## Computing real solutions to polynomial equations

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Key words: Polynomial functions, Julia implementation
Problem description:

We consider the problem of solving a system of multivariate equations

$$
\begin{equation*}
f_{1}\left(x_{1}, \ldots, x_{n}\right)=\cdots=f_{s}\left(x_{1}, \ldots, x_{n}\right)=0 \tag{1.1}
\end{equation*}
$$

where $f_{i} \in \mathbb{R}\left[x_{1}, \ldots, x_{n}\right]$ are polynomial functions in the unknowns $x_{1}, \ldots, x_{n}$. Geometrically, each of the polynomials $f_{i}$ defines a hypersurface $V_{i}$ in $\mathbb{R}^{n}$, and our solutions form the intersection $V_{1} \cap \cdots \cap V_{s}$ of all these hypersurfaces. In the real plane $\mathbb{R}^{2}$, we intersect curves.

Example $1.1(s=n=2)$. Let $f_{1}=x_{1}^{2}+x_{1} x_{2}+x_{2}^{2}-1$ and $f_{2}=\left(x_{1}-1\right)^{2}+x_{2}^{2}-1$. The solutions to $f_{1}=f_{2}=0$ are the intersection points of an ellipse and a circle in the real plane. Figure 1 shows that there are two solutions. A more complicated situation is illustrated in the right part of that figure, where the equations each have degree 20.

Many standard algorithms for solving (1.1) intrinsically work over the complex numbers. That is, they compute all points $\left(x_{1}, \ldots, x_{n}\right) \in \mathbb{C}^{n}$ satisfying (1.1), and then select the real solutions. This holds for homotopy continuation methods, as well as for normal form methods. See for instance [3] for an overview. One way to avoid computing all complex solutions is to add equations $f_{s+1}, \ldots, f_{t}$ which are only satisfied by the real solutions.

Example 1.2. The equations $f_{1}=f_{2}=0$ from Example 1.1 have 4 complex solutions, 2 of which are real. Adding the equation $f_{3}=1-(1+\alpha) x_{1}-\alpha x_{2}=0$, with $\alpha \approx 0.5652$, only the two real solutions are left. Geometrically, we add the dotted line to the picture.


Figure 1: Systems of bivariate equations represent intersecting plane curves.

Project goals: The goal of this project is to compute the equations $f_{s+1}, \ldots, f_{t}$ needed to eliminate all nonreal solutions of (1.1), using adapted versions of the moment method [2]. We will compare with the recent Julia implementation in [1]. We will use this in a numerical method for finding all real solutions of (1.1), and test our algorithms on real-life problems.

Prerequisits: This project is suitable for students in mathematics or related subjects, with a strong knowledge of basic linear algebra and an interest in algebra and computation.

Contact: For questions, please send an e-mail to Simon.Telen@cwi.nl.

## References

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