# Small closure models for large multiscale problems

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## About me

- ► Aerospace Engineering TU Delft: MSc.
- ▶ Arts et Métiers ParisTech & TU Delft: joint-PhD.
- Stanford University: postdoc.
- ► CWI: postdoc & tenure track.





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#### What is turbulent flow?

▶ Not laminar.



- ▶ Not laminar.
- ► Unsteady.

![](_page_6_Picture_1.jpeg)

- ▶ Not laminar.
- Unsteady.
- Mixing.

![](_page_7_Picture_1.jpeg)

- ▶ Not laminar.
- Unsteady.
- Mixing.
- Multiscale.

## Numerical simulation

Numerical simulation resolving all spatial & temporal scales:

![](_page_8_Picture_2.jpeg)

Credit: turbulence team: https://www.youtube.com/watch?v=OM0l2YPVMf8

#### Discretization

▶ Numerical simulation = discretization:  $\omega(x, y) \rightarrow \omega^h(x, y)$ 

![](_page_9_Figure_2.jpeg)

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▶ Numerical simulation = discretization:  $\omega(x, y) \rightarrow \omega^h(x, y)$ 

![](_page_10_Figure_2.jpeg)

Solve equations on each point of a fine mesh.

![](_page_11_Picture_0.jpeg)

Problem: multi-scale nature:

 $\rightarrow$  required mesh resolution (often) much too large.

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Engineering solution:

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 decompose solution  $\omega = \overline{\omega} + \omega'$ .

 $\rightarrow$  only solve for large scales  $\overline{\omega}.$ 

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► How to get 
$$\overline{\omega}$$
?  
→ Use filter  $\overline{\omega} = P\omega$ 

#### ► Governing equations:

$$\begin{aligned} \frac{\partial \omega}{\partial t} + J(\psi, \omega) &= \nu \nabla^2 \omega + \mu \left( F - \omega \right) \\ \nabla^2 \psi &= \omega. \end{aligned}$$

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$$\frac{\partial \bar{\omega}}{\partial t} + \overline{J\left(\bar{\psi},\bar{\omega}\right)} = \nu \nabla^2 \bar{\omega} + \mu \left(F - \bar{\omega}\right) - \overline{r},$$
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► Solving both equations side by side:

![](_page_17_Figure_2.jpeg)

## Closing governing equations

▶ Problem: SGS model is unknown / unclosed  $\overline{r} = \overline{r}(\omega, \psi)$ . →  $\overline{r}$  must be modelled

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![](_page_18_Figure_3.jpeg)

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![](_page_19_Figure_3.jpeg)

# Question

▶ What should we learn from data?

![](_page_20_Figure_2.jpeg)

1 There are *d* global QoI:

$$q_i(t)=\left(rac{1}{2\pi}
ight)^2\int_0^{2\pi}\int_0^{2\pi}f_i(ar{\omega},ar{\psi};x,y,t)\,\mathrm{d}x\mathrm{d}y,\quad i=1,\cdots,d.$$

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2 Replace  $\overline{r} = \overline{r(\psi, \omega)}$  with <u>reduced</u> SGS term <u>r</u>:

$$\underline{\underline{r}} := \sum_{i=1}^{d} \underline{\tau_i}(t) P_i(x, y, t) ,$$

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Justified if:

▶  $\underline{r}$  is 'just as good' as  $\overline{r}$  for  $q_i$ .

Justified

$$\underline{\underline{r}} := \sum_{i=1}^{d} \tau_i(t) P_i(x, y, t),$$
degrees of freedom
$$\mathcal{O}(10^6)$$

$$\stackrel{I}{\longrightarrow} \text{ is 'just as good' as } \overline{\underline{r}} \text{ for } q_i.$$

$$\mathcal{O}(10^4)$$

$$\stackrel{I}{\longrightarrow} \text{ Must tie } \tau_i \& P_i \text{ to } q_i \text{ physics.}$$

$$\mathcal{O}(1)$$

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▶ Derive *q<sub>i</sub>* ODEs:

$$\frac{\mathrm{d}\boldsymbol{q}_i}{\mathrm{d}\boldsymbol{t}} = \dots + \left(\frac{\partial f_i}{\partial \bar{\omega}}, \underline{\boldsymbol{r}}\right) = \dots + \sum_{j=1}^d \boldsymbol{\tau}_j \left(\frac{\partial f_i}{\partial \bar{\omega}}, \boldsymbol{P}_j\right)$$

• 
$$(A,B) := \left(\frac{1}{2\pi}\right)^2 \int_0^{2\pi} \int_0^{2\pi} AB \, \mathrm{d}x \mathrm{d}y.$$

<sup>&</sup>lt;sup>1</sup>Edeling, W., & Crommelin, D. (2020). Reducing data-driven dynamical subgrid scale models by physical constraints. Computers & Fluids, 201, 104470.

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$$(A,B) := \left(\frac{1}{2\pi}\right)^2 \int_0^{2\pi} \int_0^{2\pi} AB \, \mathrm{d}x \mathrm{d}y.$$

• Every  $q_i$  ODE has d SGS terms: remove  $\sum_{i=1}^{d}$ 

• Orthogonality condition  $\forall t$ :

$$\left(\frac{\partial f_i}{\partial \bar{\omega}}, P_j\right) = 0 \text{ if } i \neq j$$

• Separate expansion for  $P_j$  and small linear solve <sup>1</sup>.

<sup>&</sup>lt;sup>1</sup>Edeling, W., & Crommelin, D. (2020). Reducing data-driven dynamical subgrid scale models by physical constraints. Computers & Fluids, 201, 104470.

### Extract $\tau_i$ from data

**>** Due to orthogonality,  $q_i$  transport equation becomes:

$$\frac{\mathrm{d}\boldsymbol{q}_{i}}{\mathrm{d}\boldsymbol{t}} = \ldots + \left(\frac{\partial f_{i}}{\partial \bar{\omega}}, \underline{\boldsymbol{r}}\right) = \ldots + \boldsymbol{\tau}_{i} \left(\frac{\partial f_{i}}{\partial \bar{\omega}}, \boldsymbol{P}_{i}\right)$$

► Goal: error  $q_i^{ref}(t) - q_i(t) =: \Delta q_i$  is small  $\forall t$  in training.

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Goal: error q<sub>i</sub><sup>ref</sup>(t) − q<sub>i</sub>(t) =: Δq<sub>i</sub> is small ∀t in training.
 Assumption: τ<sub>i</sub> depends upon Δq<sub>i</sub>.

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- ► Goal: error  $q_i^{ref}(t) q_i(t) =: \Delta q_i$  is small  $\forall t$  in training.
- Assumption:  $\tau_i$  depends upon  $\Delta q_i$ .

Simply equate source term to  $\Delta q_i$ :

$$au_i\left(\frac{\partial f_i}{\partial \omega}, P_i\right) = \Delta q_i/T_i, \quad T_i = 1, \quad i = 1, \cdots, d$$

 Assumes τ<sub>i</sub> ~ Δq<sub>i</sub> + imposes linear relaxation towards reference.

 $\blacktriangleright \Delta q_i$  is the only data we need.

▶  $q_1$  = energy E,  $q_2$  = enstrophy Z.

![](_page_32_Figure_2.jpeg)

 $\blacktriangleright$  <u>r</u> is 'just as good' as  $\overline{r}$  for  $q_i$ .

 $\rightarrow$  Number of unknowns reduced from 64<sup>2</sup> to 2.

 $\rightarrow$  Training data size reduced by factor 64<sup>2</sup>/2.

• 
$$q_1$$
 = energy  $E$ ,  $q_2$  = enstrophy  $Z$ .

![](_page_33_Figure_2.jpeg)

# Question

▶ What should we learn from data?

![](_page_34_Figure_2.jpeg)

# Conclusion

 $\blacktriangleright \tau_i \text{ (or } \Delta q_i \text{)}$ 

![](_page_35_Figure_2.jpeg)

## Questions?

Edeling, W., & Crommelin, D. (2020). Reducing data-driven dynamical subgrid scale models by physical constraints. Computers & Fluids, 201, 104470.

# Offline training

▶ Now: train ML model on reduced training data.

• <u>Offline</u> training: train e.g. ANN on  $\Delta E$ ,  $\Delta Z$  database.

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## Offline training

- ▶ Now: train ML model on reduced training data.
- <u>Offline</u> training: train e.g. ANN on  $\Delta E$ ,  $\Delta Z$  database.

Now we have a coupled PDE - ML system:

$$\frac{\partial \bar{\omega}}{\partial t} + \overline{J\left(\bar{\psi},\bar{\omega}\right)} = \nu \nabla^2 \bar{\omega} + \mu \left(F - \bar{\omega}\right) - \tau_1(\widetilde{\Delta E})P_1 - \tau_2(\widetilde{\Delta Z})P_2,$$
$$\nabla^2 \bar{\psi} = \bar{\omega}.$$
$$[\widetilde{\Delta E}, \widetilde{\Delta Z}] = ANN(X_1, \cdots, X_7)$$

## Prediction with offline surrogate

Can become unstable:

![](_page_40_Figure_2.jpeg)

# Prediction with offline surrogate

#### Can become unstable:

![](_page_41_Figure_2.jpeg)

- Why?: ANN was not trained not to operate in a two-way coupled modelling environment.
- ▶ Other authors reported similar issues.

## Online training

#### ▶ <u>online</u> training while ANN is coupled to PDE.

 $<sup>^2</sup> Rasp, S. (2020).$  Coupled online learning as a way to tackle instabilities and biases in neural network parameterizations: general algorithms and Lorenz 96 case study (v1. 0). Geoscientific Model Development, 13(5), 2185-2196.

 $<sup>^3</sup> Sahoo, D. et al, (2017). Online deep learning: Learning deep neural networks on the fly. arXiv preprint arXiv:1711.03705.$ 

## Online training

- online training while ANN is coupled to PDE.
- ▶ 1 data point per time step.

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## Online training

- online training while ANN is coupled to PDE.
- ▶ 1 data point per time step.
- First step: just do back propagation online:

![](_page_44_Figure_4.jpeg)

#### More sophisticated methods, See Rasp or Sahoo <sup>2 3</sup>.

 $^2 Rasp, S.$  (2020). Coupled online learning as a way to tackle instabilities and biases in neural network parameterizations: general algorithms and Lorenz 96 case study (v1. 0). Geoscientific Model Development, 13(5), 2185-2196.

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•  $M\Delta t$  = time interval between back propagation steps.

- $M\Delta t$  = time interval between back propagation steps.
- M = 1, <u>continual</u> online learning:

![](_page_46_Figure_3.jpeg)

coupled LR - ML model conserves HR energy and enstrophy.

► *M* = 20:

![](_page_47_Figure_2.jpeg)

coupled LR - ML model conserves HR energy and enstrophy.

▶ Thus far, initial conditions were perfect:  $q^{ref} = q$ .

▶ Can it recover when  $q^{ref} \neq q$ ?

- Thus far, initial conditions were perfect:  $q^{ref} = q$ .
- Can it recover when  $q^{ref} \neq q$ ?
- ▶ No SGS term before 10 days:

![](_page_49_Figure_4.jpeg)

coupled LR - ML model can quickly recover HR Qol.

#### Next steps

One of the next steps:

▶ When do we turn online training on / off? Is a UQ question.

## Questions?

Edeling, W., & Crommelin, D. (2020). Reducing data-driven dynamical subgrid scale models by physical constraints. Computers & Fluids, 201, 104470.

# Online training: Rasp (2020)<sup>4</sup>

Fig from Rasp 2020: HR state is nudged towards LR state.

![](_page_52_Figure_2.jpeg)

- Keeps HR LR small, helps with online convergence.
- Allows LR to learn 'what HR would do under similar states'.

#### Applied to Lorenz96.

 $^{4}$  Rasp, S. (2020). Coupled online learning as a way to tackle instabilities and biases in neural network parameterizations: general algorithms and Lorenz 96 case study (v1. 0). Geoscientific Model Development, 13(5), 2185-2196.

# Online training: Rasp (2020)<sup>4</sup>

Fig from Rasp 2020: HR state is nudged towards LR state.

![](_page_53_Figure_2.jpeg)

However: nudging & ML correction is applied to <u>entire</u> state.
 <u>Reduced ML: ML correction</u> is only applied via τ.

 $^{4}$  Rasp, S. (2020). Coupled online learning as a way to tackle instabilities and biases in neural network parameterizations: general algorithms and Lorenz 96 case study (v1. 0). Geoscientific Model Development, 13(5), 2185-2196.

# Reduced online training

![](_page_54_Figure_1.jpeg)

- ▶ Modified online (reduced) learning:
  - $\rightarrow$  Extract  $\Delta q$  data.
  - $\rightarrow$  Only 1 LR step.

- ► Are the results spectrally accurate?
- Map 2D wave numbers  $\mathbf{k} = (k_1, k_2)$  to 1D k:

$$k-rac{1}{2}\leq \sqrt{k_1^2+k_2^2}< k+rac{1}{2}, \quad k=0,1,\cdots,\operatorname{ceil}\left(\sqrt{2}\mathcal{K}
ight)$$

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![](_page_56_Figure_4.jpeg)

▶ <u>No</u> accurate spectra, only explicitly track overall E and Z.

- ► However, scale-aware QoI are also possible
- $\blacktriangleright$  Focus on a specific wave-number range via (spectral) filter  $\mathcal{T}:$ 
  - $\rightarrow$  zeros out all wave numbers k < K.

$$au_i\left(rac{\partial f_i}{\partial \omega}, \mathsf{P}_i
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- Focus on a specific wave-number range via (spectral) filter  $\mathcal{T}$ :
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$$\tau_i\left(\frac{\partial f_i}{\partial \omega}, P_i\right) = \Delta q_i \to \tau_i\left(\mathcal{T}\frac{\partial f_i}{\partial \omega}, P_i\right) = \mathcal{T}(\Delta q_i)$$

![](_page_58_Figure_5.jpeg)

Focus on wave numbers  $k \in [21, 30]$ .