

How to minimize time-discretization error?

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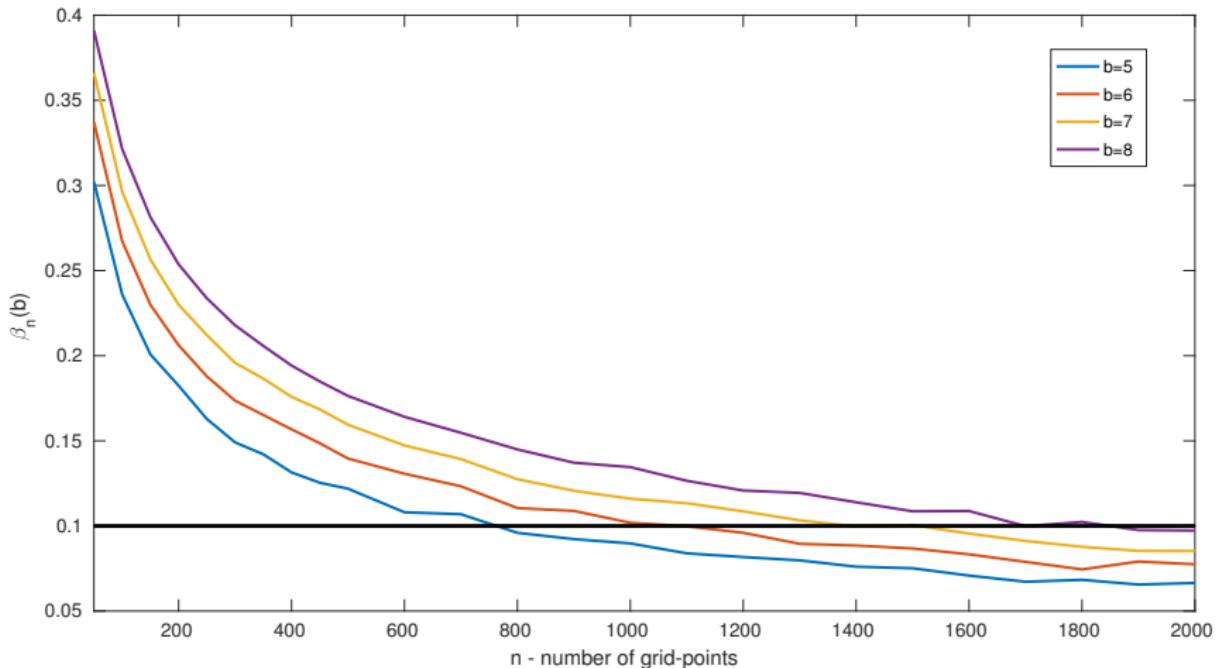
Joint work with:

Daan Crommelin^{*+}, Michel Mandjes⁺

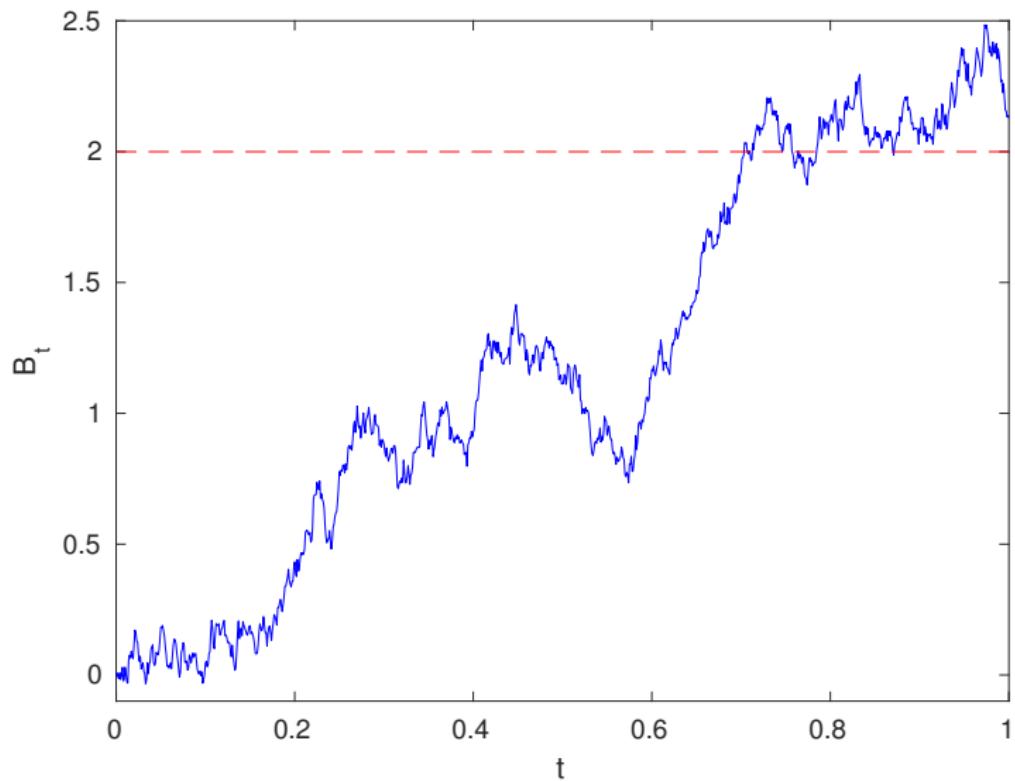
(*Centrum Wiskunde & Informatica, ⁺KdVI University of Amsterdam)

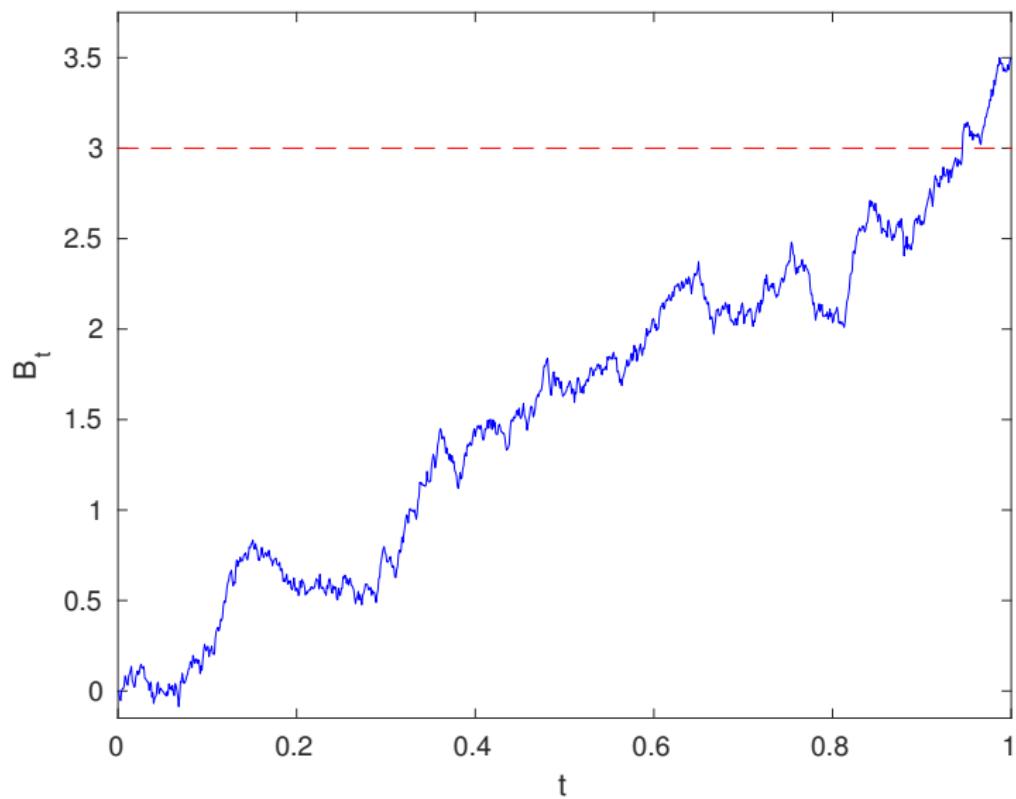
Introduction

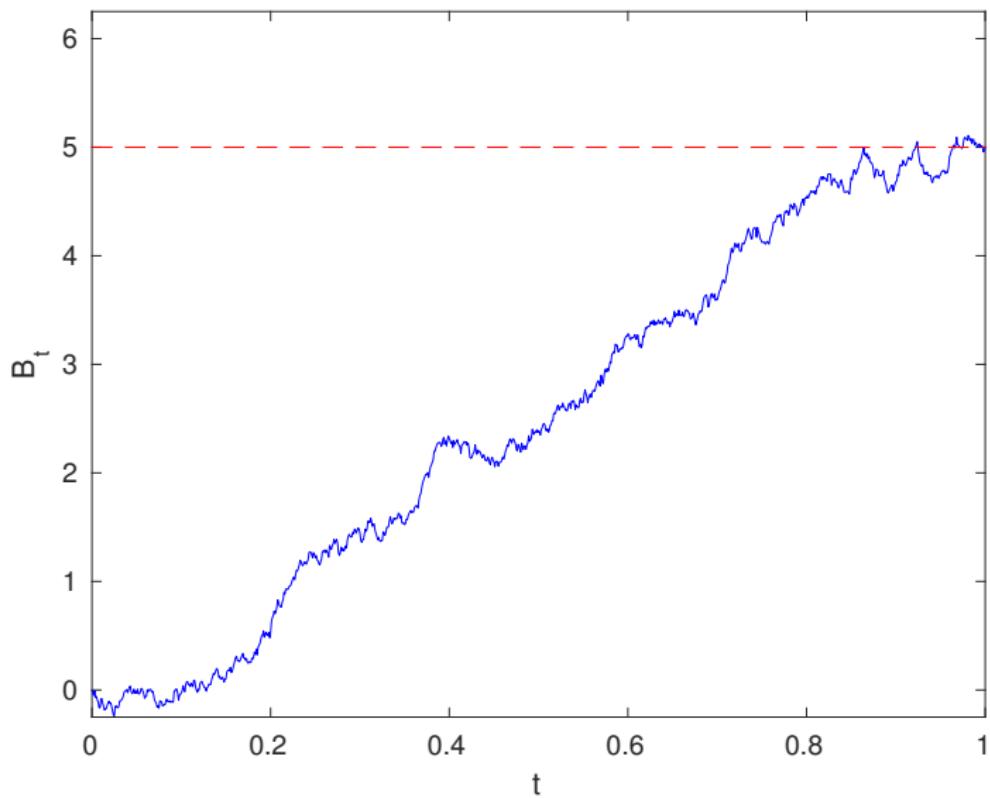
Equidistant grids

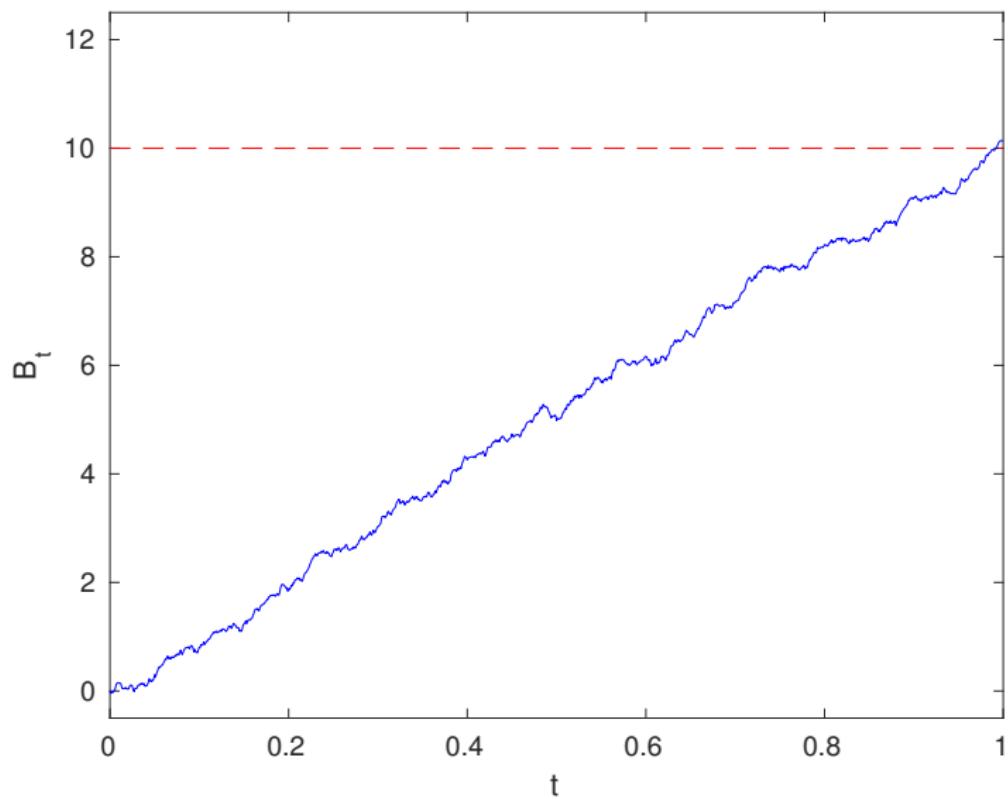


How does a path leading to the threshold look like?









Adaptive grids

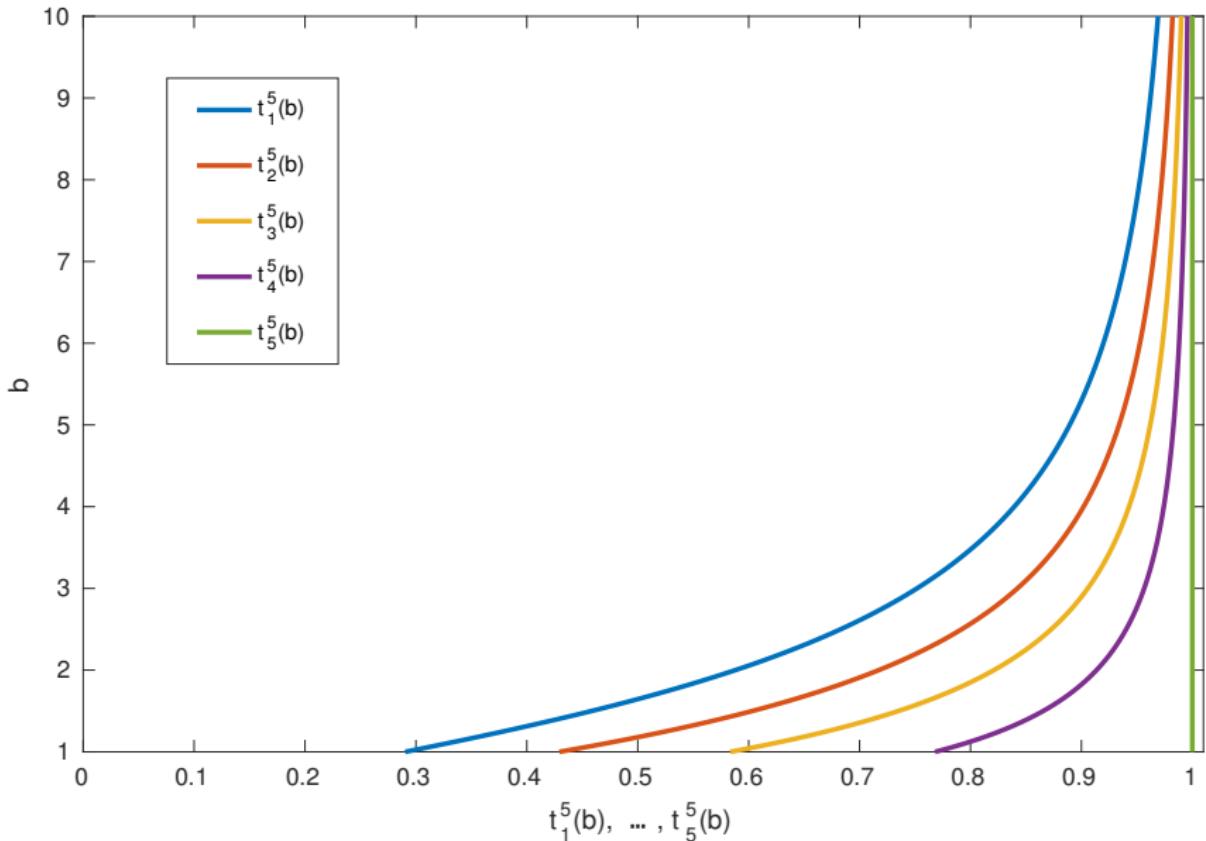
Adaptive grids

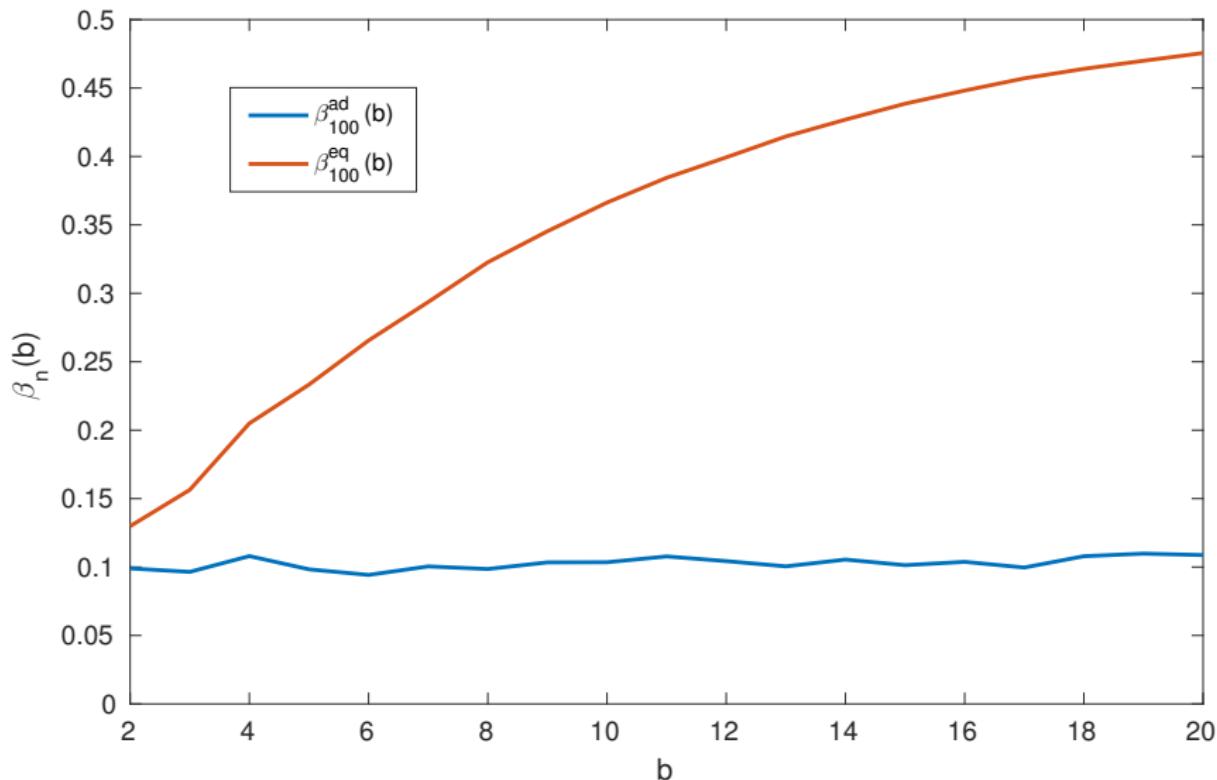
$$t_k^n(b) := \left(\frac{b}{\Phi^{-1} \left(\frac{k}{n} \Phi(-b) \right)} \right)^2 \approx 1 - \frac{2 \log(k/n)}{b^2}$$

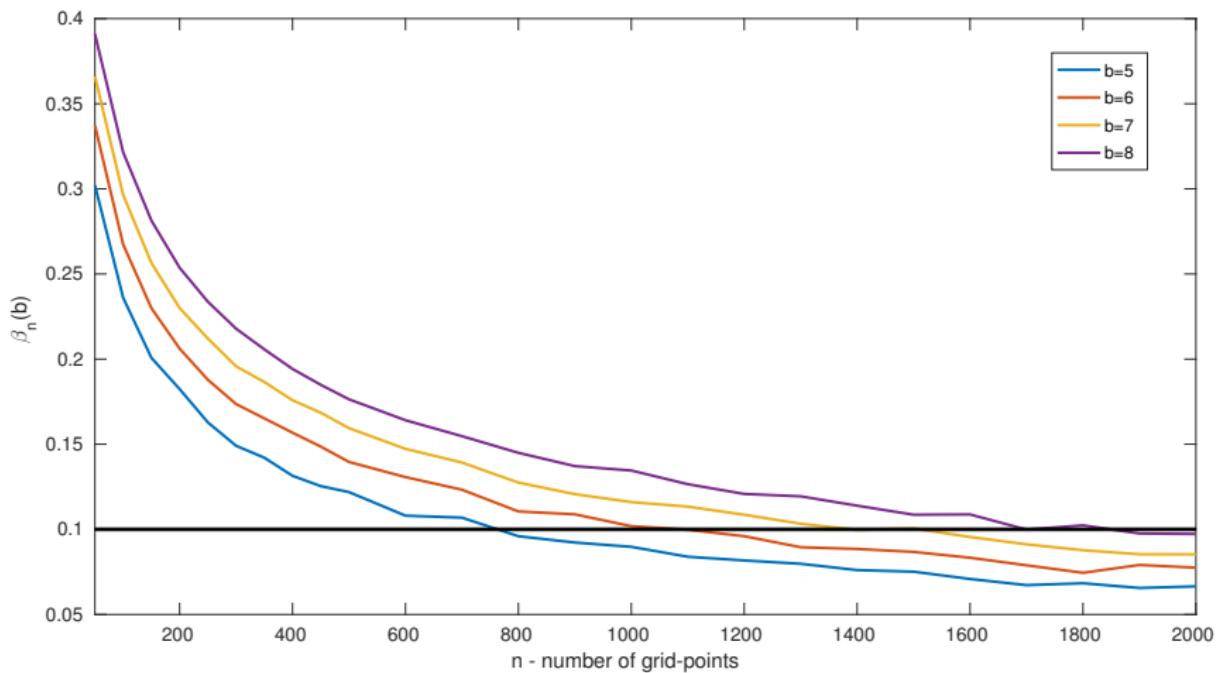
Adaptive grids

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Relative error is bounded independently of b !







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- Develop general methods for finding the threshold-crossing probability