

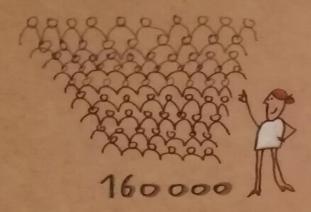


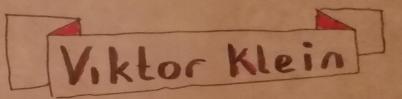


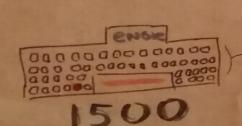
Viktor Klein





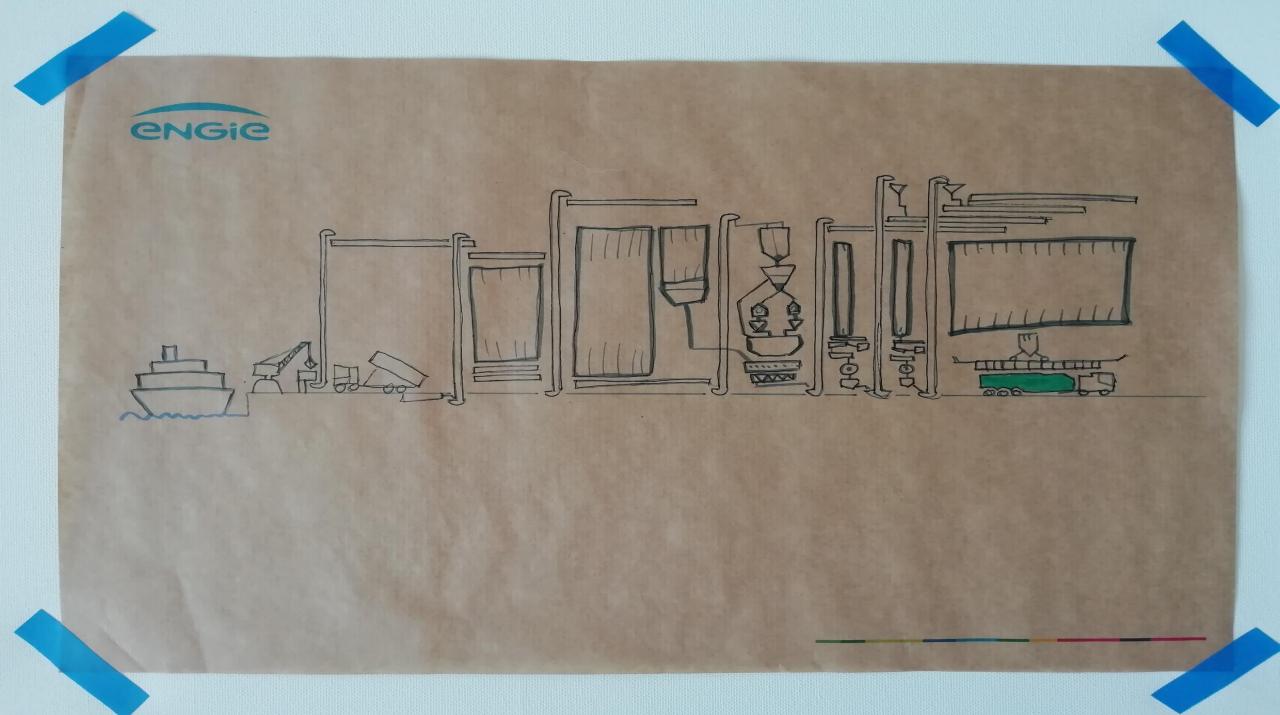


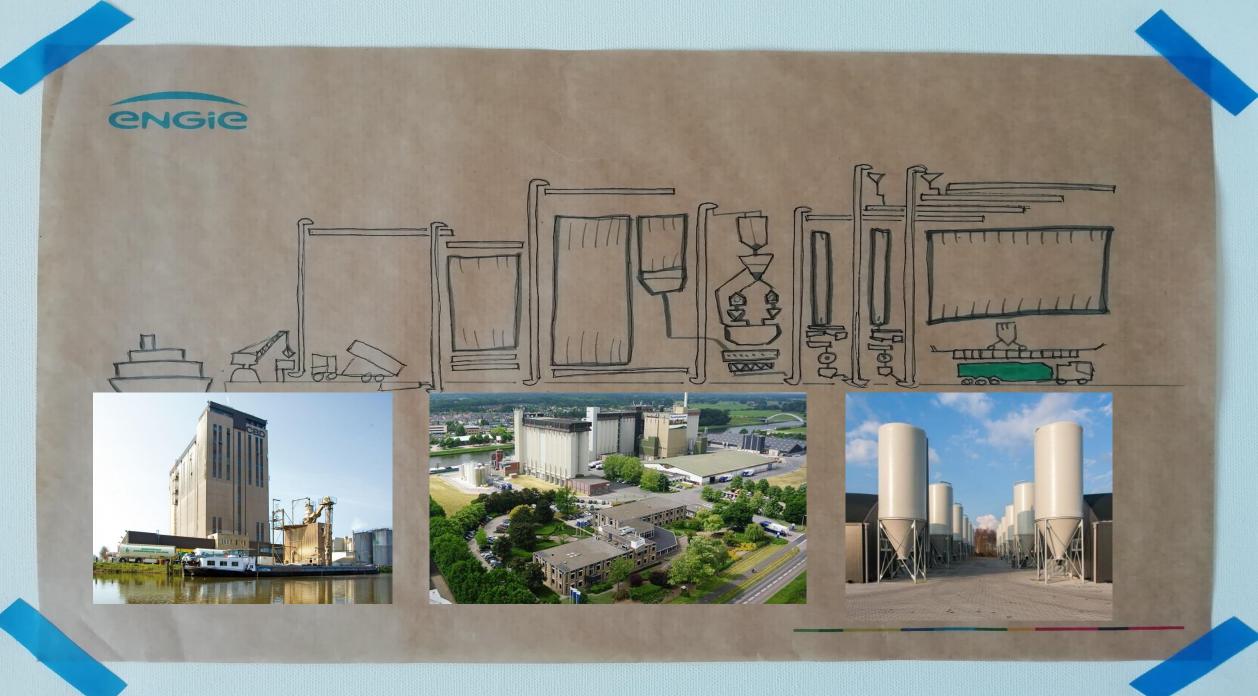












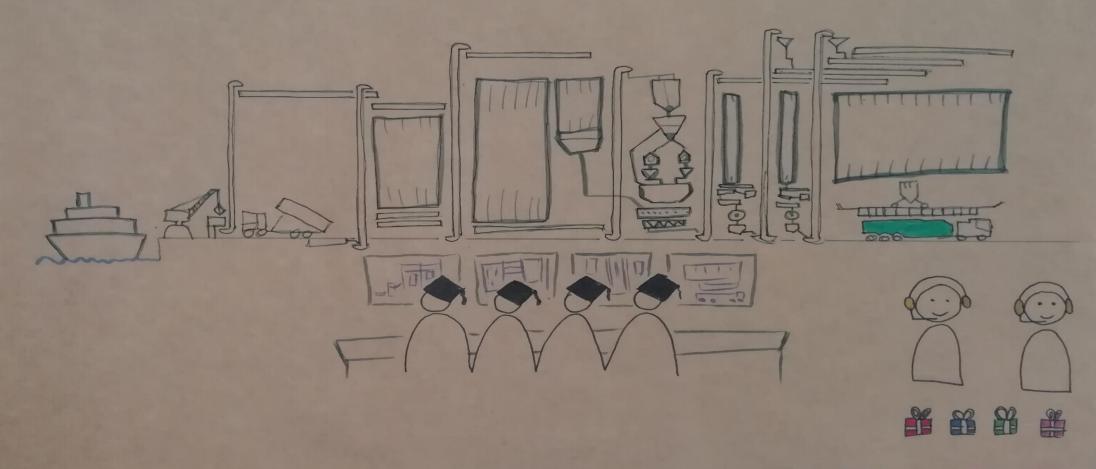














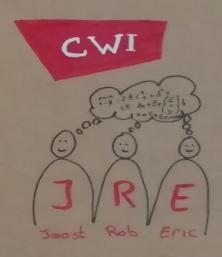








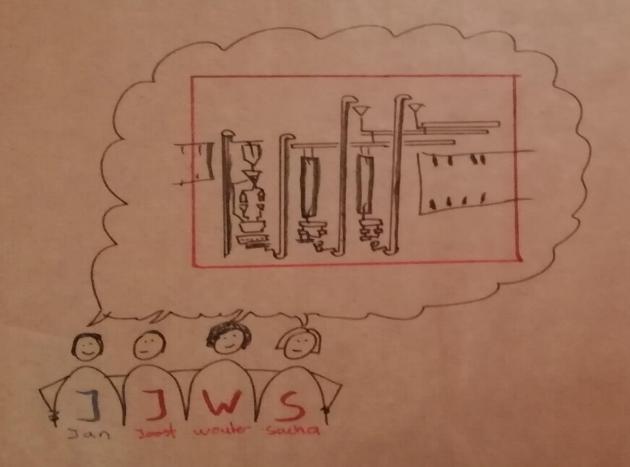


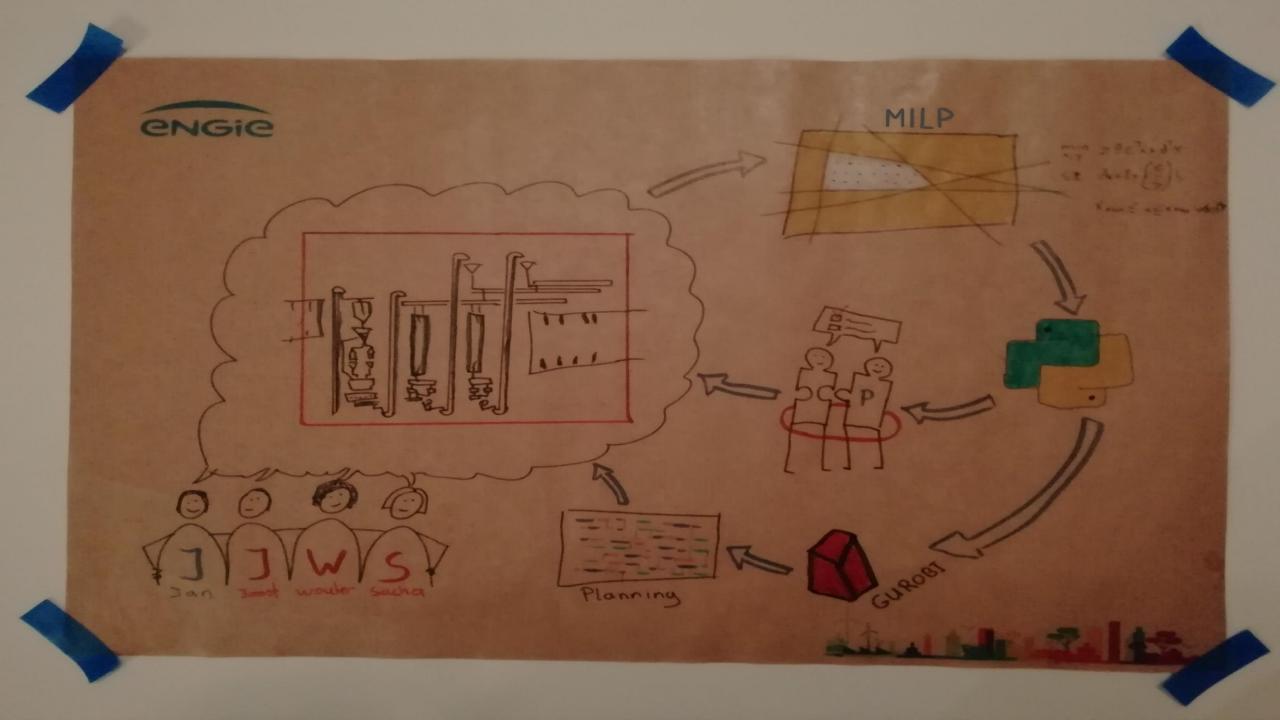




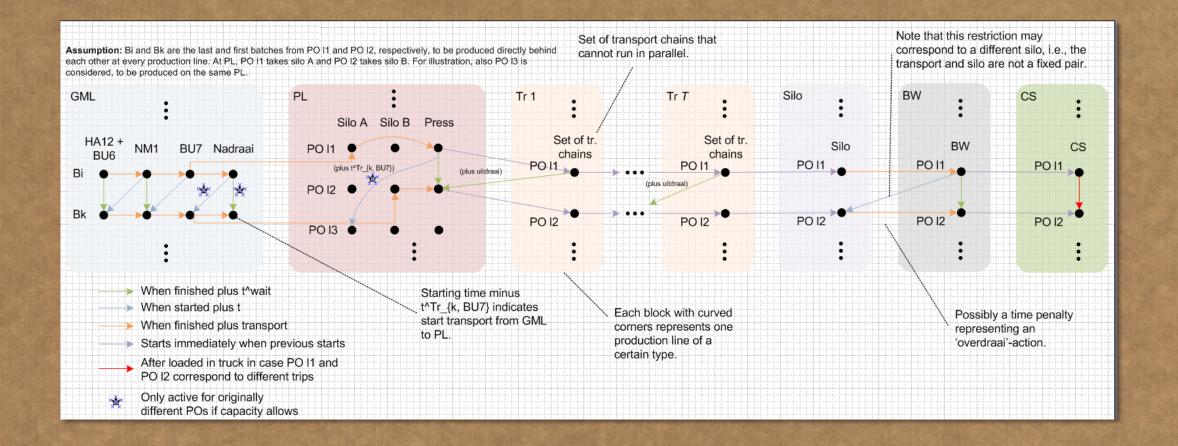










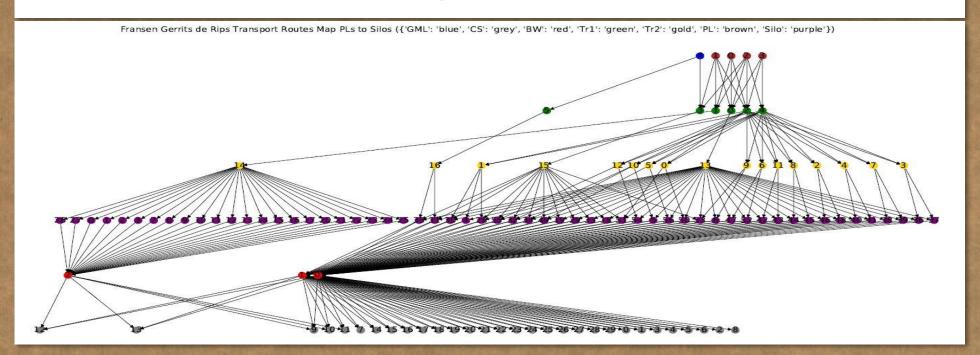






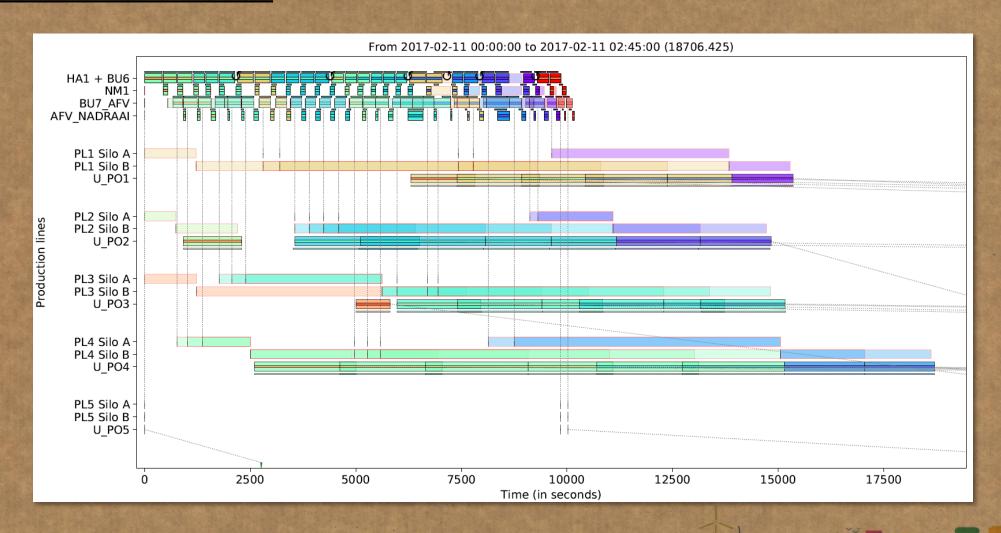
$$\bar{t}_{l_1, l_2, u, j} = (1 - c_{\theta_{l_1}, \theta_{l_2}}) \cdot (\bar{t}_{uj} + \bar{t}_{l_1, l_2, u, j}^+) + c_{\theta_{l_1}, \theta_{l_2}} \cdot \min_{\substack{l = 1, \dots, \kappa: \\ c_{\theta_{l_1}, \theta_l} = c_{\theta_l}, \theta_{l_2} = 0, \\ j \in \bar{M}_l}} \left(\bar{t}_{l_1, l, u, j} + \sum_{z = \theta_l}^{\widehat{\theta}_l} \bar{\tau}_{zuj} + \bar{t}_{l, l_2, u, j} \right).$$

search for a non-contaminating feasible PO l with minimum completion time between POs l_1 and l_2





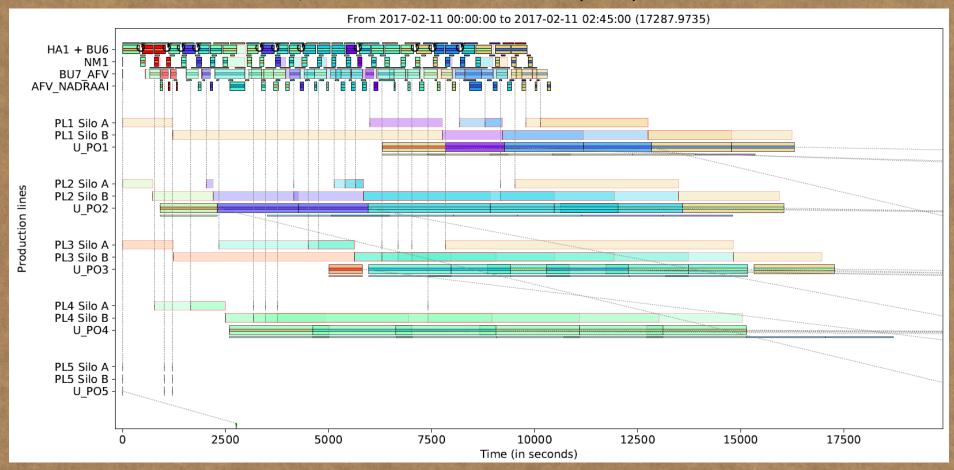
Realized Schedule:





Optimized Schedule:

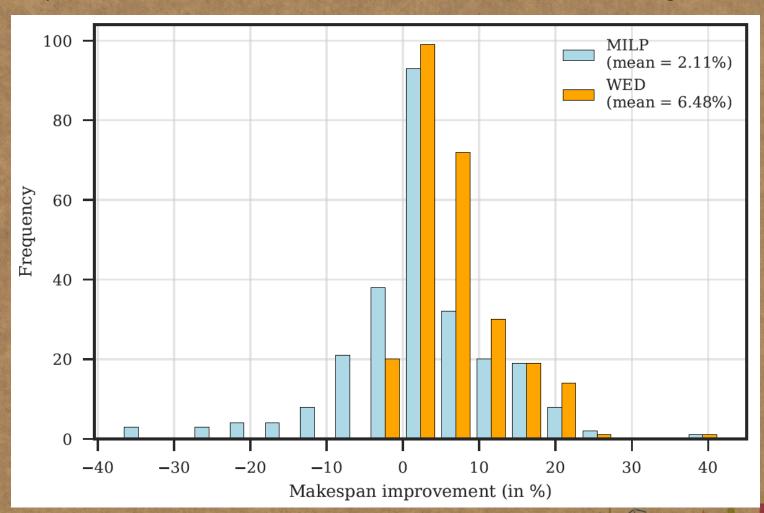
Solved for 180 seconds, 23 minutes earlier finished (7.5%)



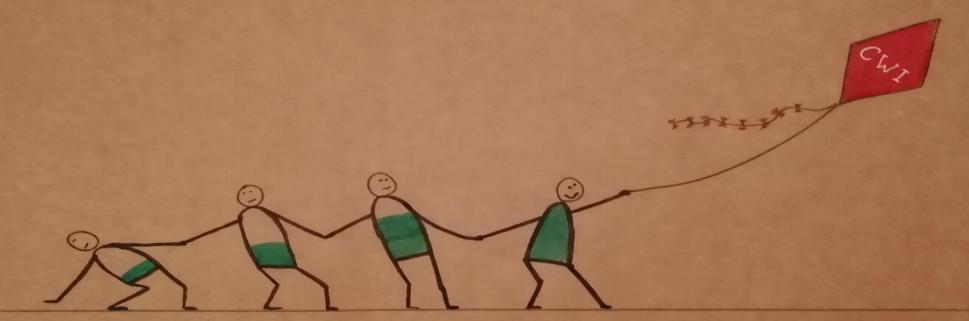


Efficiency gain:

Comparison to realized schedules for 257 instances (5h) when solving for 180 seconds







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