

# Can linear programs solve NP-hard problems?

Ronald de Wolf



Centrum Wiskunde & Informatica



UNIVERSITEIT VAN AMSTERDAM

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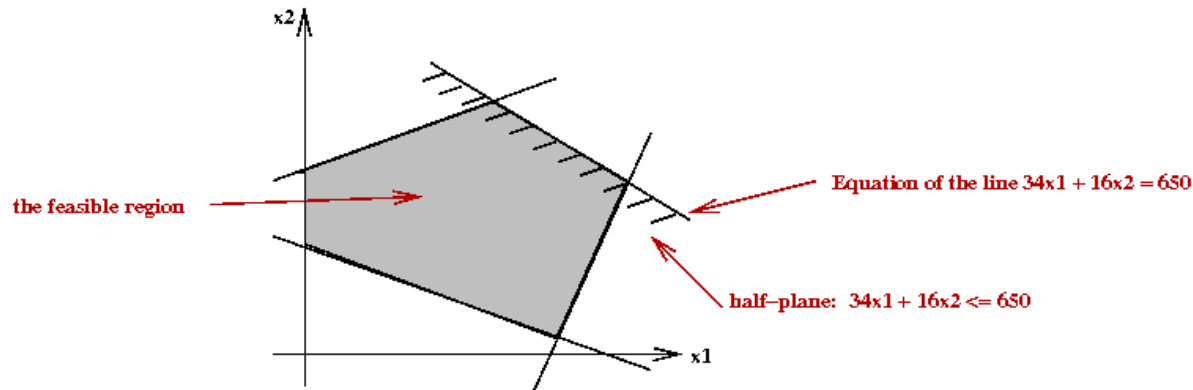
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- Feasible region is a **polytope**



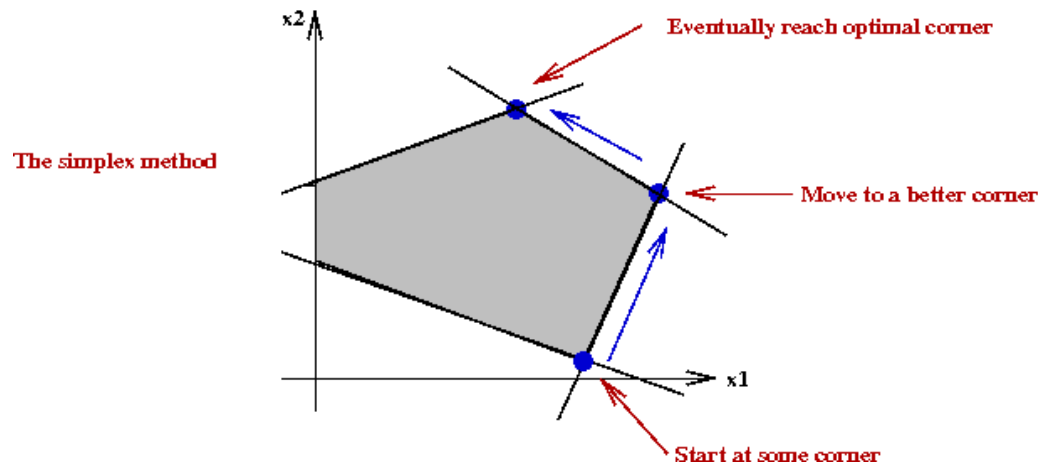
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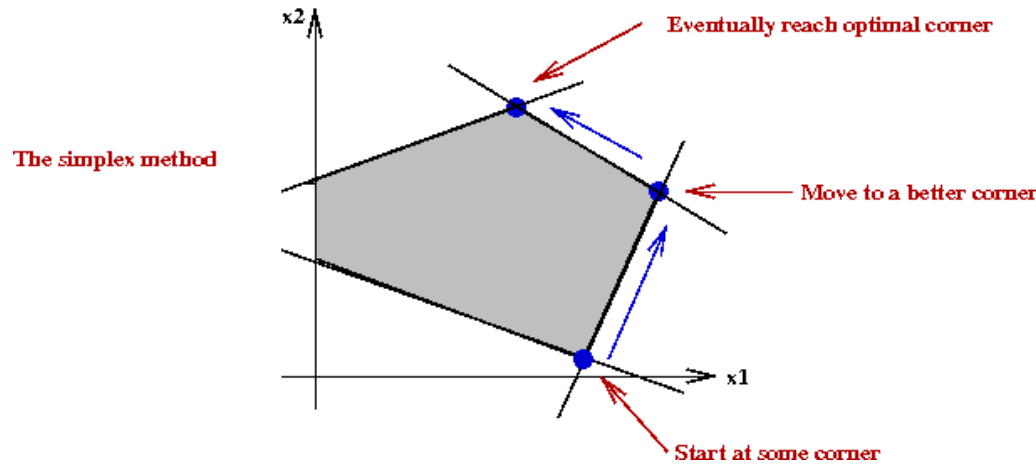
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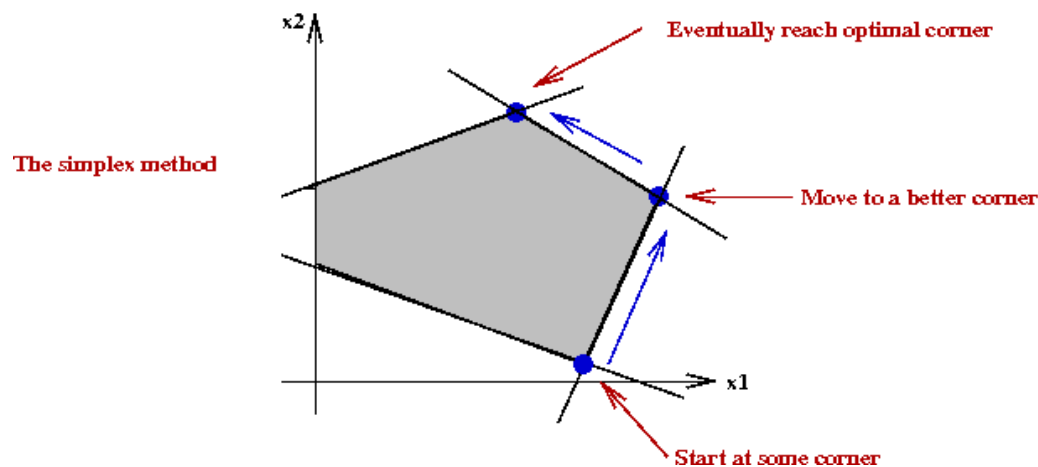
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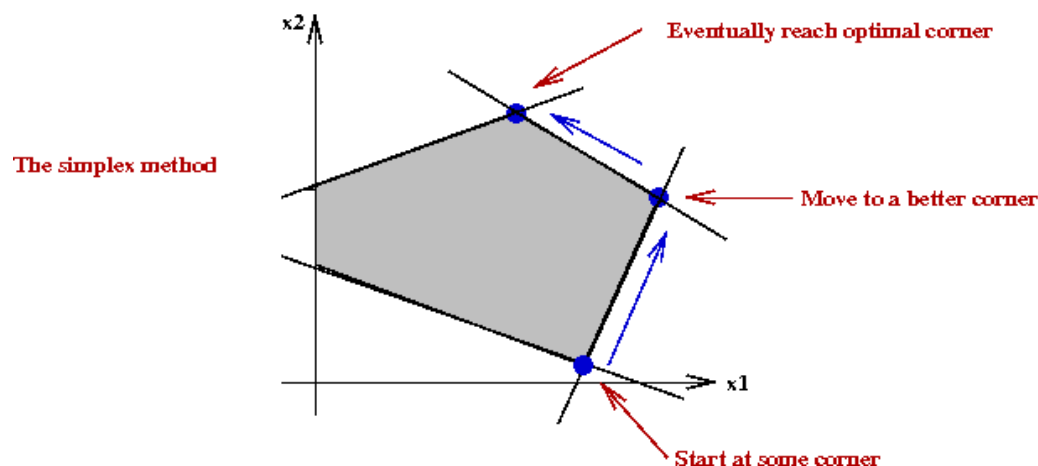


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- **Interior point method** (Karmarkar'84): reasonably efficient in practice

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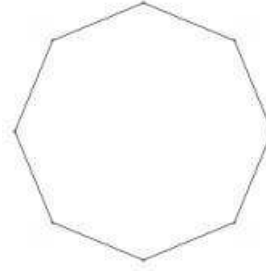
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- Fiorini, Massar, Pokutta, Tiwary, dW (STOC'12):  
**any LP for TSP needs exponential size**



# Polytopes and optimization problems

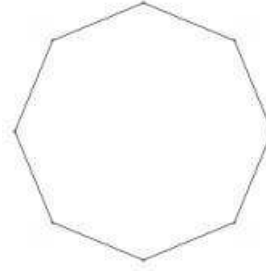
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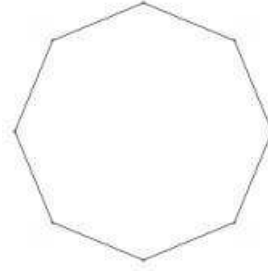
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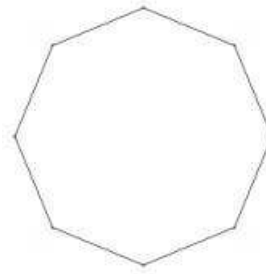


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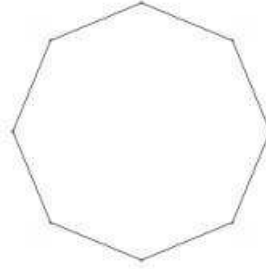
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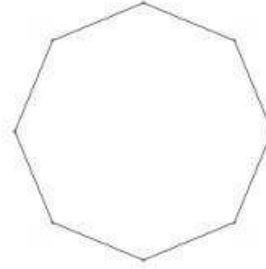
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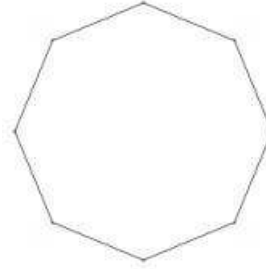
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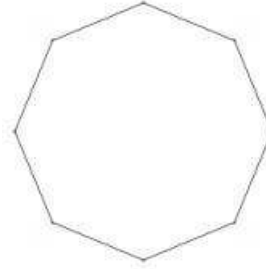
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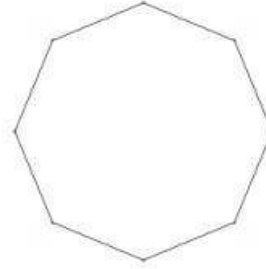
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- TSP( $n$ ) has exponential size

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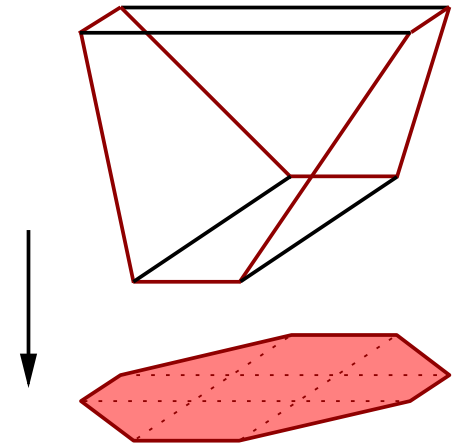
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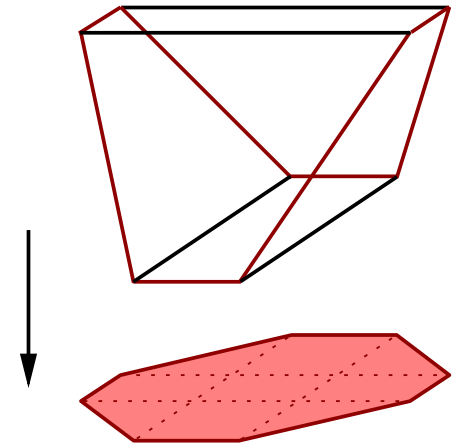


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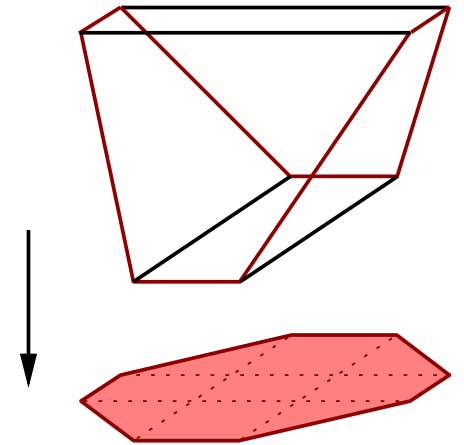


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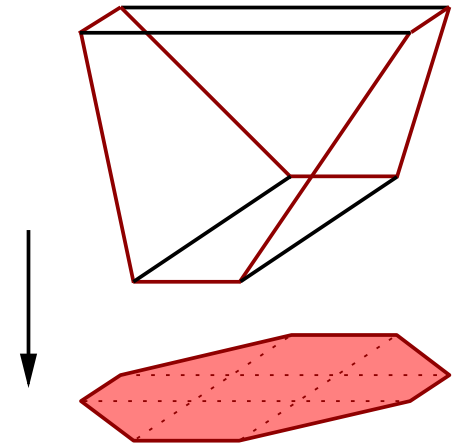
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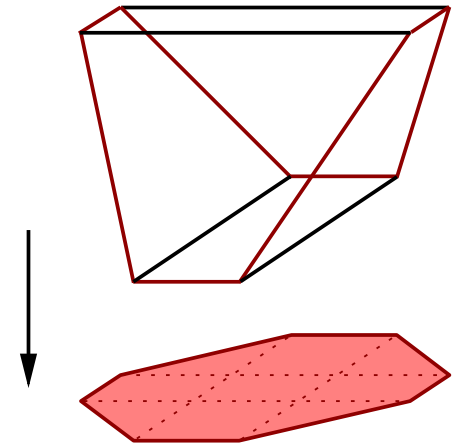




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- Our goal: strong lower bounds on  $xc(P)$  for interesting  $P$

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- Big problem until now: which polytope to analyze, and how to analyze its slack matrix?



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# Lower bound for correlation polytope

- Correlation polytope:  $\text{COR}(n) = \text{conv}\{bb^T \mid b \in \{0, 1\}^n\}$
  - Occurs naturally in NP-hard problems, e.g. MaxClique
  - We can find  $2^n$  valid constraints (indexed by  $a \in \{0, 1\}^n$ ) whose slacks w.r.t. vertex  $bb^T$  are  $M_{ab} = (1 - a^T b)^2$
  - Nondeterministic communication complexity of  $M$  was **already analyzed in the quantum computing!** (dW'00)
  - Take slack matrix  $S$  for  $\text{COR}(n)$ , with  $2^n$  vertices  $bb^T$  for columns,  $2^n$   $a$ -constraints for first  $2^n$  rows, remaining facets for other rows
- $$S = \begin{bmatrix} & & \vdots & & \\ & \dots & M_{ab} & \dots & \\ & & \vdots & & \\ \hline & & \vdots & & \end{bmatrix}$$
- $xc(\text{COR}(n)) = \text{rank}_+(S) \geq \text{rank}_+(M) \geq 2^{\Omega(n)}$

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- So every linear program based on extended formulations **needs exponentially many constraints**
- This rules out many efficient algorithms for NP-hard problems, and **refutes all P=NP “proofs” à la Swart**