

Stochastic optimal control of open quantum systems using path integral methods

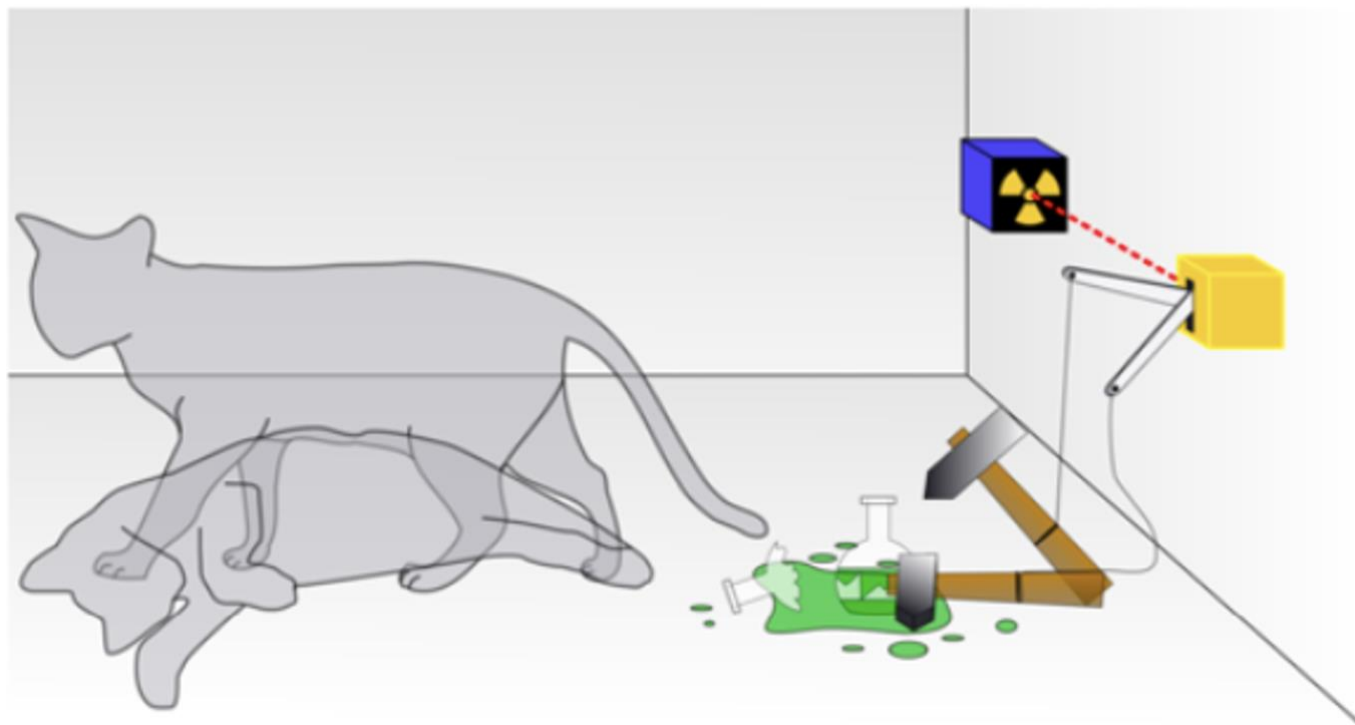
Bert Kappen

Faculty of Science

Radboud University Nijmegen

The Netherlands

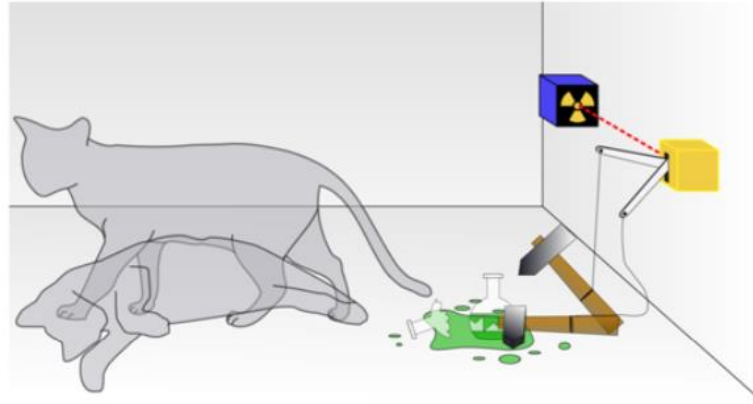
The quantum picture



A quantum state $\psi(s)$ represents possible outcomes s simultaneously.

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Define a procedure to map a probability distribution to a quantum state:

$$q(s) \quad \leftrightarrow \quad \psi(s)$$

Estimate expected values by performing repeated measurement on the same quantum state.

Quantum advantage

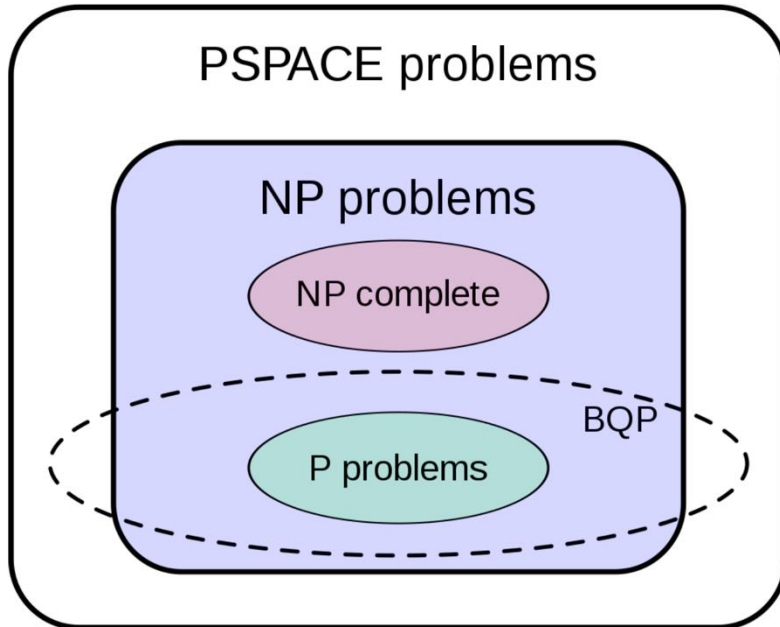


Image credits: wikipedia.org

P: solvable in poly time

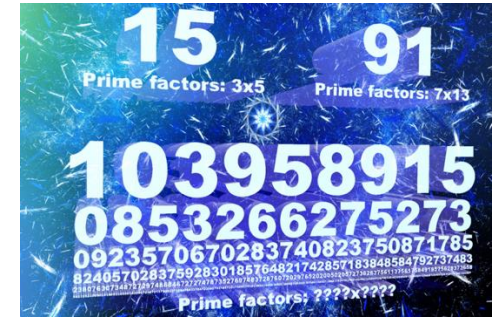
NP: solution verifiable in poly time

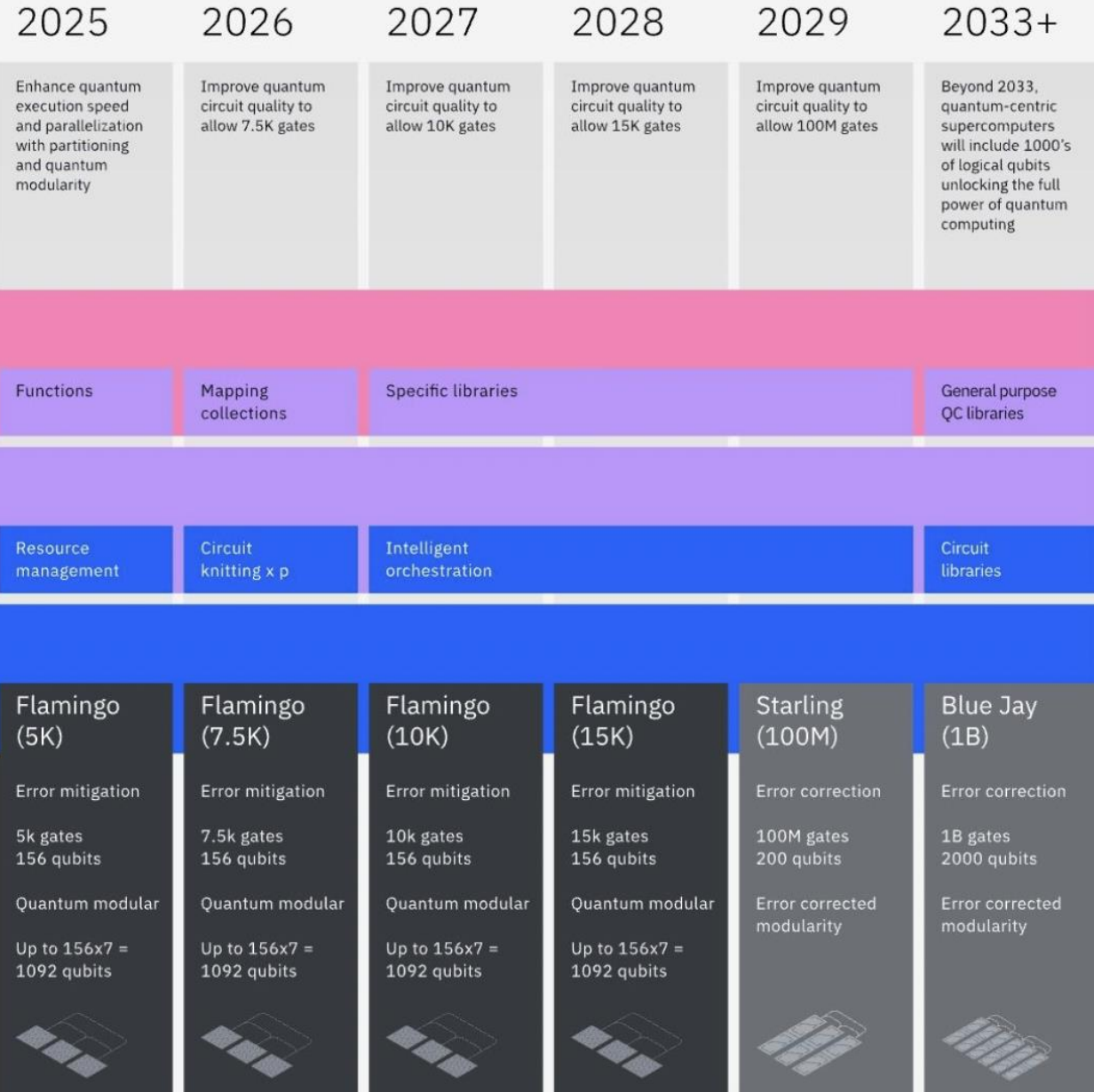
Pspace: solvable with poly memory

BQP: Bounded Quantum Polynomial

It is conjectured that BQP solves hard problems outside of P, specifically, problems in NP. Examples are

- Integer factorization (Shor's algorithm) $\mathcal{O}\left(e^{N^{\frac{1}{3}}}\right) \rightarrow \mathcal{O}(N^2)$
- Solving sparse linear system (HHL) $\mathcal{O}(N) \rightarrow \mathcal{O}(\log N)$





Quantum Computing in the NISQ era and beyond

John Preskill

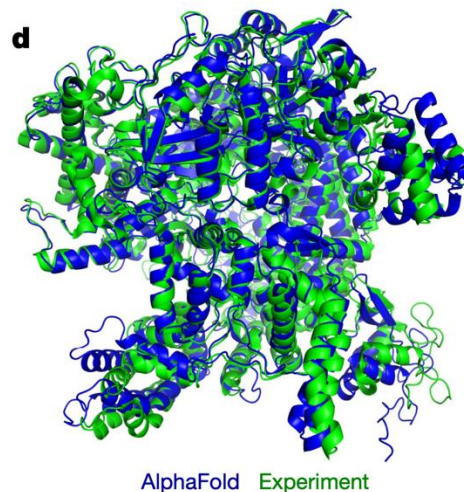
Institute for Quantum Information and Matter and Walter Burke Institute for Theoretical Physics,
California Institute of Technology, Pasadena CA 91125, USA

30 July 2018

Noisy Intermediate-Scale Quantum (NISQ) technology will be available in the near future. Quantum computers with 50-100 qubits may be able to perform tasks which surpass the capabilities of today's classical digital computers, but noise in quantum gates will limit the size of quantum circuits that can be executed reliably. NISQ devices will be useful tools for exploring many-body quantum physics, and may have other useful applications, but the 100-qubit quantum computer will not change the world right away — we should regard it as a significant step toward the more powerful quantum technologies of the future. Quantum technologists should continue to strive for more accurate quantum gates and, eventually, fully fault-tolerant quantum computing.

Quantum state preparation

- Prepare a quantum state that
 - Represents the ground state of a complex molecule (drug design, material design)
 - Solves a complex optimization problem (traveling salesman problem)
 - Sample from a complex distribution (statistical problems)



Quantum variational algorithms

Most famous example is the variational quantum eigensolver VQE to find the ground state of a Hamiltonian

$$\min_{\theta} \frac{\langle \psi | H | \psi \rangle}{\langle \psi | \psi \rangle} \quad |\psi\rangle = U(\theta) |0\rangle$$

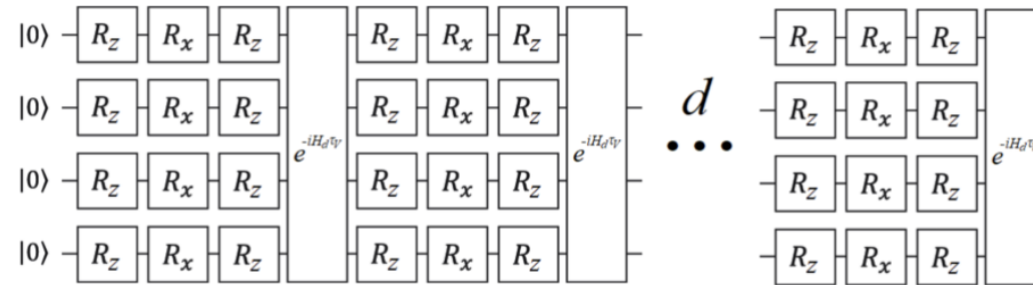
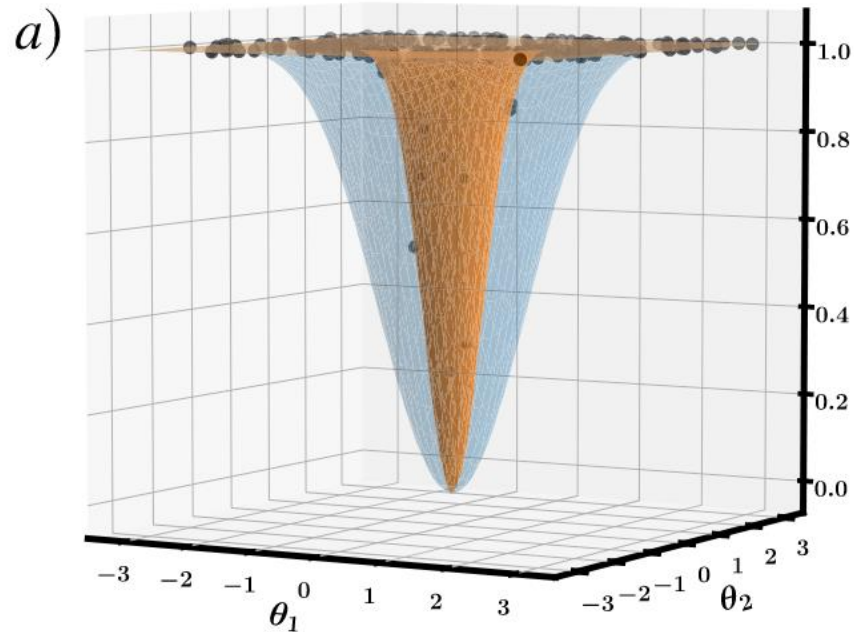


Figure 1a: Gate-based quantum circuit

θ is found by minimizing $R(\theta) = \frac{\langle \psi | H | \psi \rangle}{\langle \psi | \psi \rangle}$ with $|\psi\rangle = U(\theta) |0\rangle$ with respect to θ using gradient descend.

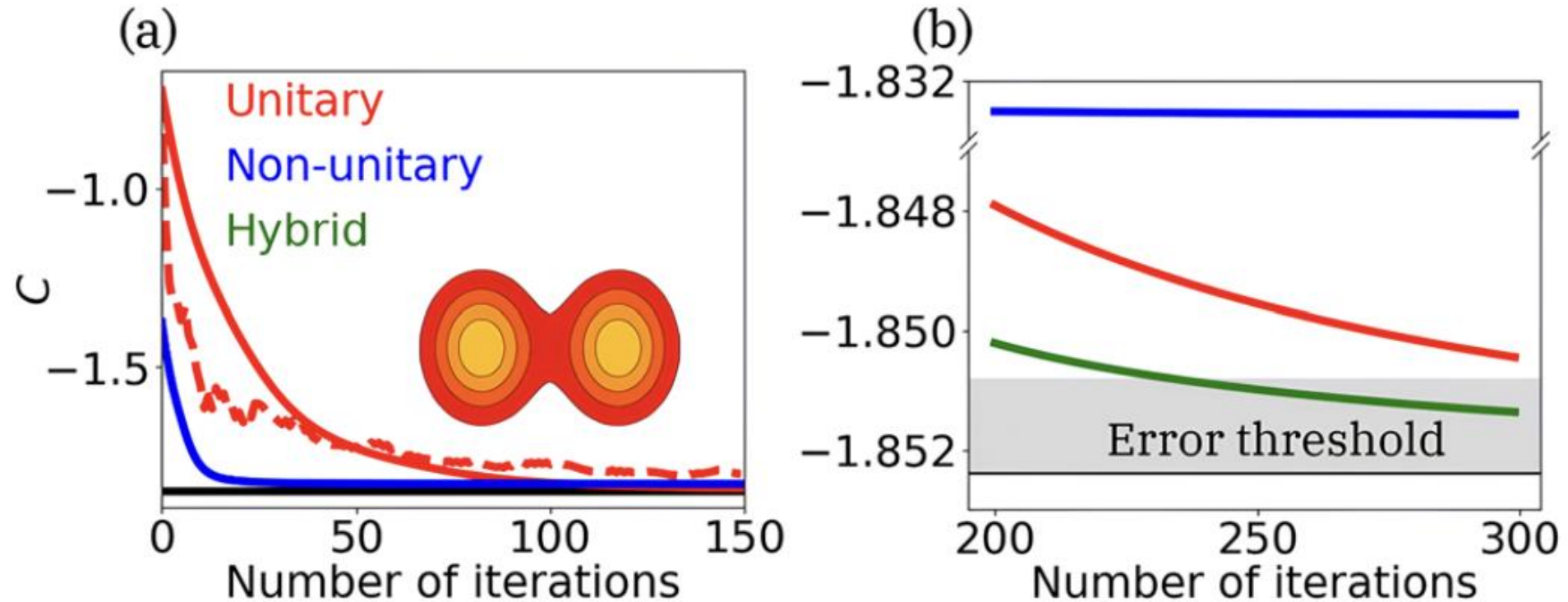
Barren plateaus

θ is found by minimizing $R(\theta) = \frac{\langle \psi | H | \psi \rangle}{\langle \psi | \psi \rangle}$ with $|\psi\rangle = U(\theta) |0\rangle$ with respect to θ using gradient descend.



Gradients vanish almost everywhere
for large problems

Noise improves convergence



Engineered dissipation to mitigate barren plateaus
Sannia et al. 2024

Optimal control for analog quantum circuits

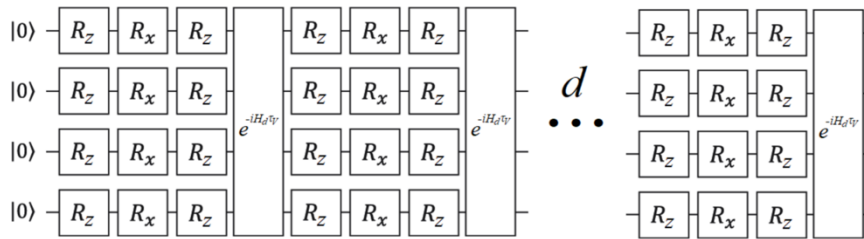


Figure 1a: Gate-based quantum circuit

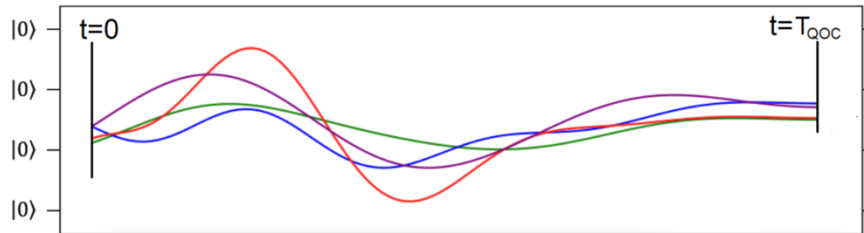


Figure 1b: Pulse-based quantum circuit

$$|\psi_0\rangle \rightarrow \frac{d}{dt} |\psi\rangle = -iH(u) |\psi\rangle \rightarrow |\psi_f\rangle$$

with $H(u) = H_0 + \sum_k u_k H_k$. Find optimal u_k .

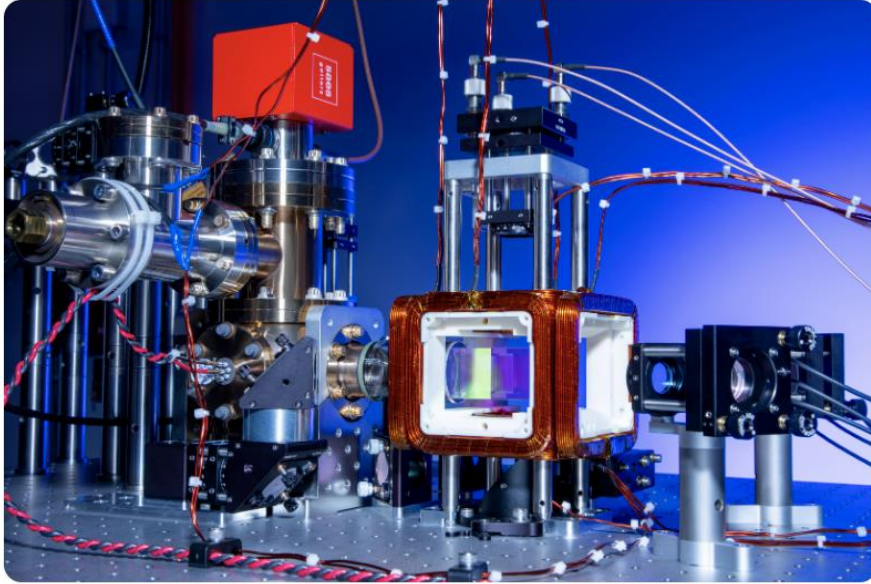
Analog controlled superconducting qubits have significantly shorter circuit times:

H₂, HeH⁺, 2 qubits: 9 ns versus 500-800 ns

LiH, 4 qubits: 40 ns versus 3.500-82.000 ns

T₁, T₂ times of IBMQ are order 70.000 ns on average

(Meitei et al. 2021)



Quantum computing with neutral atoms

QuEra's quantum computing technology uses lasers to arrange and excite individual neutral atoms into highly energetic states. These excited-atom qubits naturally interact at a distance, enabling entanglement and a multi-qubit connectivity that can be turned on and off at will. As atomic positions can be rearranged from one calculation to the next, these processors present extremely flexible and programmable layouts for their users. The ease of assembly and control, and the strong quantum coherence properties of neutral atoms, uniquely positions the technology to access new frontiers in simulating large quantum systems, exploring quantum optimization, and sampling.

QuEra's Aquila processor

Aquila is QuEra's first generation of quantum processing units (QPU) available on Amazon Braket. It operates up to 256 qubits in analog mode. The qubits have long lifetimes, supporting tens of qubit flips before decoherence sets in.

Approach

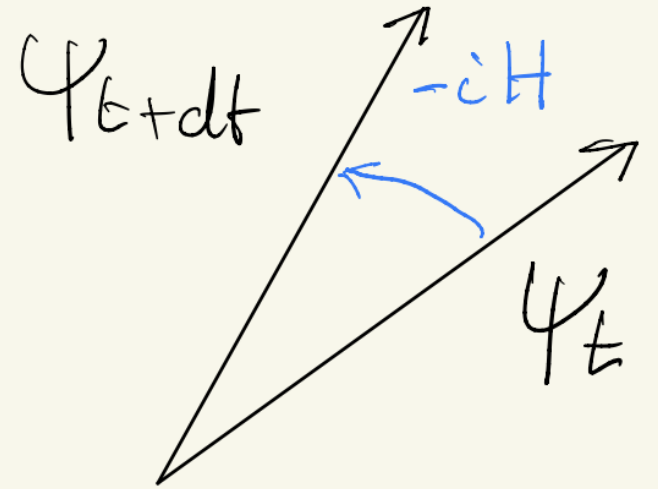
- Stochastic optimal control of analog open quantum systems
 - Analog yields shorter circuits
 - Stochastic yields better optimization
- Unravelings aka quantum trajectories
- Quantum state preparation as a stochastic optimal control problem
 - path integral control formulation

Outline

- Open quantum systems
 - Unravelings
- Stochastic optimal control
 - Path integral control
- Stochastic optimal control of open quantum systems
 - Examples of quantum state preparation

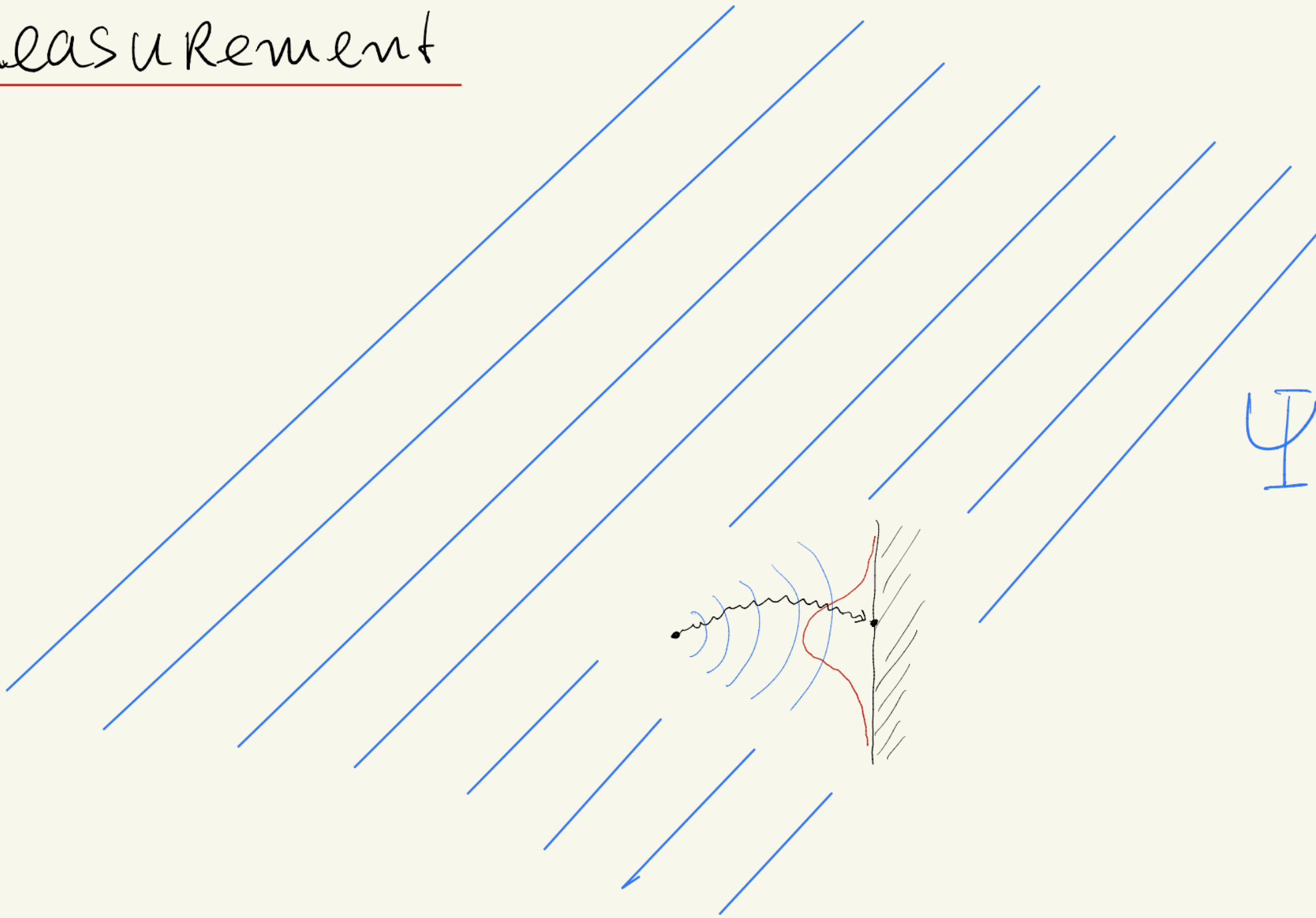
Unitary evolution is rotation in Hilbert Space

$$\frac{\partial \psi}{\partial t} = -i H \psi$$



Linear and deterministic

2. Measurement



Ψ universe

Density Matrix

$$\frac{d}{dt} |\psi\rangle = -i H |\psi\rangle$$

$$\rho = |\psi\rangle \langle \psi|$$

$$\frac{d}{dt} \rho = -i [H, \rho]$$

ρ is called a pure state

Mixed State



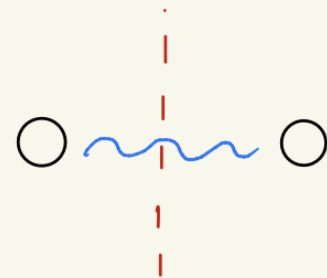
ω_1, b_1

ω_2, b_2

$$|\psi\rangle = |\omega_1; \omega_2\rangle + |b_1; b_2\rangle$$

$$\rho = |\psi\rangle\langle\psi|$$

Total system is in
a pure state ρ

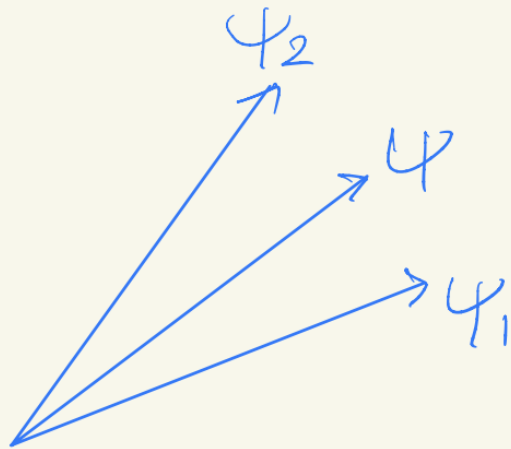


$$\begin{aligned}\rho_1 &= \text{"Average"}(\rho) \\ &= \frac{1}{2} |\omega_1\rangle\langle\omega_1| + \frac{1}{2} |b_1\rangle\langle b_1|\end{aligned}$$

Subsystem is in
a mixed state ρ_1

Pure v.s mixed state

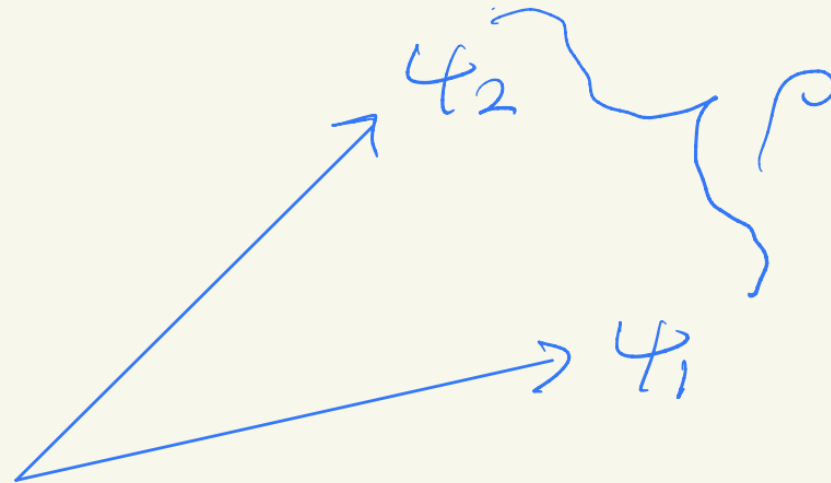
pure state



$$\psi = \frac{1}{\sqrt{2}} (\psi_1 + \psi_2)$$

$$\rho = \psi \psi^\dagger$$

Mixed state



$$\rho = \frac{1}{2} \psi_1 \psi_1^\dagger + \frac{1}{2} \psi_2 \psi_2^\dagger$$

The Lindblad equation

When coupling between system and environment is weak and environment is sufficiently large¹:

$$\dot{\rho} = \underbrace{-i[H, \rho]}_{\text{unitary part}} + \underbrace{D_{kl} \left(C_k \rho C_l^\dagger - \frac{1}{2} \{C_l^\dagger C_k, \rho\} \right)}_{\text{coupling to environment}}$$

Examples of Lindblad operators are measurement operators in which case C_k is Hermitian, or dissipation operators such as σ_\pm for a single qubit.

Unravelings

Define the stochastic Schrödinger equation

$$d\psi = -iH\psi dt - \frac{1}{2}D_{kl}\left(C_l^\dagger C_k - 2c_k C_l + c_k c_l\right)\psi dt + (\textcolor{red}{C}_k - c_k)\textcolor{red}{\psi}d\xi_k$$

$d\xi_k$ is a real-valued Wiener process with $\langle d\xi_k \rangle = 0$ and $\langle d\xi_k d\xi_l \rangle = D_{kl}dt$.

$c_k = \psi^\dagger C_k^{(h)} \psi$ real-valued make SSE non-linear and $d\|\psi\|^2 = 0$.

This defines an unraveling of the Lindblad equation, meaning that the expectation $\rho = \langle \psi \psi^\dagger \rangle$ satisfies the Lindblad equation.

$$\dot{\rho} = -i[H, \rho] + D_{kl}\left(C_k \rho C_l^\dagger - \frac{1}{2}\{C_l^\dagger C_k, \rho\}\right)$$

Measuring a single qubit

Consider a single qubit with $H = 0$ and $C = \hat{\sigma}_z$ and $D = 1$.

The Lindblad equation is

$$\dot{\rho} = \hat{\sigma}_z \rho \hat{\sigma}_z - \rho$$

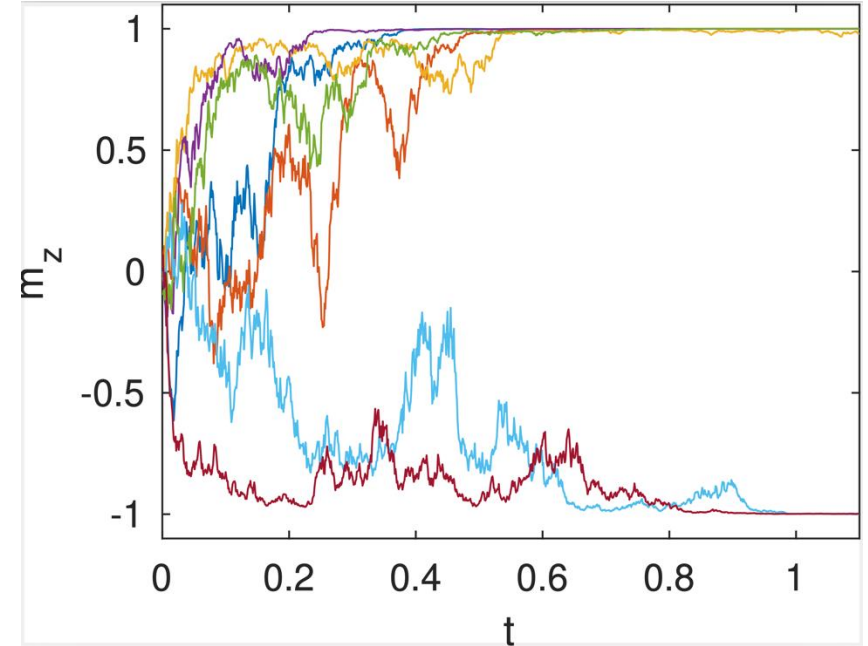
The SSE is

$$\begin{aligned} d\psi &= -\frac{1}{2}(\hat{\sigma}_z - m_z)^2 \psi dt + (\hat{\sigma}_z - m_z) \psi d\xi \\ dm_z &= 2(1 - m_z^2) d\xi \end{aligned}$$

with $m_z = \psi^\dagger \hat{\sigma}_z \psi$ and $\langle d\xi^2 \rangle = dt$

Note, that $\hat{\sigma}_z \rightarrow i\hat{\sigma}_z$ leaves Lindblad equation invariant but makes the unraveling linear

$$d\psi = -\frac{1}{2}\psi dt + i\hat{\sigma}_z \psi d\xi \quad dm_z = 0$$



Optimal control theory



Given a current state and a future desired state, what is the best/cheapest/fastest way to get there.

Stochastic optimal control

Consider a stochastic dynamical system

$$dx = f(t, x, u)dt + g(t, x, u)d\xi$$

$d\xi$ Gaussian noise $\langle d\xi d\xi' \rangle = \nu dt$.

The cost is an expectation:

$$C_u(t, x) = \left\langle \phi(x(T)) + \int_t^T d\tau V(\tau, x(\tau), u(\tau, x)) \right\rangle_u$$

over all stochastic trajectories with control function u starting at t, x .

The optimal cost to go: $J(t, x) = \min_u C_u(t, x)$ satisfies the Bellman equation

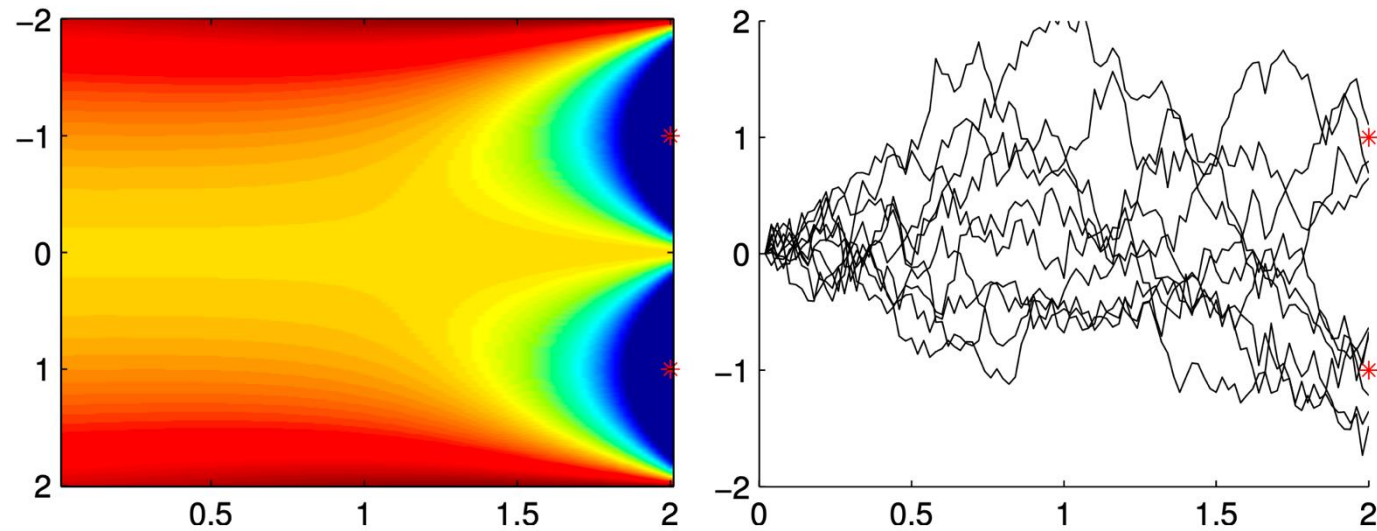
$$-\partial_t J = \min_u \left(V + f \nabla J + \frac{1}{2} \nu \text{Tr}(g \nu g' \nabla^2) J \right)$$

is a PDE with boundary condition $J(\cdot, T) = \phi(\cdot)$.

Delayed choice

Compute the optimal control in x, t when

$$dx = udt + d\xi \quad C_u(t, x) = \left\langle \phi(x_T) + \int_t^T ds \frac{1}{2} u^2 \right\rangle_u$$



Decision is made at $t = T - \frac{1}{\nu}$.

Path integral (PI) control methods

$$\begin{aligned} dx &= f(t, x)dt + g(t, x)(u(t, x)dt + d\xi) & \langle d\xi \rangle &= vdt \\ C_u(t, x) &= \langle S_u(\tau) \rangle_u & S_u(\tau) &= \phi(x(T)) + \int_t^T ds V(s, x) + \frac{1}{2}u'Ru + u'Rd\xi \end{aligned}$$

with $\tau = x_{t:T}$ a trajectory starting at t, x .

When $R = \lambda v^{-1}$ the Bellman equation can be linearized by a log transform. The solution is given as a path integral

$$\begin{aligned} J(t, x) &= -\lambda \log \langle e^{-S_u(\tau)/\lambda} \rangle_u \\ u^*(t, x) &= u(t, x) + \lim_{dt \downarrow 0} \frac{1}{dt} \frac{\langle d\xi_t e^{-S_u(\tau)/\lambda} \rangle}{\langle e^{-S_u(\tau)/\lambda} \rangle} \end{aligned}$$

The optimal control solution can be obtained by sampling [Kappen, 2005, Thijssen and Kappen, 2015].

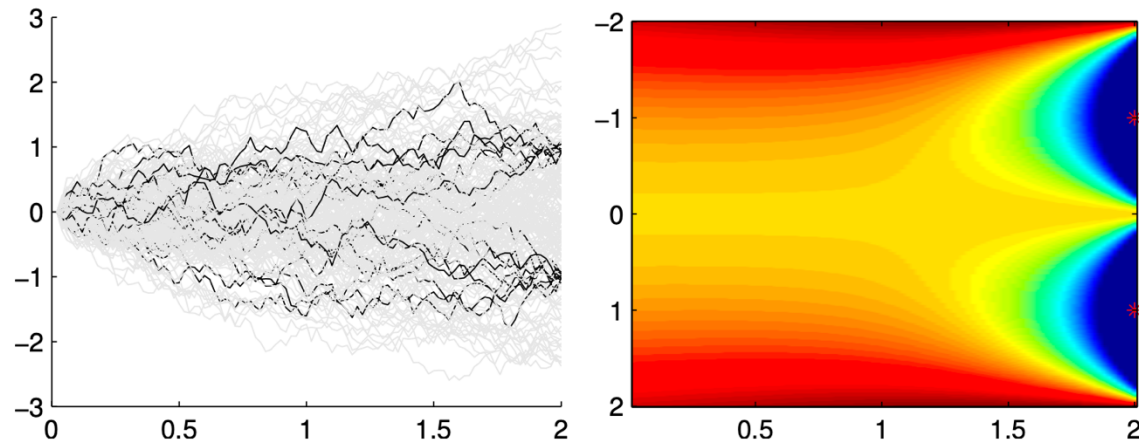
Delayed choice

Compute the optimal control in x, t when

$$dx = udt + d\xi \quad C_u(t, x) = \left\langle \phi(x_T) + \int_t^T ds \frac{1}{2} u^2 \right\rangle_u$$

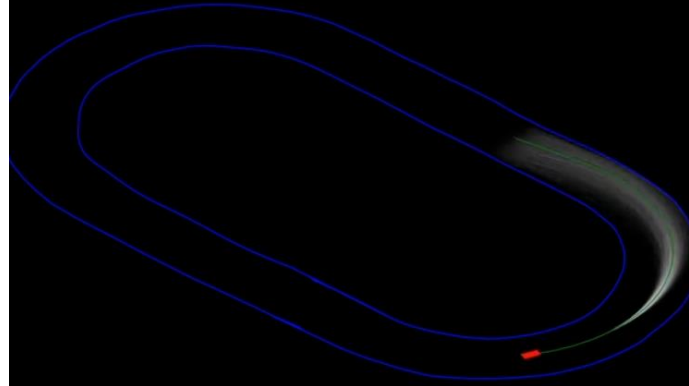
Solution

$$J(t, x) = -\nu \log \left\langle e^{-\phi(x_T)/\nu} \right\rangle_{u=0} \quad u(t, x) = -\nabla J(t, x)$$





2560, 2.5 second trajectories sampled
with cost-weighted average @ 60 Hz



Non-linear stochastic
optimal control solution
computed in real time
(Williams et al. 2016)

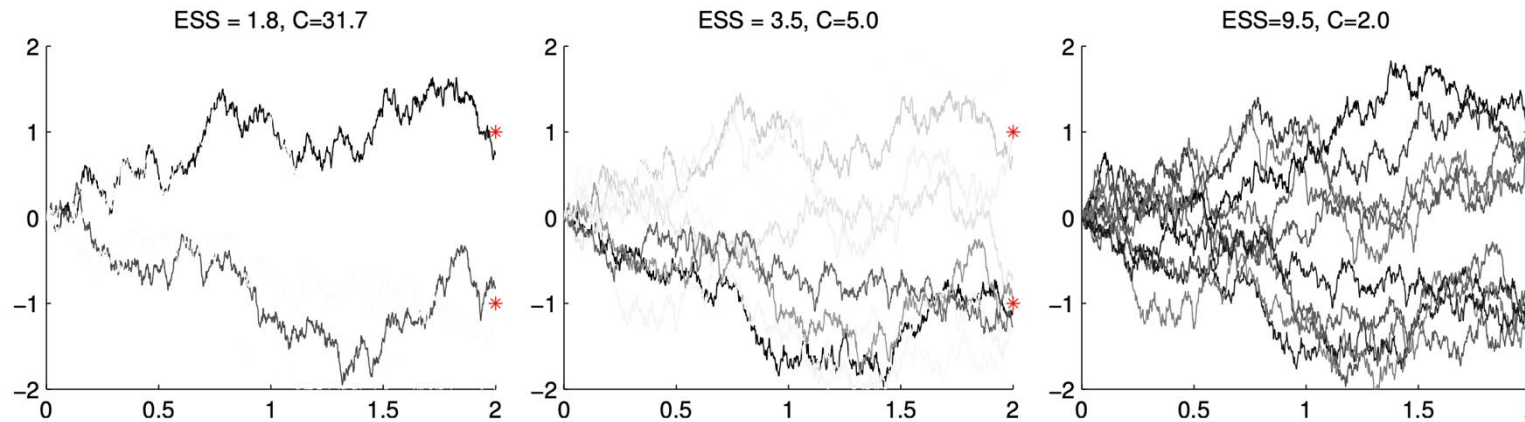


PI needs importance sampling

$$J(x, t) = -\lambda \log \left\langle e^{-S_u(\tau)/\lambda} \right\rangle_u \quad w_i = \frac{e^{-S_u(\tau_i)/\lambda}}{\sum_{j=1}^N e^{-S_u(\tau_j)/\lambda}} \quad N_{ESS} = \left(\sum_{i=1}^N w_i^2 \right)^{-1}$$

All u are unbiased estimators, but with some are more effective (smaller variance):

- Better u (smaller C) is better sampler (smaller variance, higher N_{ESS})
- Optimal u (minimal C) is optimal sampler (zero variance, $N_{ESS} = N$)



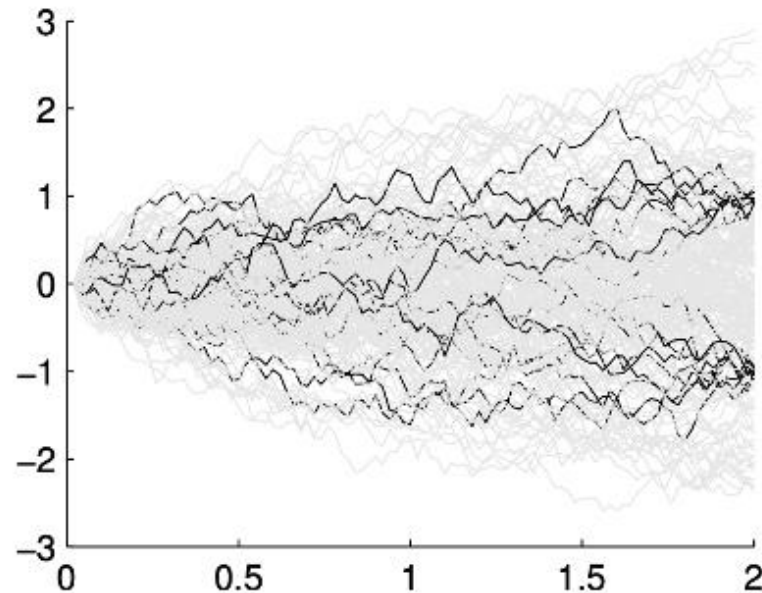
Adaptive importance sampling (PICE)

With parametrized control $u(x, t|\theta)$, adaptive importance sampling improves the control solution $\theta^p \rightarrow \theta^{p+1}$, starting with some initial control solution θ^0 .

$$\theta^{p+1} = \theta^p + \eta \frac{\left\langle e^{-S^u(t_0)/\lambda} \int_0^T \frac{\partial u(X_t^u, t|\theta^p)}{\partial \theta} d\xi_t \right\rangle_{\theta^p}}{\left\langle e^{-S^u(t_0)/\lambda} \right\rangle_{\theta^p}}$$

Stochastic integral

Importance weights



Control of the Lindblad equation

Define $H = H_0 + u_k H_k$. The (deterministic) control problem is

$$\begin{aligned}\dot{\rho}_t &= -i[H, \rho_t] + D_{kl} \left(C_k \rho_t C_l^\dagger - \frac{1}{2} \{C_l^\dagger C_k, \rho_t\} \right) \\ C(\rho_0, u) &= \text{Tr}(G \rho_T) + \int_0^T \frac{1}{2} u'_t R u_t\end{aligned}$$

with G some target Hamiltonian.

When the C_k can be transformed into anti-Hermitian operators $\tilde{C}_k = -iH_k$ and $\tilde{D} > 0$, the stochastic optimal control problem is of the path integral form:³

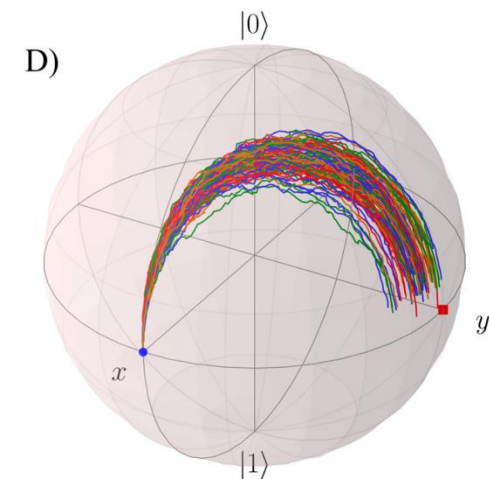
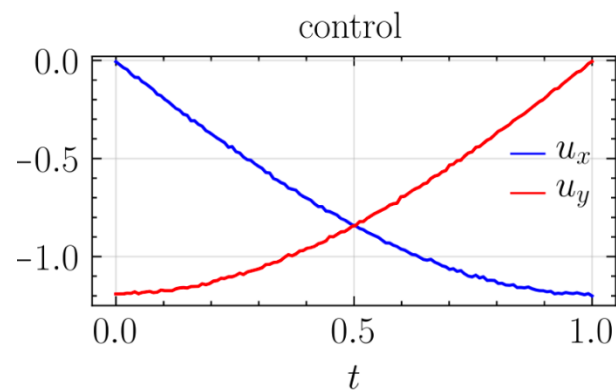
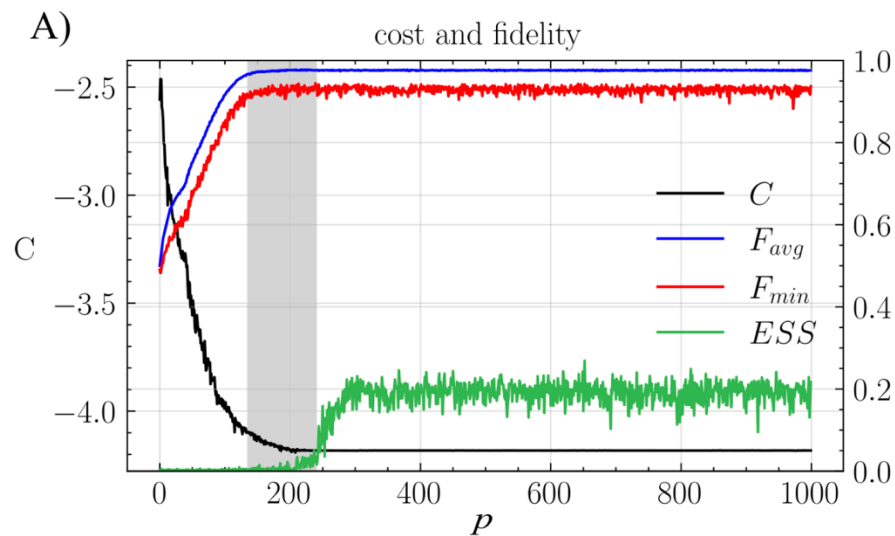
$$\begin{aligned}d\psi_t &= -iH_0\psi_t dt - \frac{1}{2}\tilde{D}_{kl}H_l H_k \psi_t dt - i(u_k dt + d\tilde{\xi}_k)H_k \psi_t \\ C(\psi_0, u) &= \left\langle \psi_T^\dagger G \psi_T + \frac{1}{2} \int_0^T u'_t R u_t dt \right\rangle_u\end{aligned}$$

³In the case of feedback control, the control problem depends on the unraveling.

Control of one qubit

Unitary control $H = u_x \hat{\sigma}_x + u_y \hat{\sigma}_y$ and dissipation $\hat{\sigma}_+$ and $\hat{\sigma}_-$ has Lindblad equation

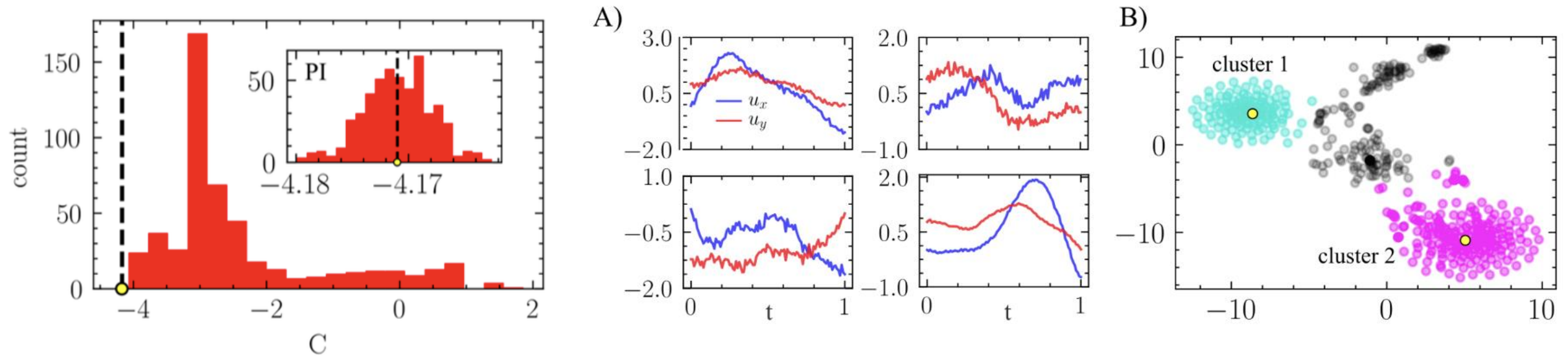
$$\dot{\rho} = \underbrace{-i[H, \rho]}_{\text{control}} + \underbrace{D(\hat{\sigma}_+ \rho \hat{\sigma}_- + \hat{\sigma}_- \rho \hat{\sigma}_+ - \rho)}_{\text{dissipation}}$$



K=128, n_traj= 400. mean asymptotic fidelity = 0.9759

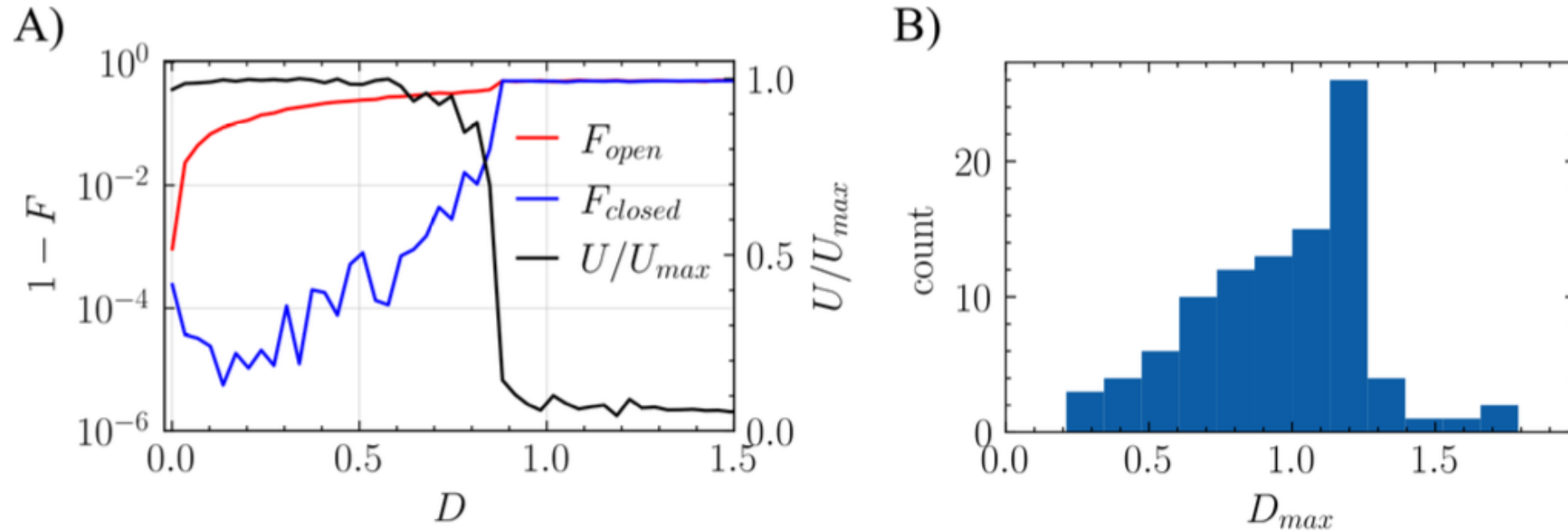
QDC versus Open GRAPE

(Open) GRAPE (Boutin 2017) solves the deterministic control problem using the Lindblad equation. It requires large number of pulses for accurate approximation of gradient



Histogram of 505 different initializations. Some Open GRAPE solutions. Clustering of solutions

The sweet spot: Stochastic optimal control solution as a proxy for deterministic optimal control solution



Left: $X \rightarrow Y$. Reaches $F > 0.98$ for $D < 0.8$.

Right: $X \rightarrow \text{Haar}$. Reaches $F > 0.98$ for all instances, often with large noise

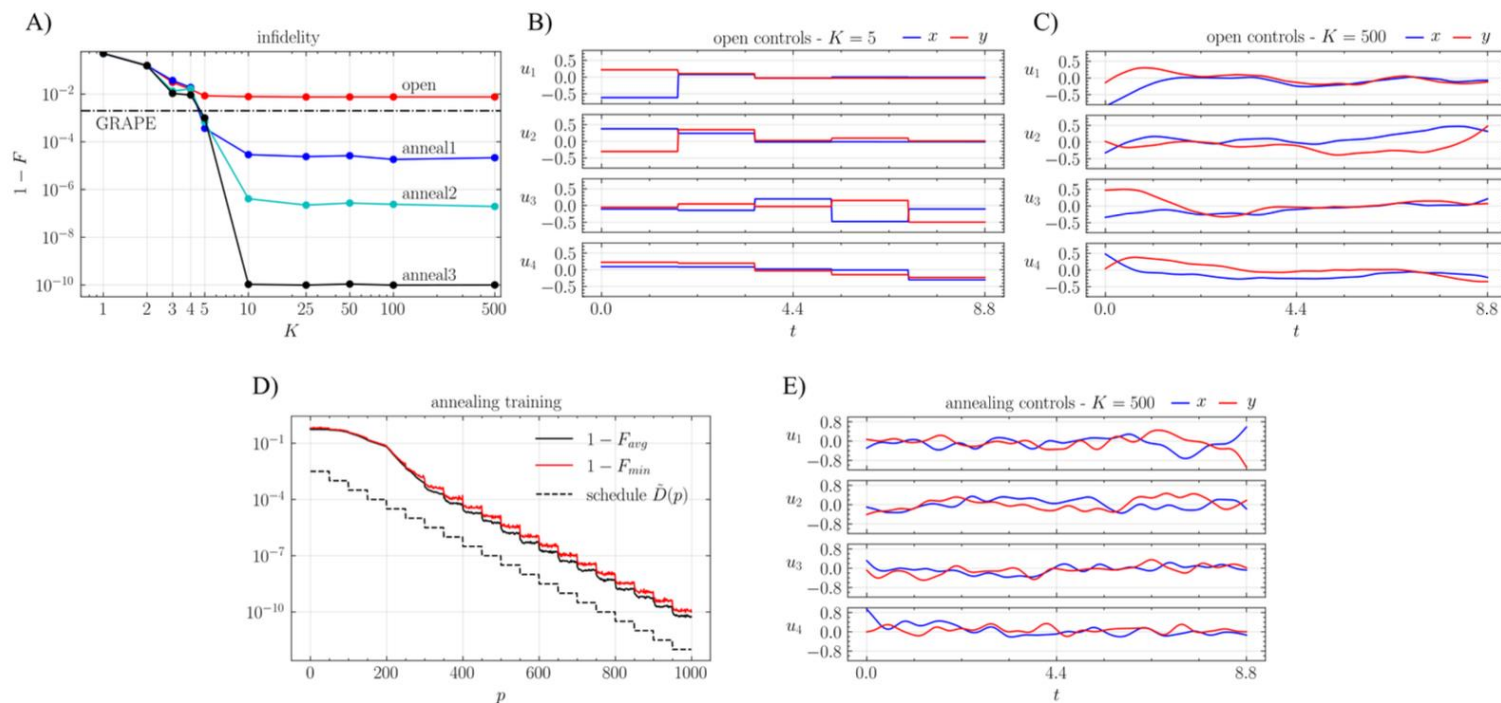
NMR physics preparation of n=4 GHZ state

Use nuclear spins of small molecules as coupled qubits.

Carbon-13-iodotrifluoroethylene

$$H_{\text{NMR}} = \sum_j (\pi \nu_j \hat{\sigma}_z^{(j)}) + \sum_{i < j} \left(\frac{\pi}{2} J_{ij} \hat{\sigma}_z^{(i)} \hat{\sigma}_z^{(j)} \right),$$

$$H_c(t) = \sum_j (\pi u_{xj}(t) \hat{\sigma}_x^{(j)} + \pi u_{yj}(t) \hat{\sigma}_y^{(j)}).$$

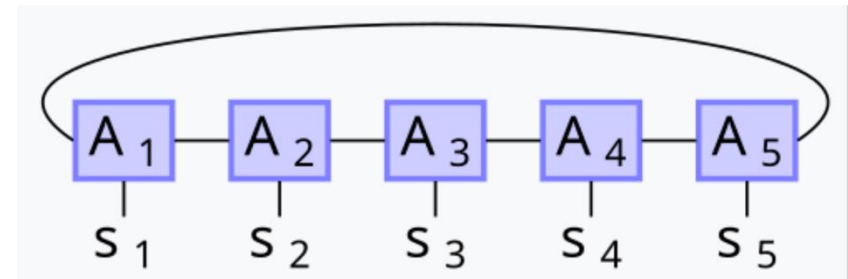
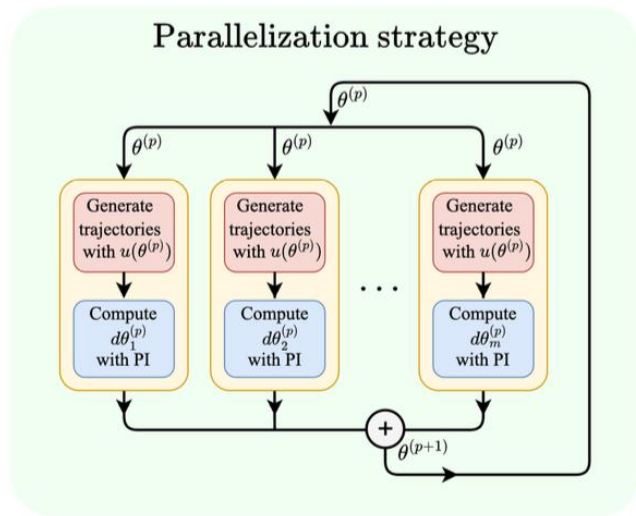


GRAPE needs large number of pulses for accuracy (1760) and Fidelity 0.998 (Chen et al. 2023).

QDC has no such requirement (32). Annealing yields infidelity 1e-10.

Scaling up: classical computing

$$u_k^{(p+1)} = u_k^{(p)} + \sum_{i=1}^N w_i \int_{\tau_k}^{\tau_{k+1}} d\xi_t^i$$



Tensor networks for efficient representation of large wave functions

Parallelization of importance sampling is very efficient

Scaling up: quantum computing

- Scalability requires that the parameter optimization is executed on a quantum device.
 - This holds for VQE for digital circuits
 - This does not hold for optimal control methods for analog quantum devices (Grap, Crab)
 - QDC can be optimized on quantum hardware

Scaling up: quantum computing

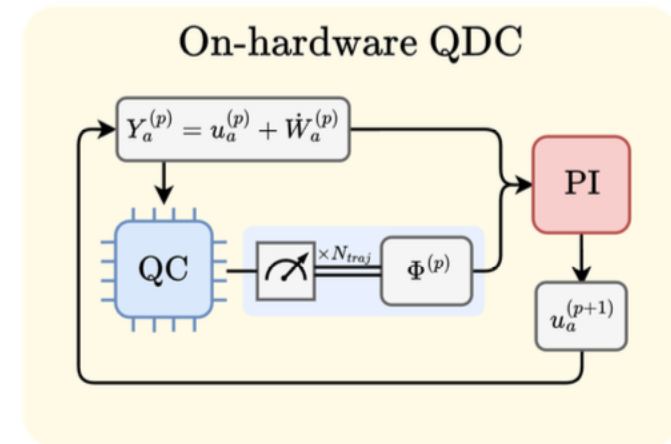
- QDC on quantum device:

- Weights depend on noise trajectory and end cost
- End cost obtainable from measurement
- The noise realization is unknown

$$u_k^{(p+1)} = u_k^{(p)} + \sum_{i=1}^N w_i \int_{\tau_k}^{\tau_{k+1}} d\xi_t^i$$

- Approach

- Assume noiseless device
- provide the noise externally
- Exploit sweet spot idea

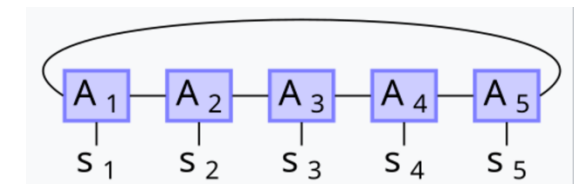
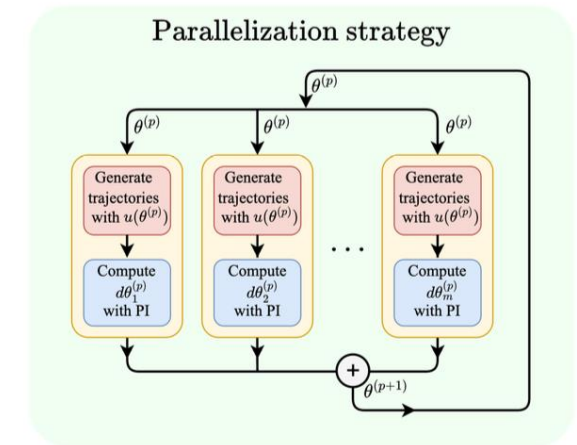
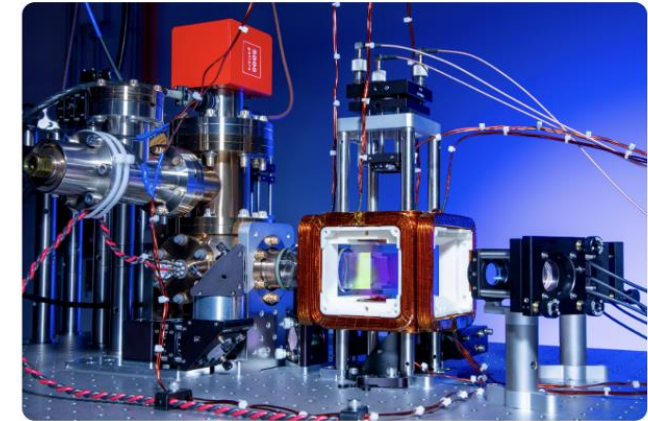


Summary

- Analog quantum computing is promising alternative for digital quantum circuits
 - Shorter circuit times
- Open quantum system approach is promising to mitigate barren plateaus
- New control framework for open analog quantum systems based on unravelings and path integral control.
 - Provides quadratic speed-up
 - Exploits quantum-noise sweet spot
 - Outperforms deterministic control methods
 - Scalable on quantum computers

Future work

- Application on analog quantum devices
- Scale up quantum simulation
 - Tensor networks
 - Parallel hardware, GPUs
- Benchmark studies comparing analog and digital circuits (quantum chemistry, QUBO)
- (Optimization of) quantum annealing



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Peyman Najafi



Aaron Villanueva



Eduardo Dominguez