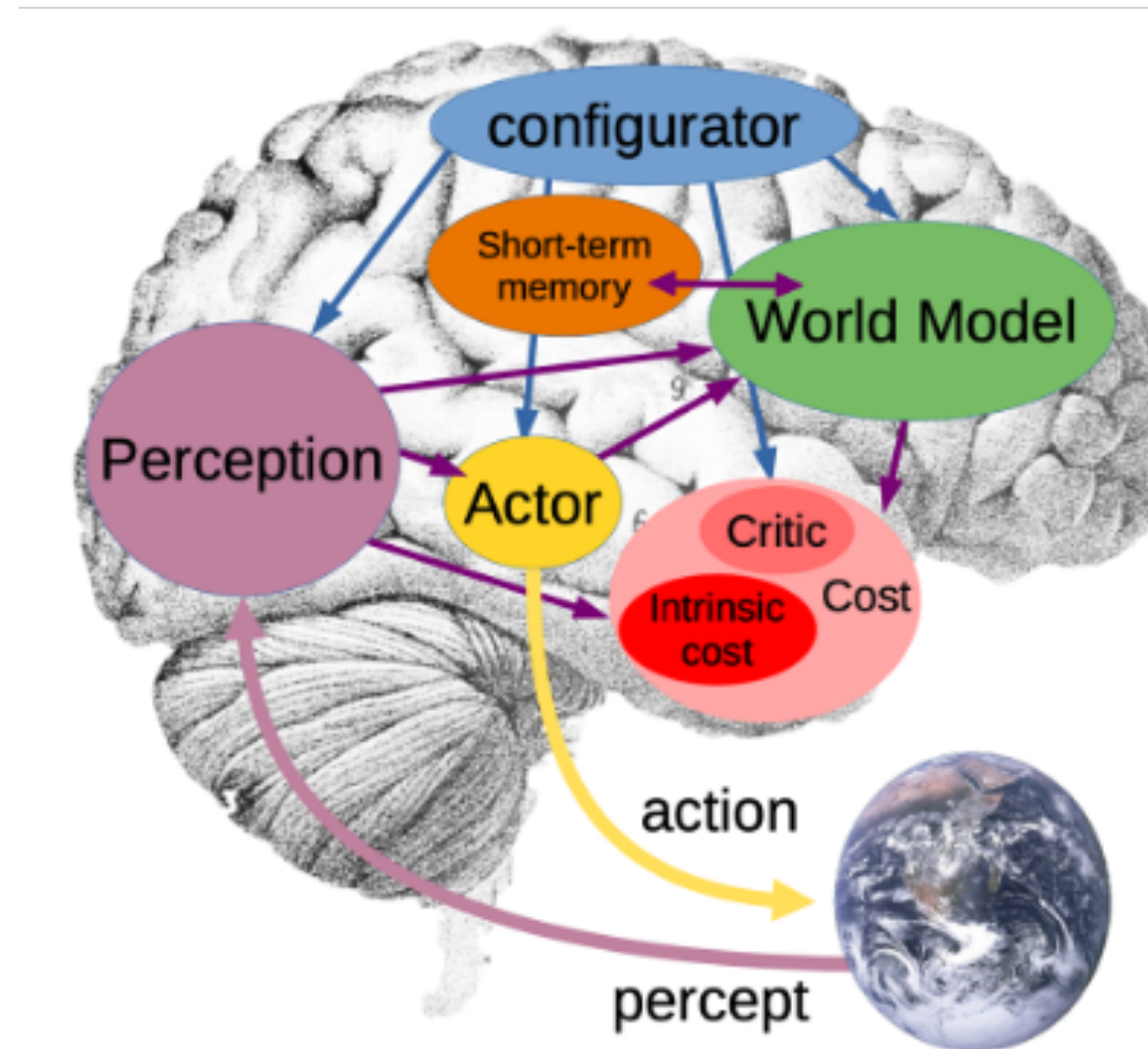
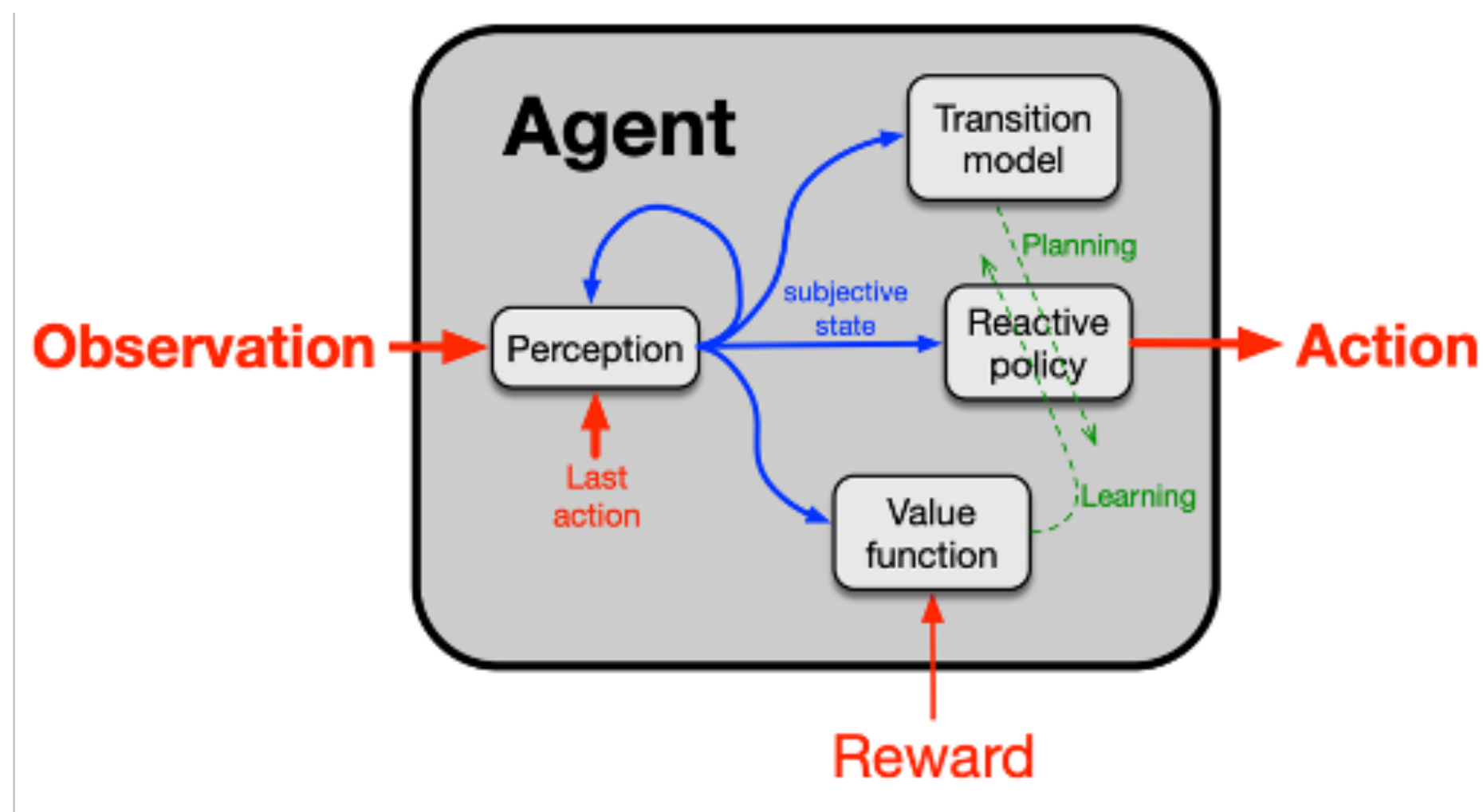
Cooperation challenges in human-machine ecologies

Why are we not cooperating more toward a sustainable future for all?

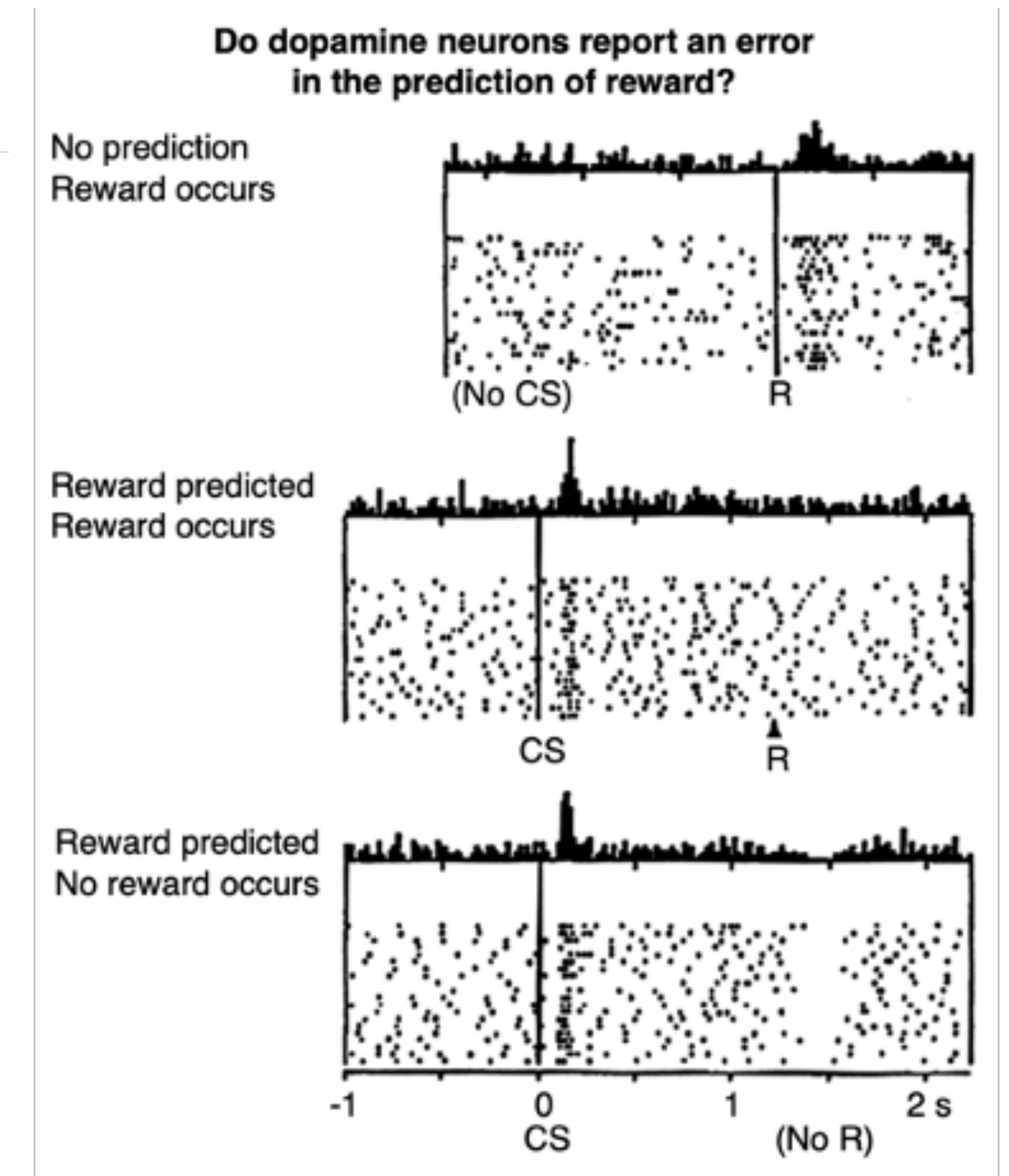


Individual cognition | Intelligent and adaptive behavior

Reinforcement learning as a general prototype model for intelligent & adaptive decision-making

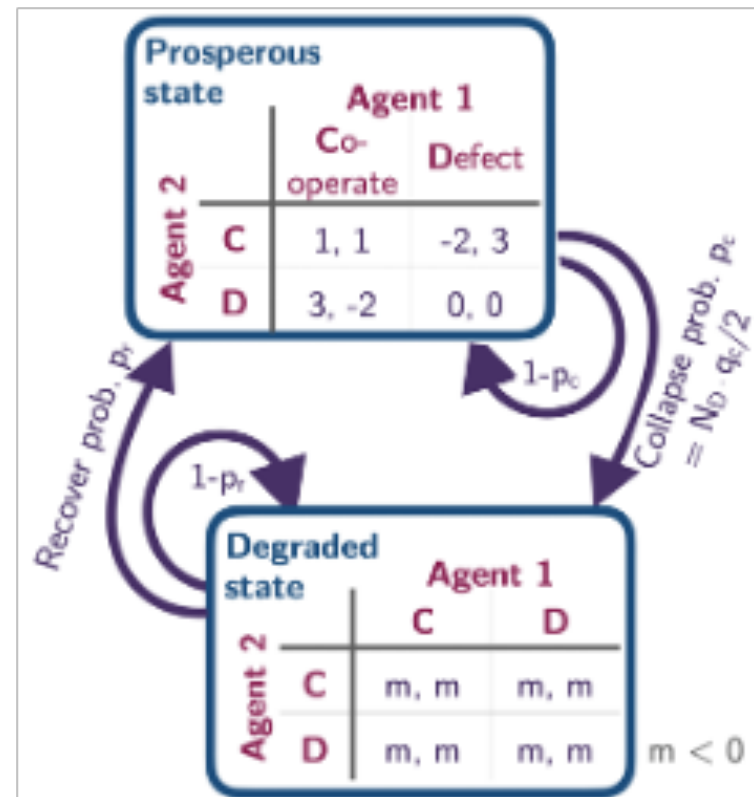


Temporal-difference reinforcement learning
empirically grounded in biology

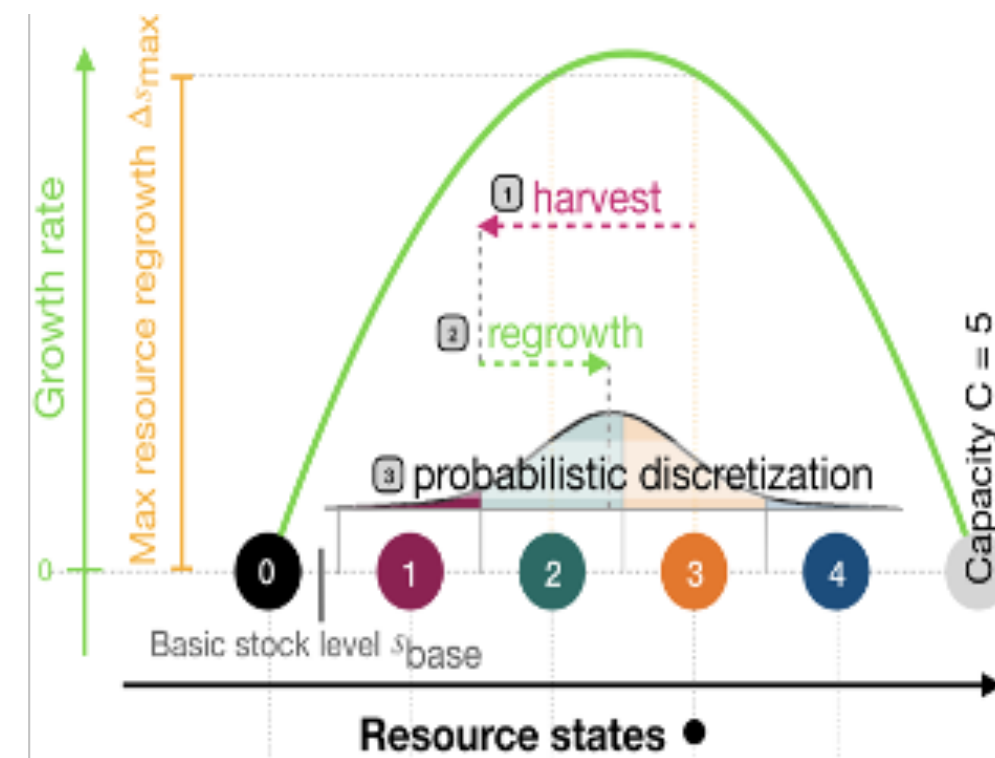


Embedded cognition | Ecology & environment

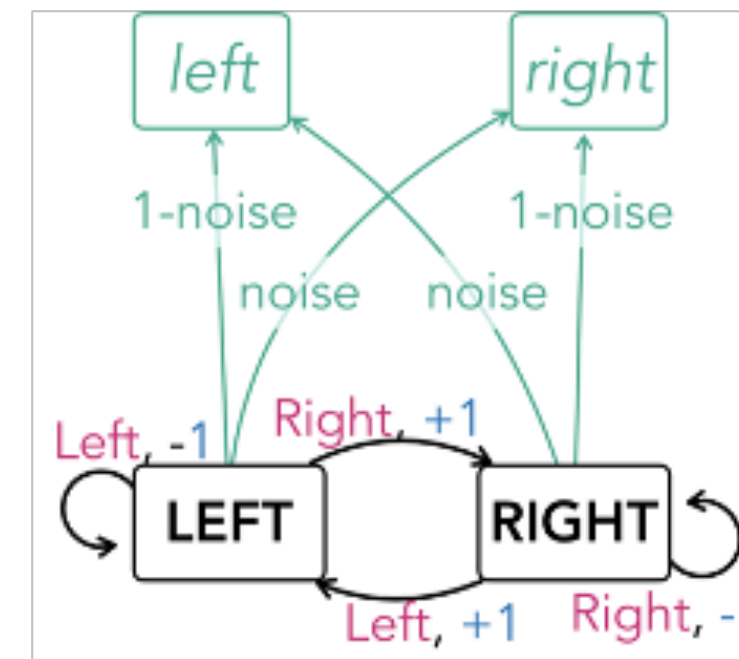
Partially observable stochastic games as a general model for environmental context with delayed and stochastic consequences



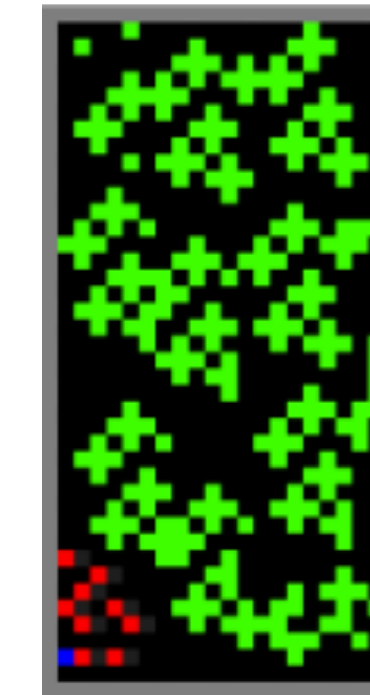
Abrupt transitions



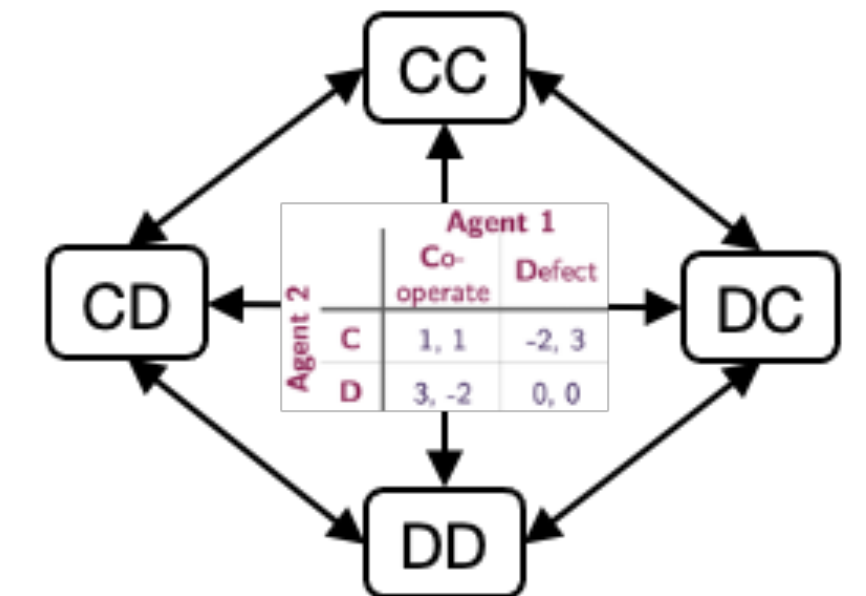
Smooth dynamics



Partial observability



Spatial



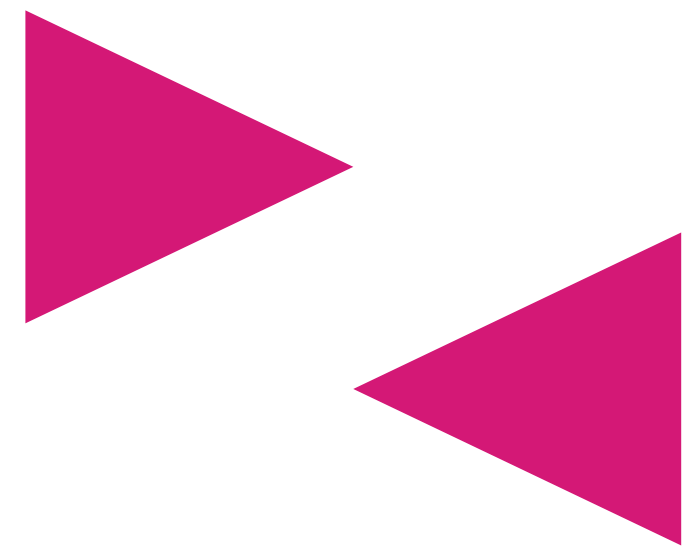
Social environment

Pure strategic interactions or noisy reward feedback included

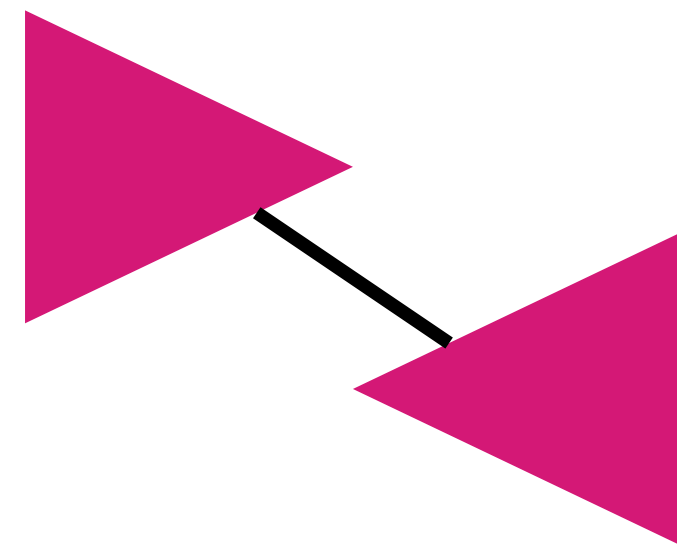
Discretization powerful - numerically and conceptually

Collective cognition | Multi-agent systems

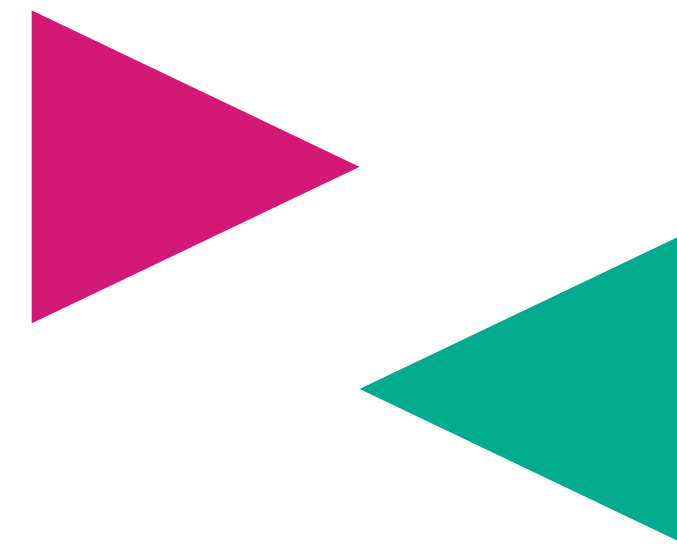
Multi-agent systems as a general model to micro-found collective behavior



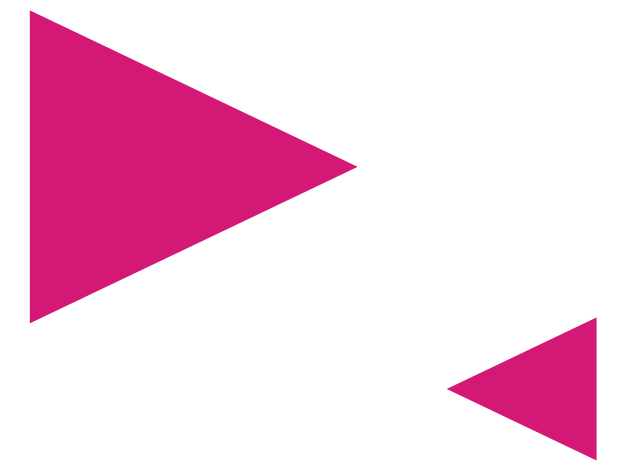
Anonymous



Structurally linked



Heterogeneous



Hierarchical

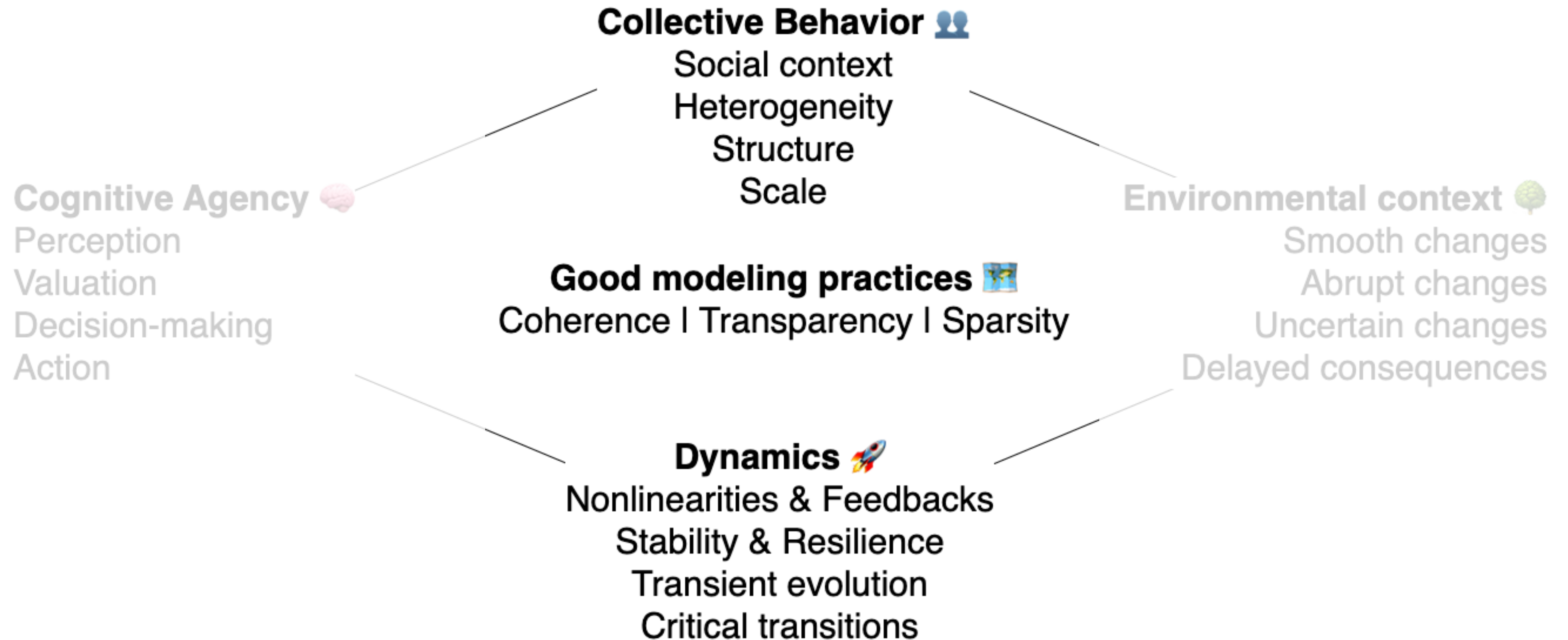
Large collectives cause a curse of dimensionality

Mean-field approaches can help

WHAT | CSS → MARL
Emergent phenomena

Cooperation challenges in human-machine ecologies

Why are we not cooperating more toward a sustainable future for all?

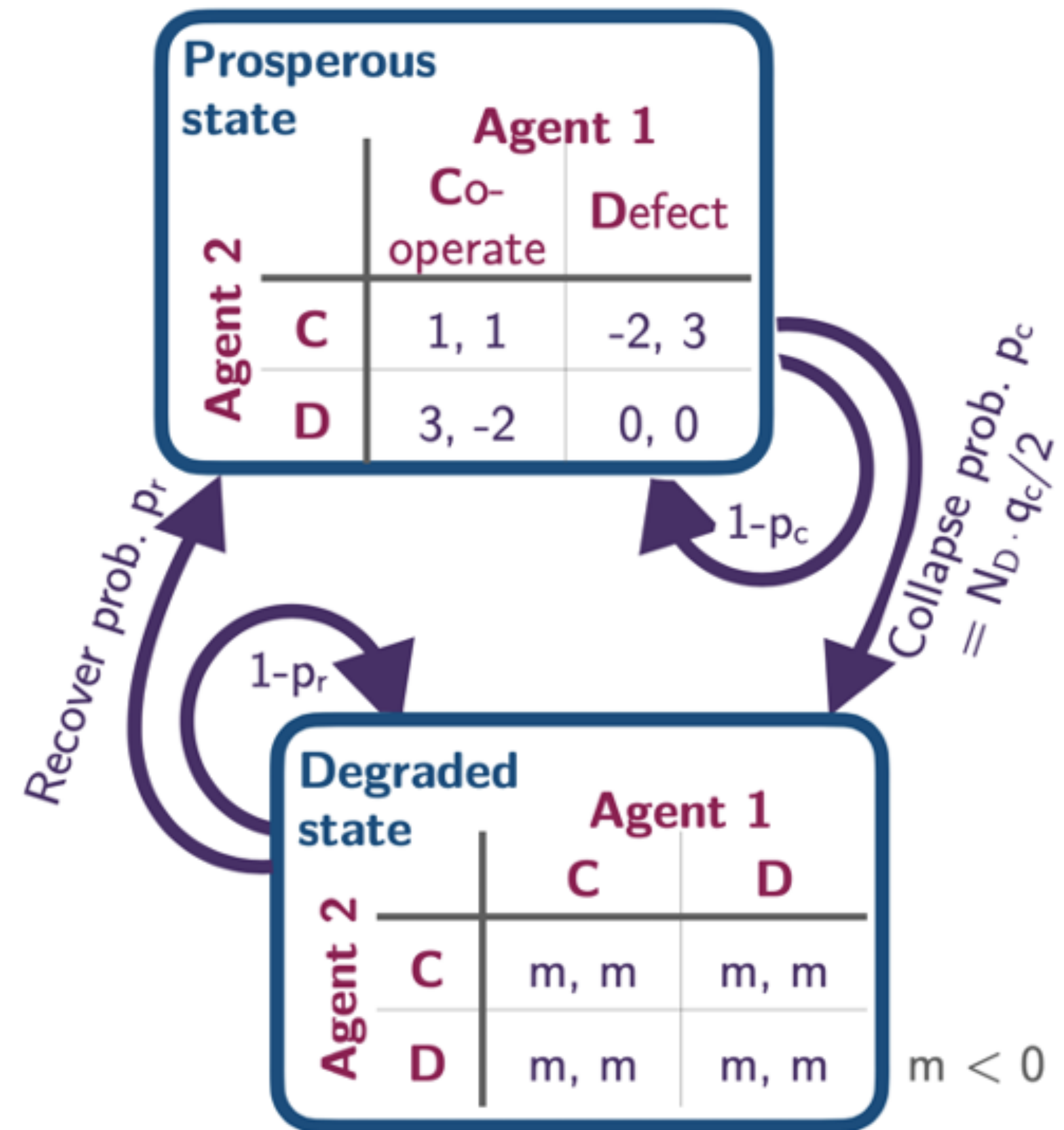


A minimal model of

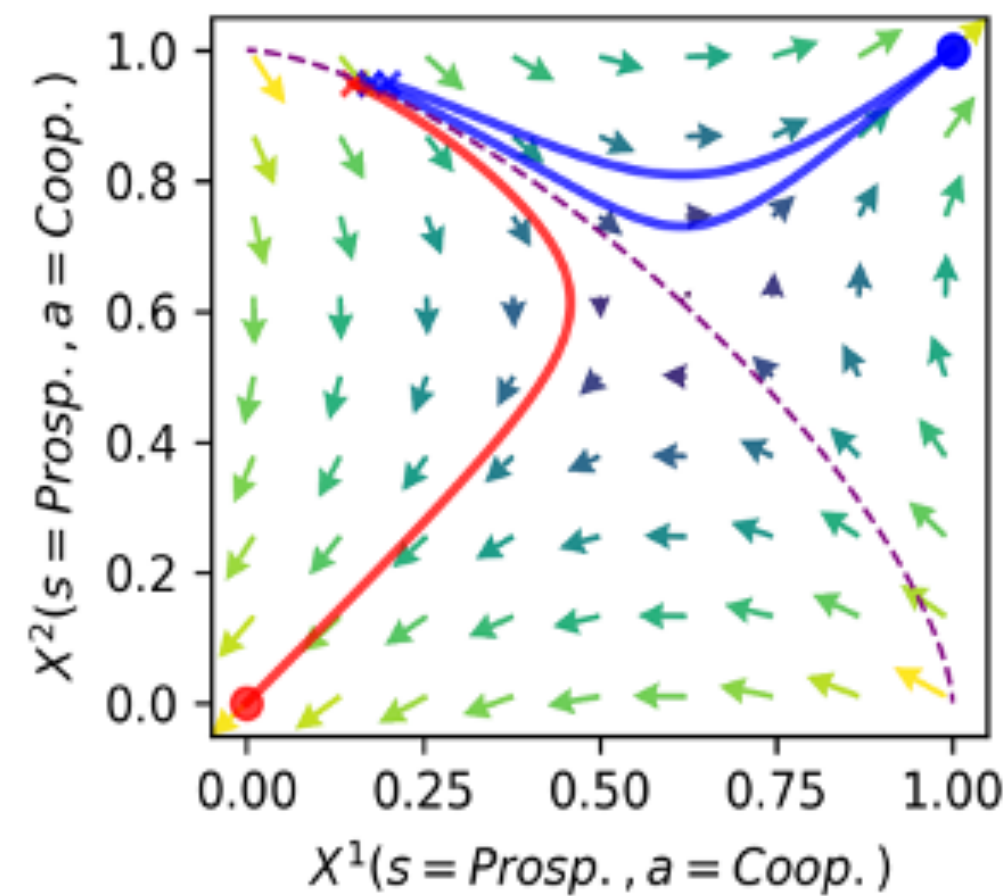
Collective action

from **individual** adaptive intelligent decision-making via RL

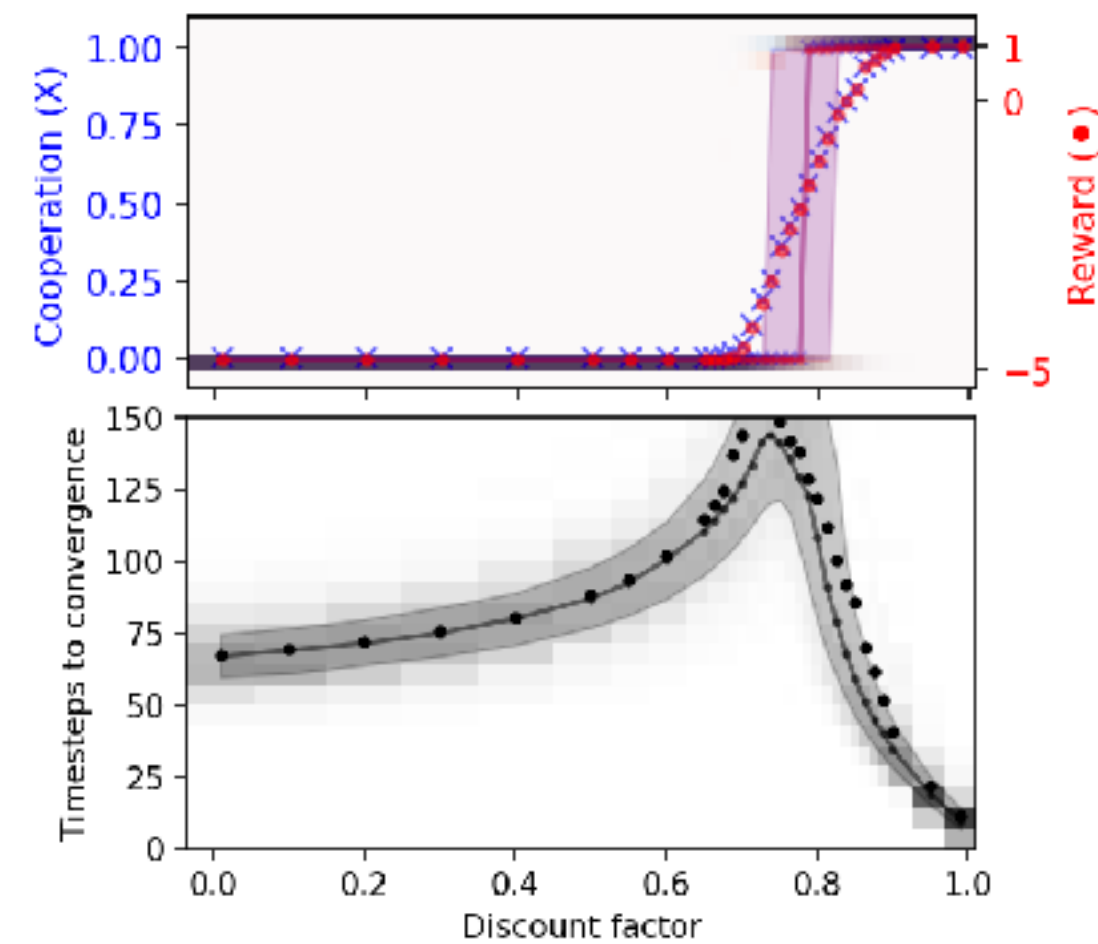
in **environmental** commons with catastrophic thresholds



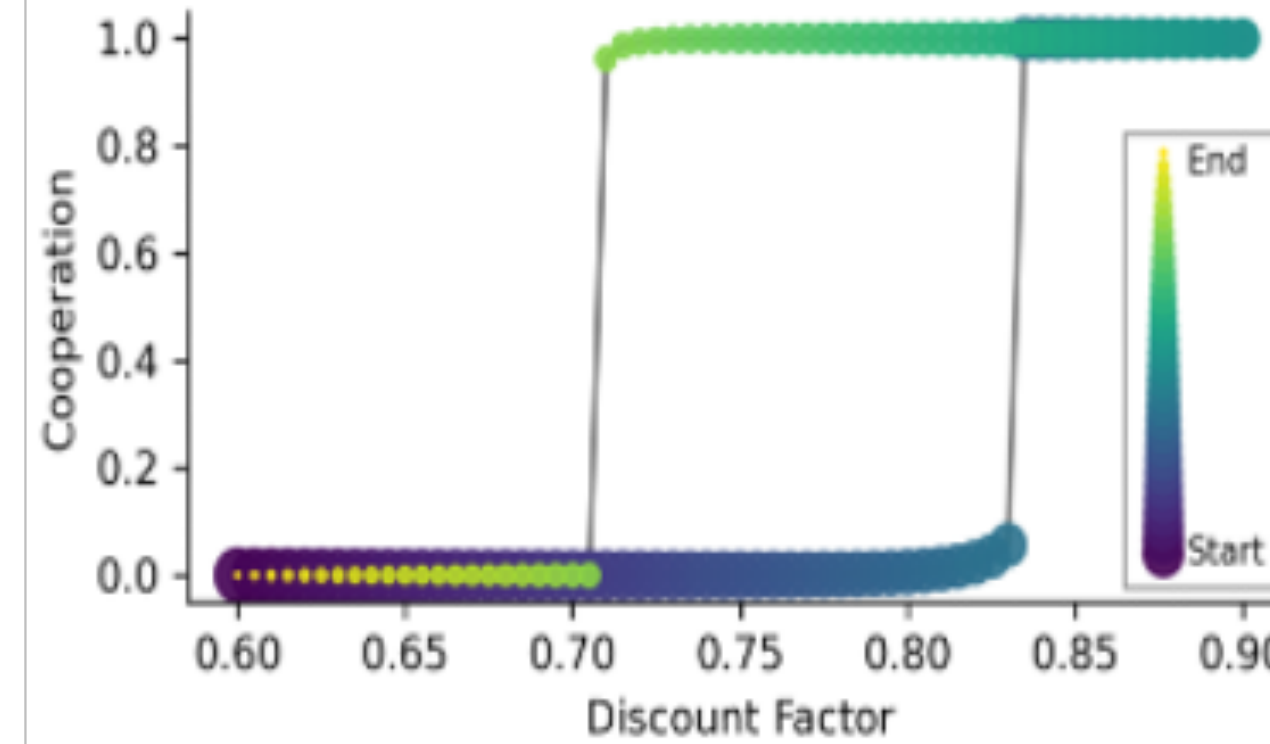
Complex emergent phenomena



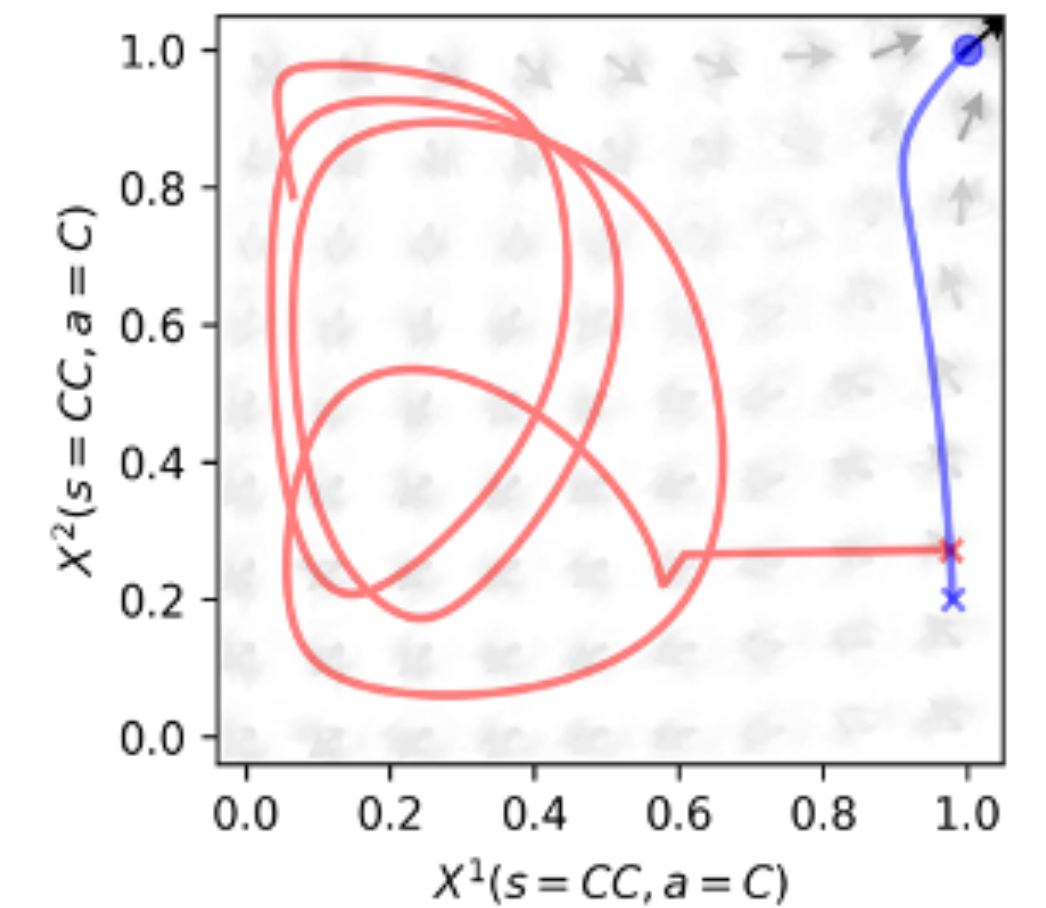
Multi-Stability



Abrupt Transitions



Hysteresis



Dynamic Regimes

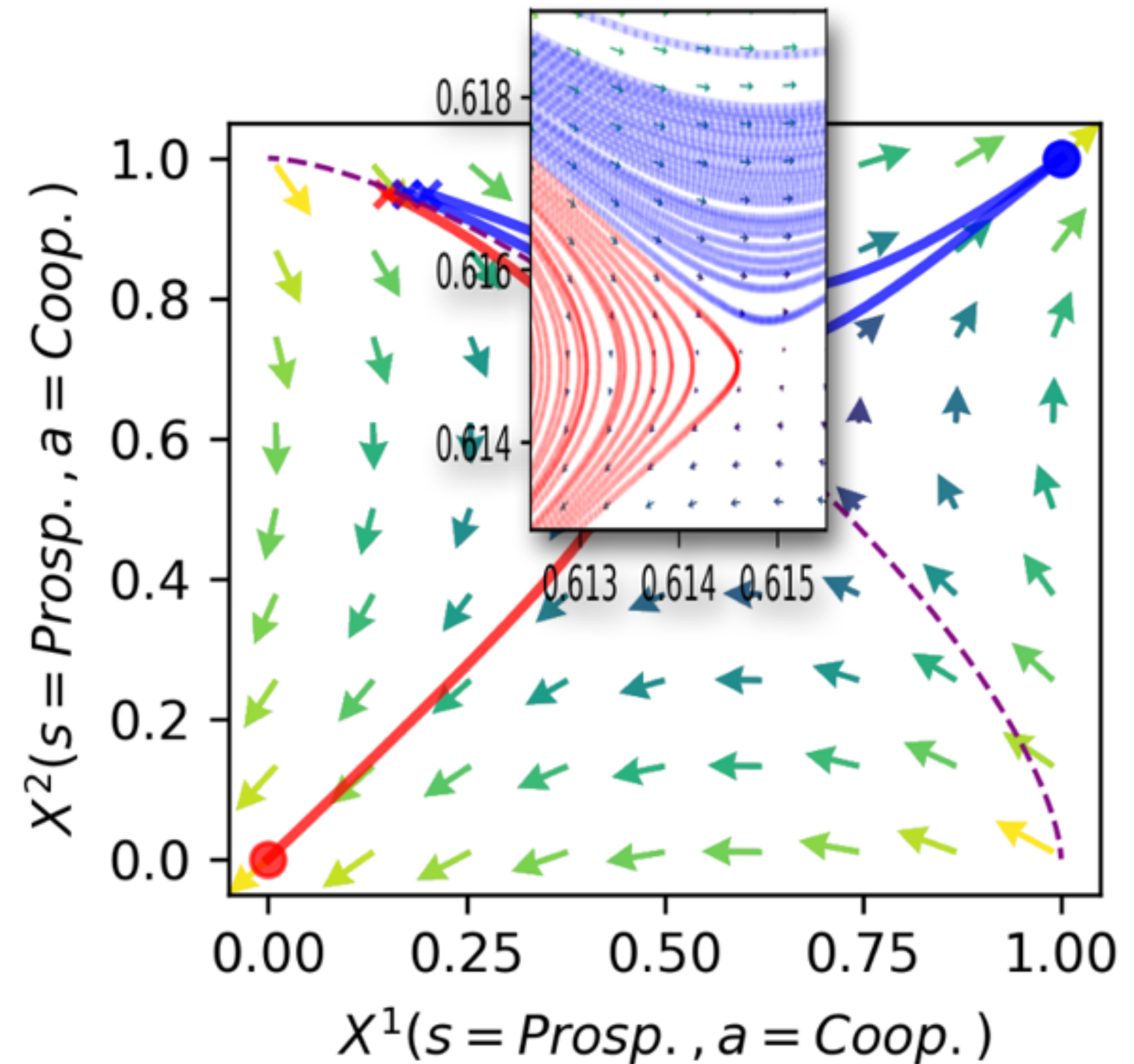
Multi-stability in commons with catastrophic thresholds

Basin of attraction (of the cooperative equilibrium) as a measure of **collective intelligence** Leonard & Levin, 2022

Encoding information in equilibrium strategy as **emergent collective memory**

Geometric view for **ad-hoc teamwork**

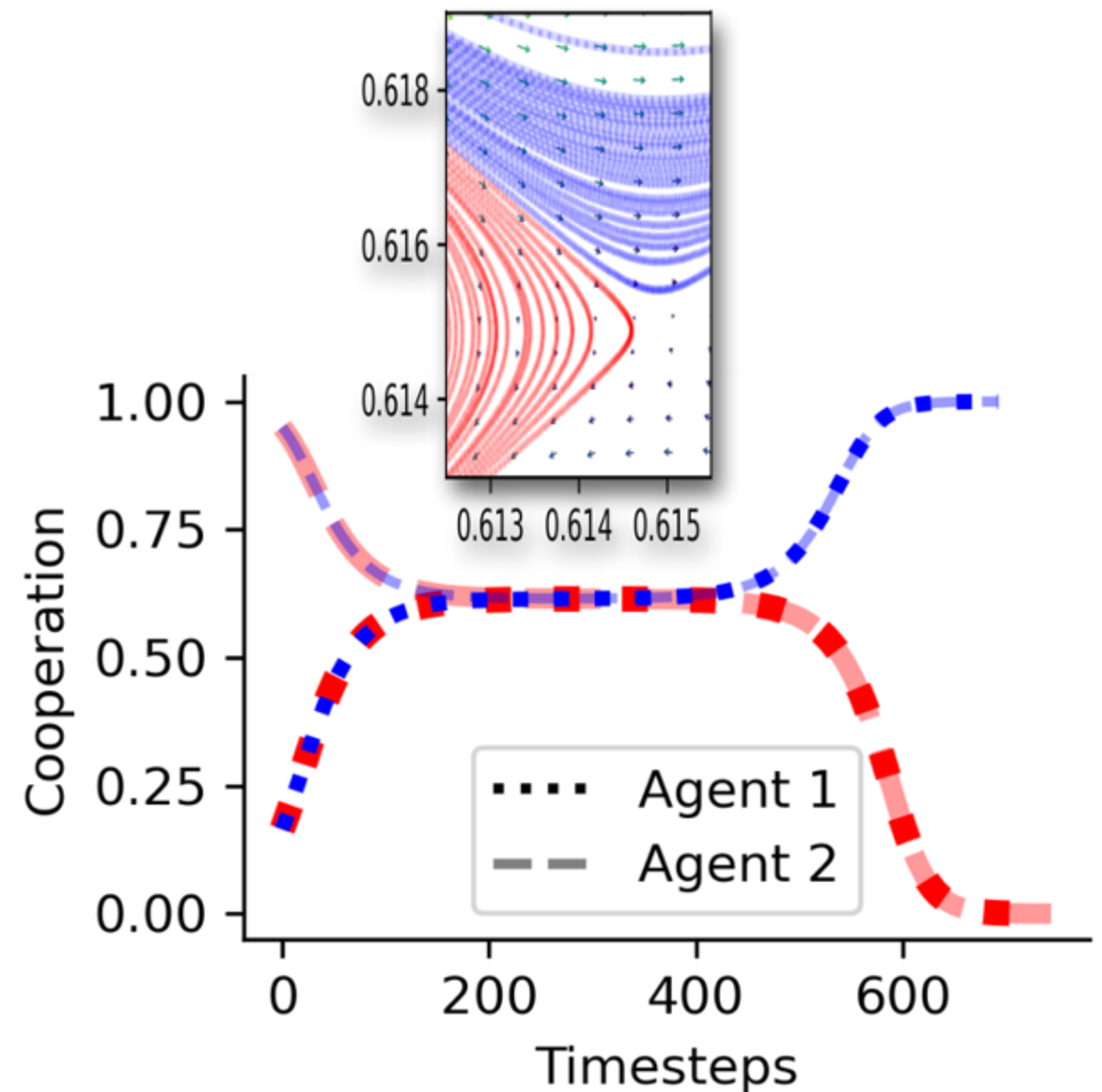
Basin of attraction as a measure of (social-ecological) **resilience**



Multi-stability in commons with catastrophic thresholds

Agents' learning almost converged until suddenly drastic and fast changes may happen again

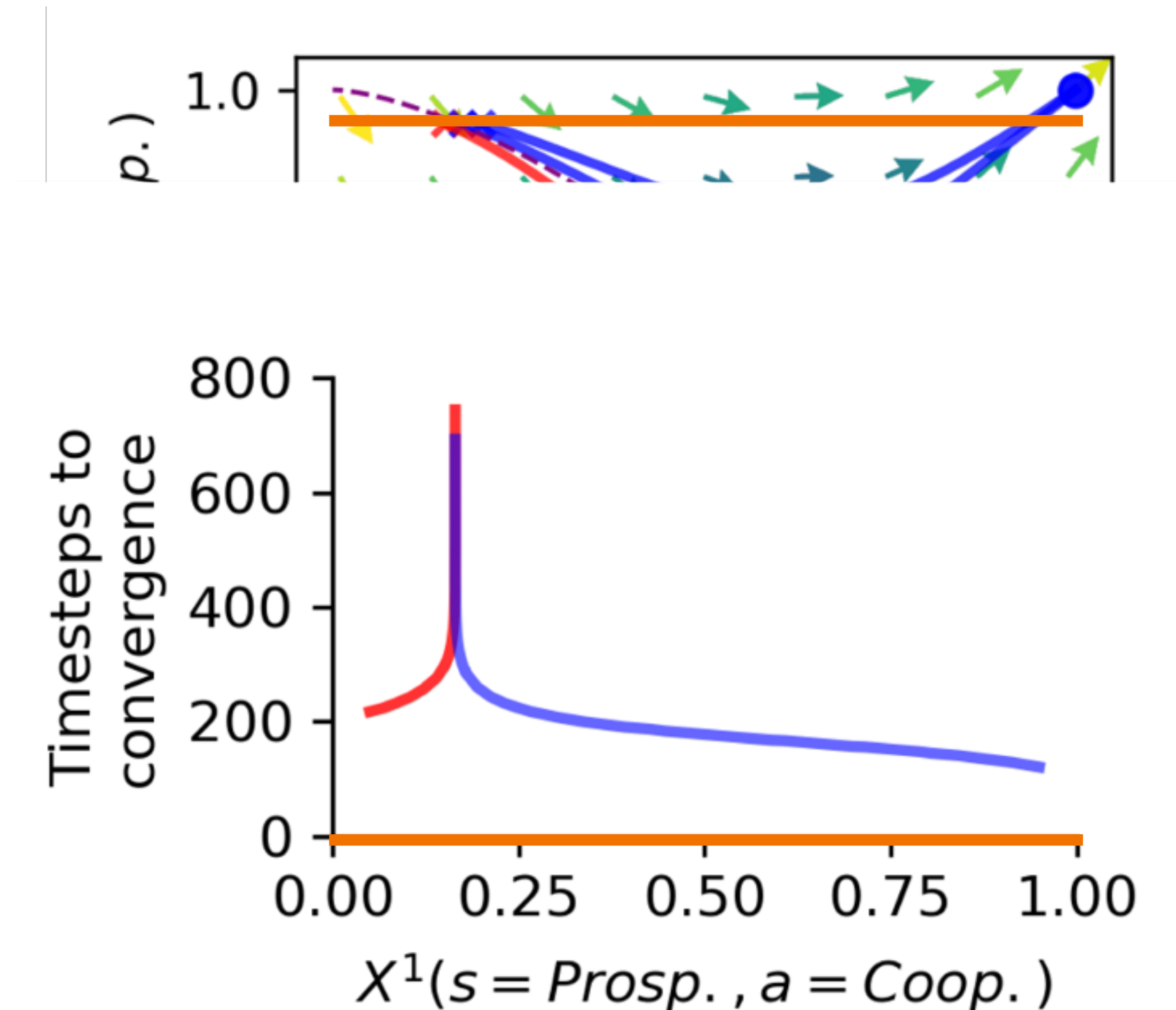
Emergent separation of time scales



Multi-stability in commons with catastrophic thresholds

Critical slowing down at the social tipping point

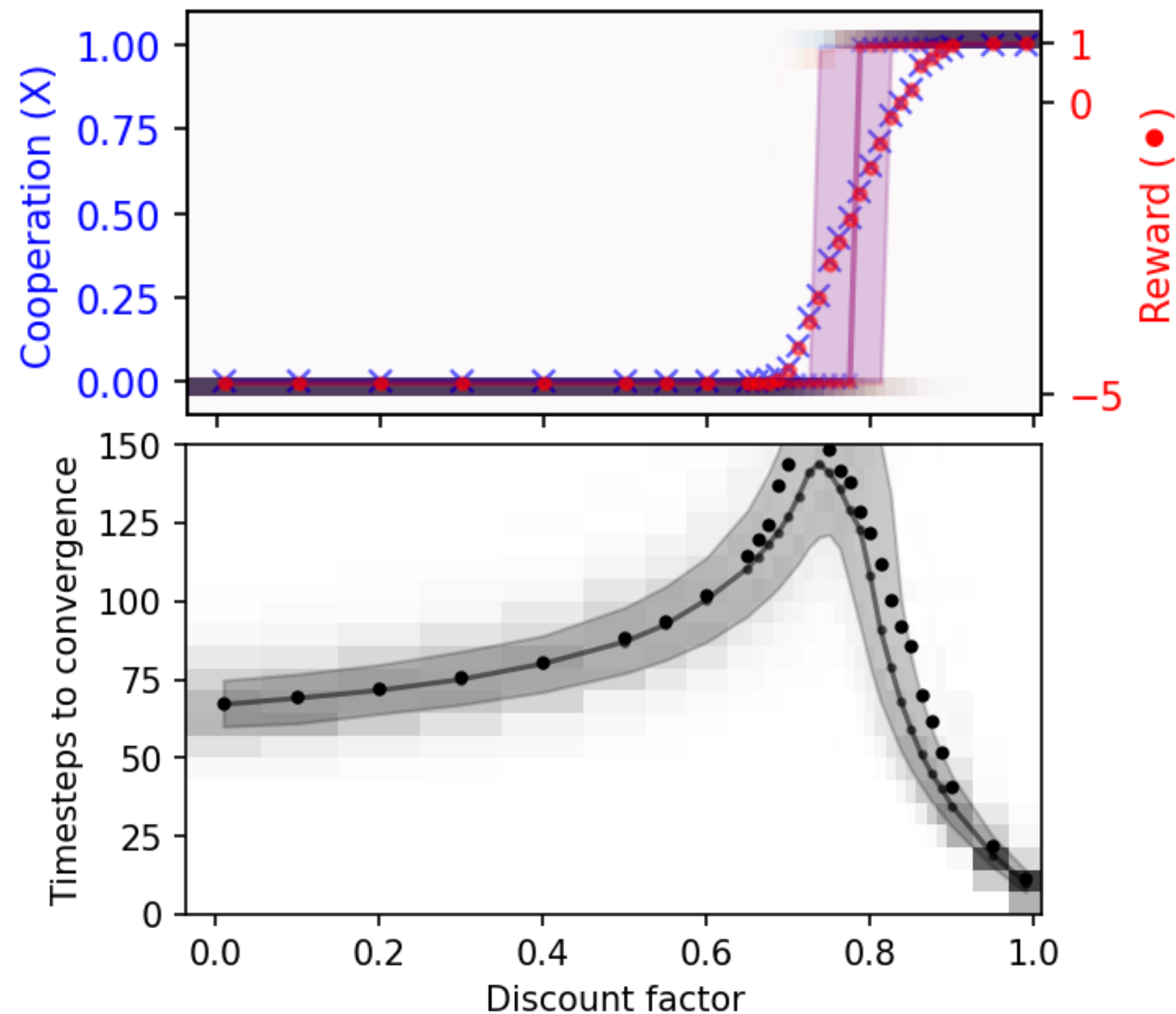
- convergence less relevant
- transient learning dynamics
- early warning indicators



Critical transitions in commons with thresholds

when agents become more future-caring

- convergence less relevant
- transient learning dynamics
- early warning indicators



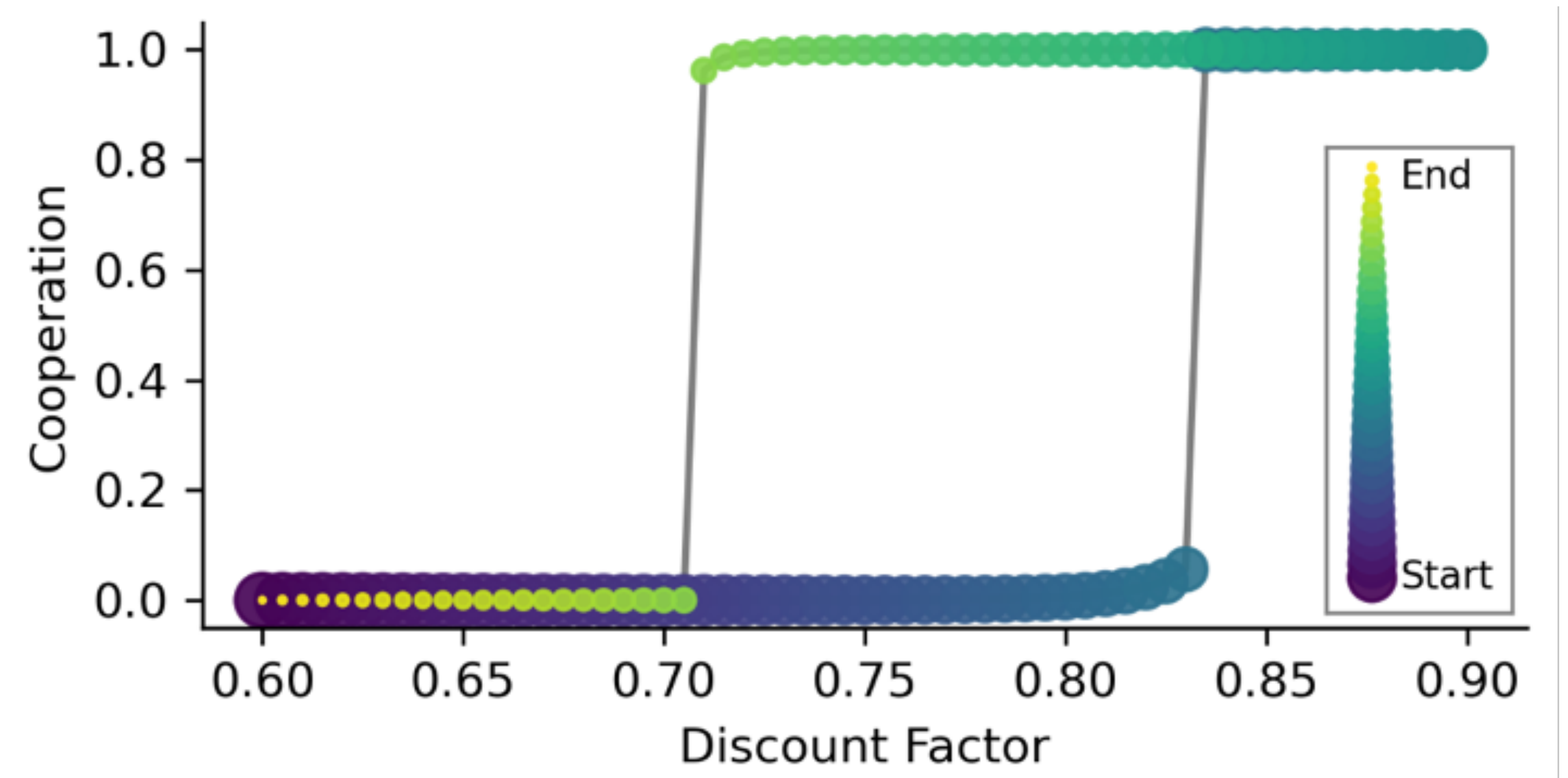
Hysteresis

e.g., when agent's future-caring weakens again

Another form of collective memory

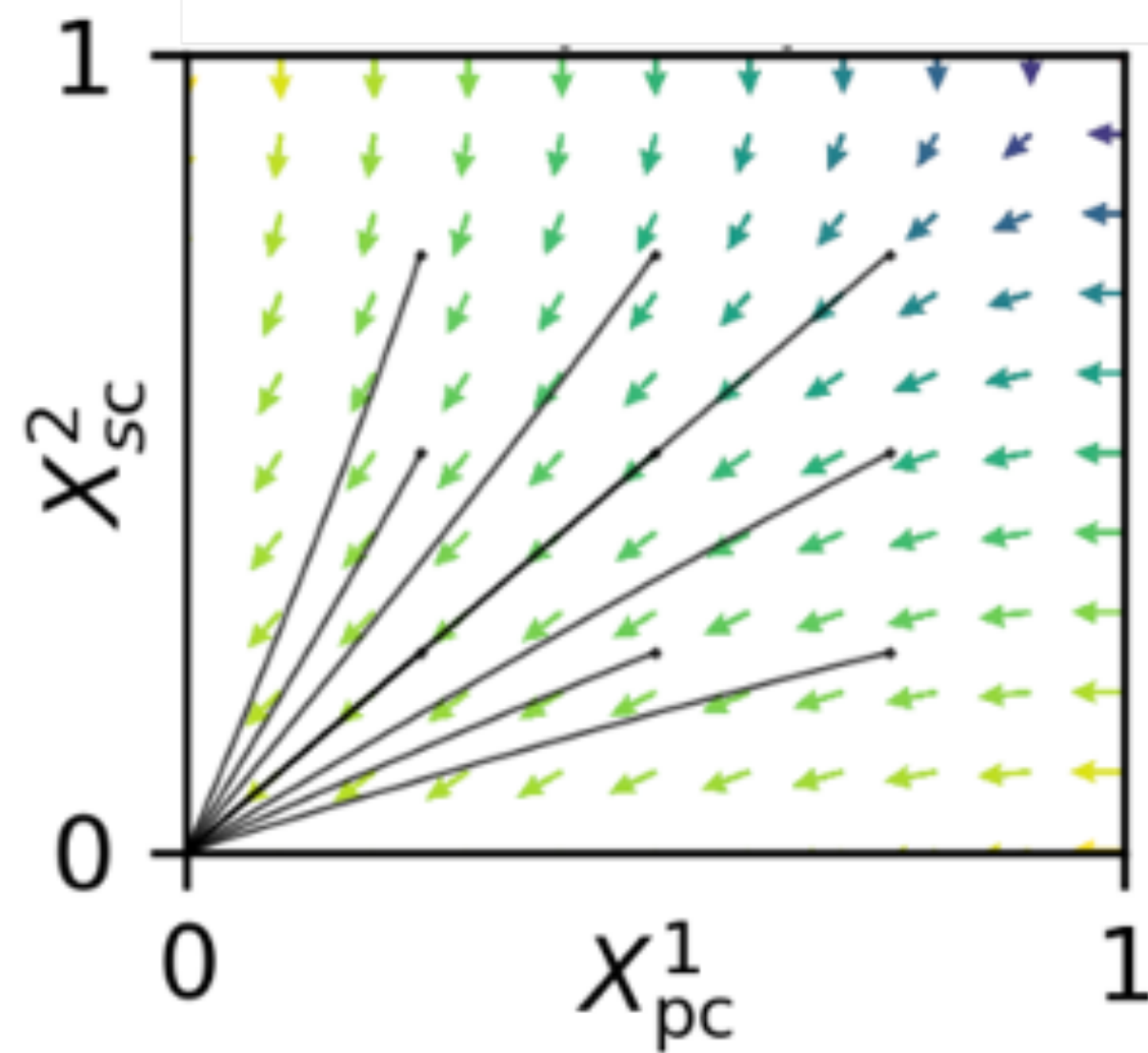
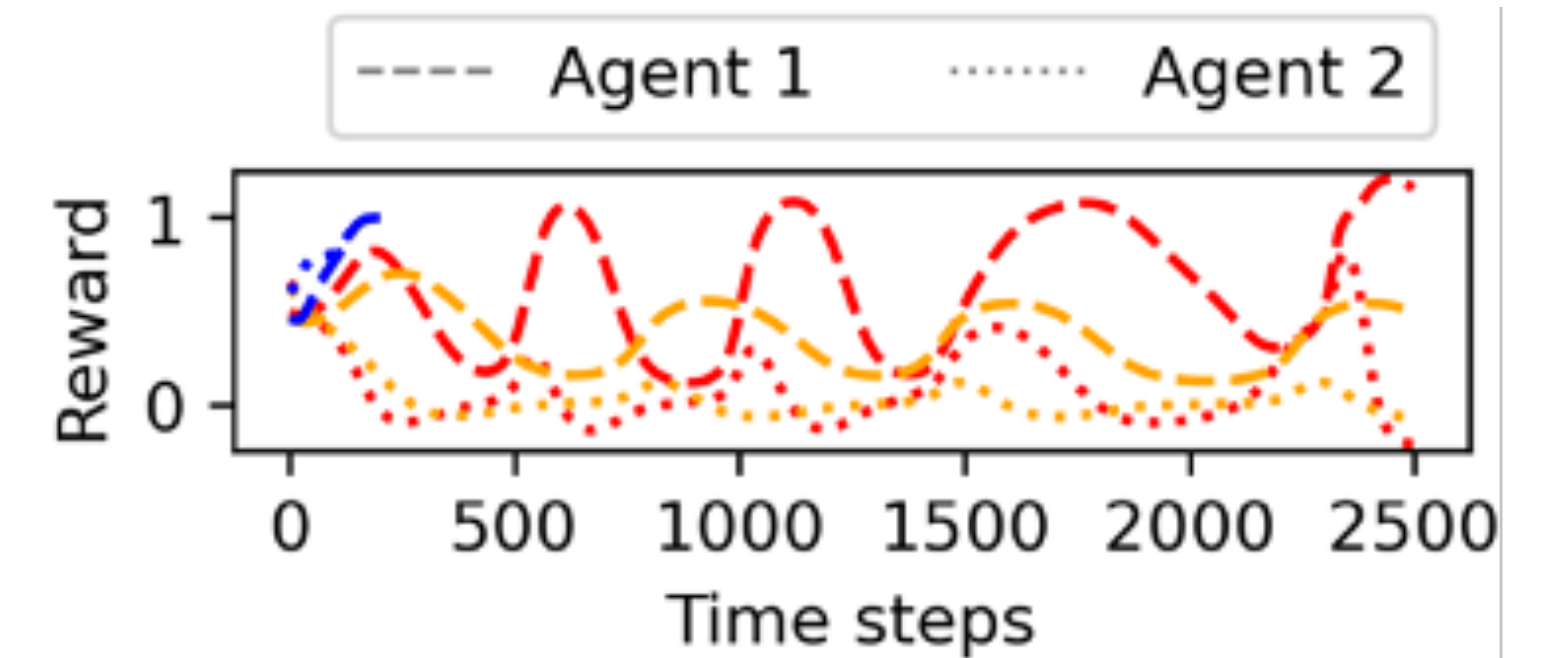
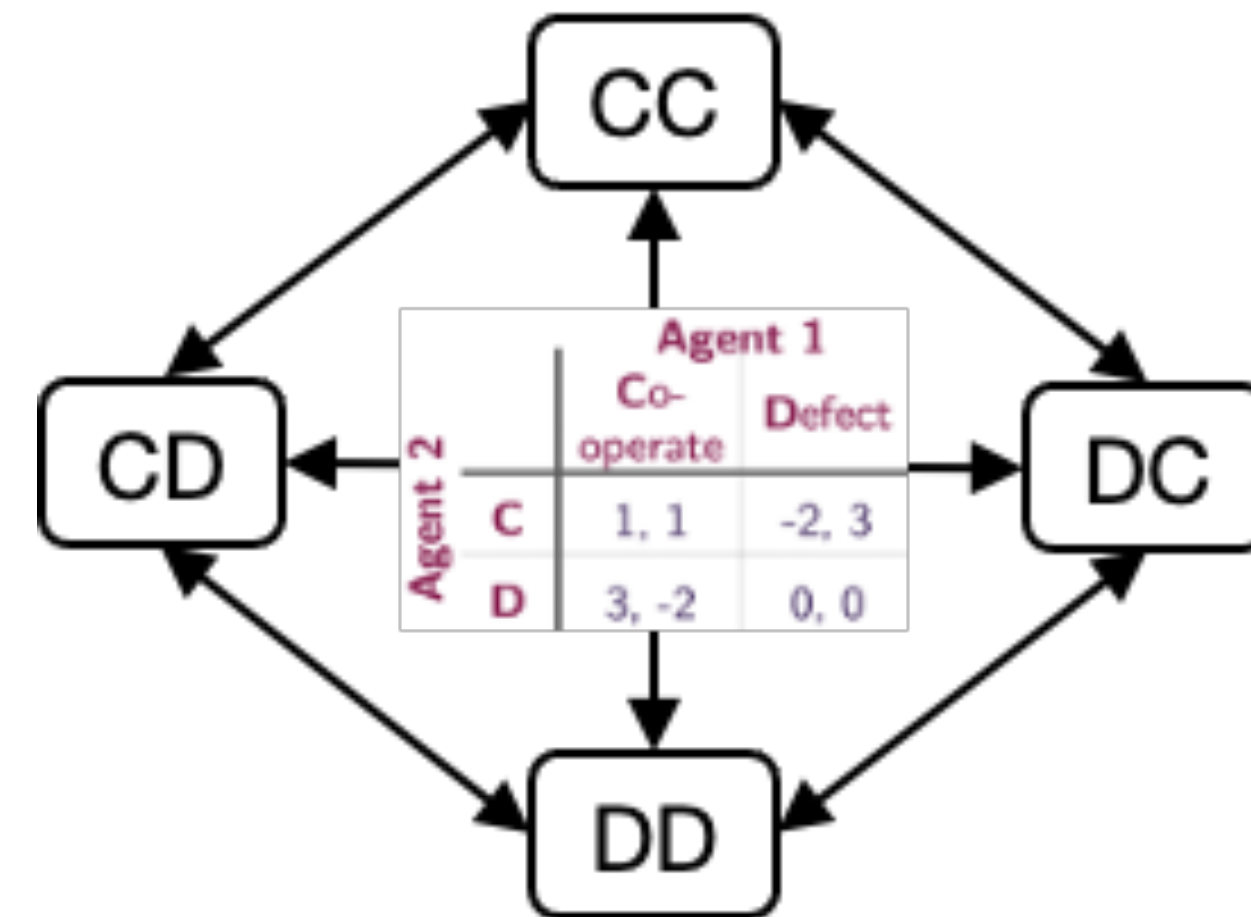
Important for social tipping elements

Potential for sustainability interventions



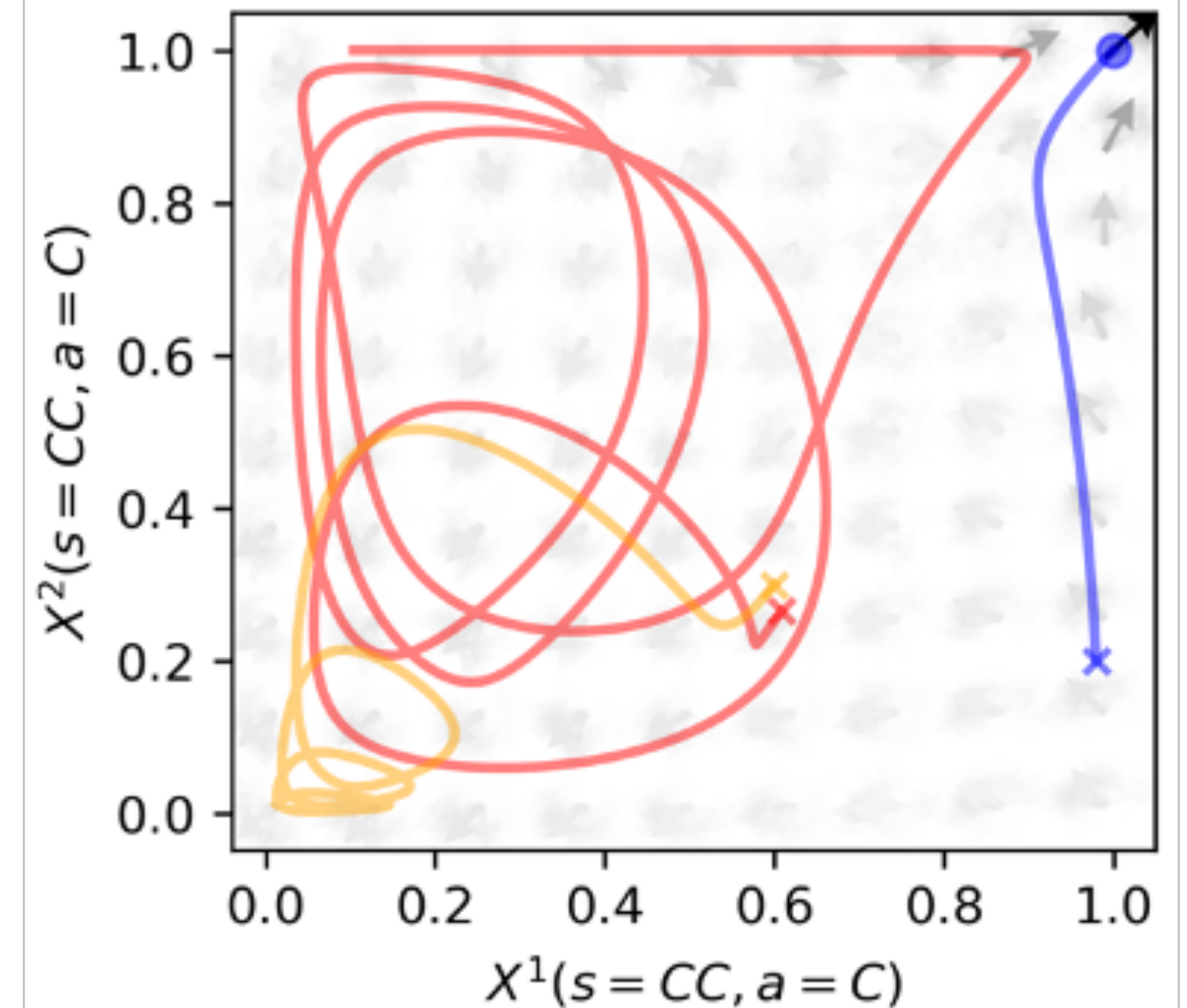
Complex collective action dynamics in social dilemma

| | | Agent 1 | |
|---------|---|------------|--------|
| | | Co-operate | Defect |
| Agent 2 | C | 1, 1 | -2, 3 |
| | D | 3, -2 | 0, 0 |



When agents condition on the previous round's action, they can

- learn to cooperate
- learn on oscillating and unpredictable transients



CONCLUSION



Collective cooperative intelligence

Wolfram Barfuss^{a,1} , Jessica Flack^b, Chaitanya S. Gokhale^{c,d} , Lewis Hammond^e , Christian Hilbe^c , Edward Hughes^f, Joel Z. Leibo^f , Tom Lenaerts^{g,h,i} , Naomi Leonard^j , Simon Levin^k , Udari Madhushani Schwag^{l,2} , Alex McAvoy^{m,n} , Janusz M. Meylahn^o , and Fernando P. Santos^p

Edited by Marco A. Janssen, Arizona State University, Tempe, AZ; received December 12, 2023; accepted May 6, 2024 by Editorial Board Member Elke U. Weber

Cooperation at scale is critical for achieving a sustainable future for humanity. However, achieving collective, cooperative behavior—in which intelligent actors in complex environments jointly improve their well-being—remains poorly understood. Complex systems science (CSS) provides a rich understanding of collective phenomena, the evolution of cooperation, and the institutions that can sustain both. Yet, much of the theory in this area fails to fully consider individual-level complexity and environmental context—largely for the sake of tractability and because it has not been clear how to do so rigorously. These elements are well captured in multiagent reinforcement learning (MARL), which has recently put focus on cooperative (artificial) intelligence. However, typical

or reward scheme, e.g., via taxes and subsidies, that makes selfish actions less attractive to individuals, whereas bottom-up arrangements and social reciprocity find a way to punish defecting behavior through peers (4). However, the challenge of cooperation is far from being solved.

First, large collectives complicate the emergence and robustness of cooperation. Although many mechanisms have been identified that support its emergence and maintenance, it is also widely recognized that effective scaling mechanisms are rare (5): in global public goods, such as the climate, there is no single outside actor with sufficient enforcement power to ensure cooperation authoritatively. In situations involving many, mostly anonymous, participants, reciprocity mechanisms are hard to stabilize (6). Hence, a key

pyCRLD work-in-progress Python package

Collective Reinforcement Learning Dynamics (CRLD)

<https://barfusslab.github.io/pyCRLD/>

pyCRLD

CRLD

Collective Reinforcement Learning Dynamics in Python

is a tool to model the collective dynamics emerging from multi-agent reinforcement learning.

Multi-agent reinforcement learning (MARL) provides a comprehensive framework for studying the interplay among learning, representation, and decision-making between multiple actors. As a result, it offers an integrating platform to in-silico test hypotheses and build theory on how different cognitive mechanisms affect collective adaptive behavior in complex environments.

On this page

- [Install](#)
- [How to use](#)

CRLD

Agents

- Strategy Actor-Critic
- Strategy SARSA
- Strategy AC (part. Obs.)
- Value SARSA
- Strategy Base
- Value Base
- Strategy Base (part. Obs.)
- Base (part. Obs.)
- Base

Environments

- Environment Base
- History Embedding
- Social Dilemma
- Ecological Public Good
- Uncertain Social Dilemma

```
graph LR; Agents[Agents] -- actions --> Environment((Environment)); Environment -- "observations, rewards" --> Agents;
```


The diagram illustrates the interaction between Agents and the Environment. On the left, three pink triangles represent the Agents. On the right, a large blue circle represents the Environment. A top arrow points from the Agents to the Environment, labeled 'actions'. A bottom arrow points from the Environment back to the Agents, labeled 'observations, rewards'.

CSMofHEI course material

Complex Systems Modeling of Human-Environment Interactions

<https://wbarfuss.github.io/csm-of-hei/>



Complex Systems
Modeling of
Human-
Environment
Interactions 



Preface

1 Introduction

Dynamic Systems 

2 Nonlinearity

3 Tipping elements

Three types of models

When addressing societal challenges, the concept of the *three types of knowledge* helps to produce not only knowledge on problems but also knowledge that helps to overcome those problems ([Buser & Schneider, 2021](#)). In general, the concept applies to all research methodologies. We will specifically discuss it in the context of formal modeling, transforming it into *three types of models* ([Figure 1.10](#)).

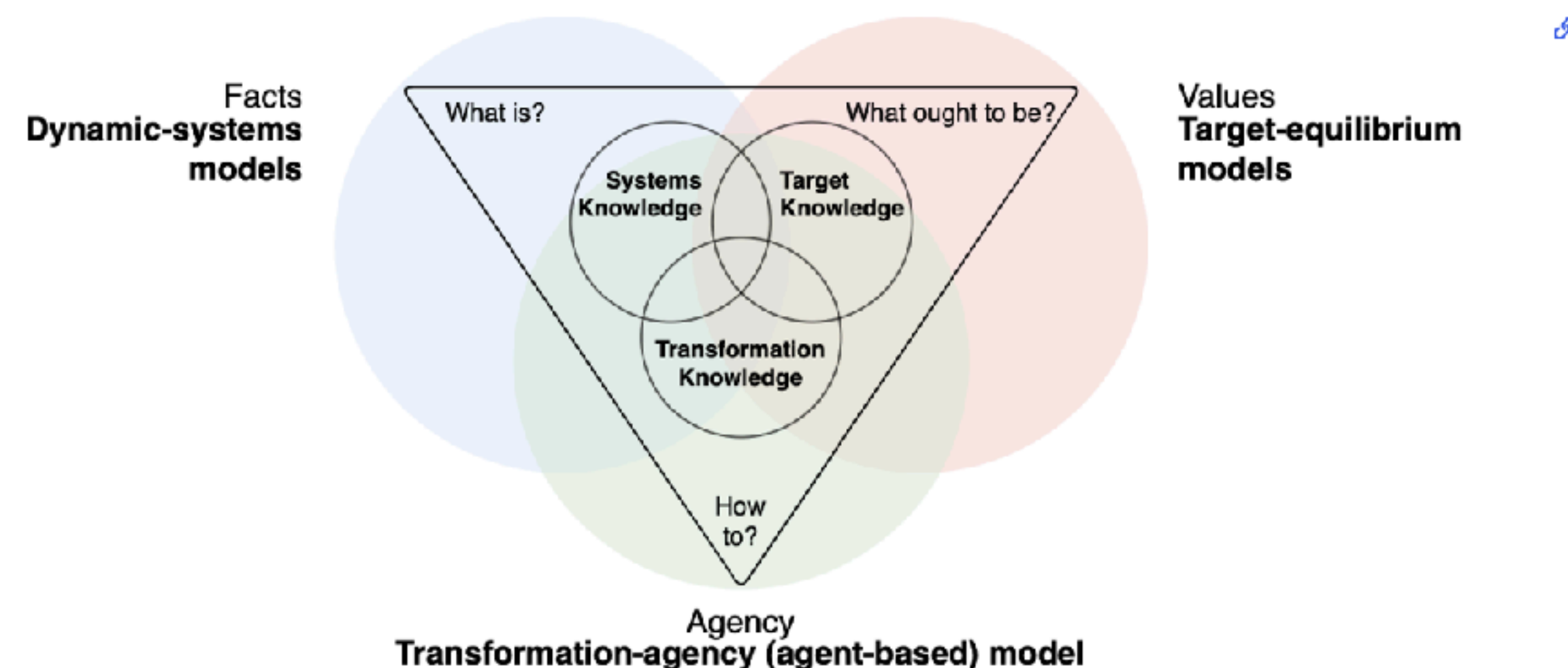


Figure 1.10: Three types of models based on three types of knowledge for transdisciplinary research

Table of contents

Learning goals

1.1 Human-environment interactions for sustainability transitions

The state of the planet
Why are we not acting?
A failure of systems thinking

1.2 Modeling

We cannot not model
All models are wrong
Some models are useful
Some models are good

1.3 Systems reductionism

Classical reductionism
The problem with experts
Complex systems
Systems reductionism

1.4 Sustainability Systems Modeling

Structural challenges
[Three types of models](#)
1.5 Learning goals revisited

Summary | CSS+MARL \longrightarrow SusEcon

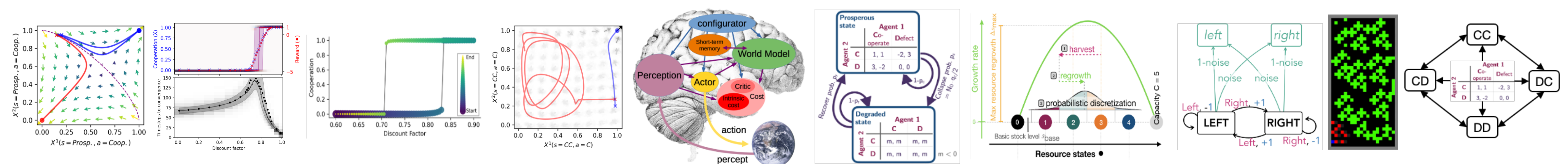
Why | Collective action challenges in human-machine ecologies

- Why are we not cooperating towards a sustainable future?
- Transparent Analysis 🔍 of the Non-linear dynamics 🚀 of the Collective behavior 👥 emerging from Individual intelligence 🧠 in some Environmental context 🌳

How | Building bridges

- Bringing the level of understanding from CSS to the richness of MARL by
- Collective Reinforcement Learning Dynamics: mitigating noise in low-dimensional environments

What | Emergent phenomena from cognition in contexts



Thank you

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barfusslab.github.io

